



Cracking the Final Frontier

Reverse Engineering and Exploiting Low Earth Orbit Satellites

Johannes Willbold

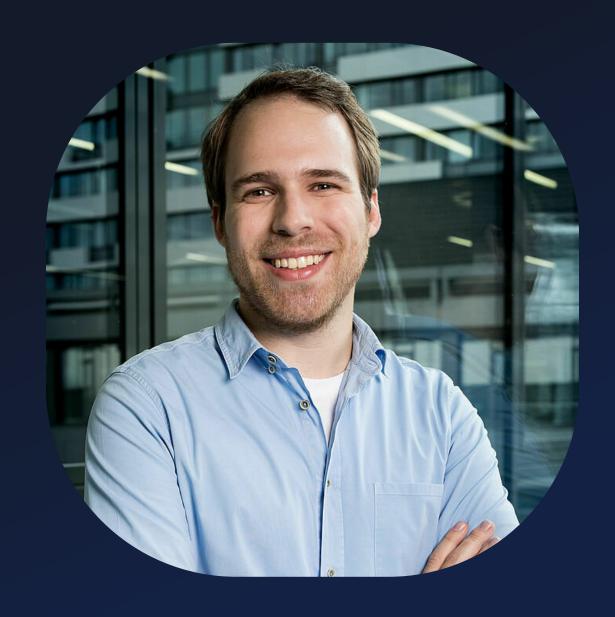






\$whoami





- Satellite & Space Systems Security
- PhD Student
 - Ruhr University Bochum, DE
- Co-Founder of SpaceSec
- Visiting Researcher
 - Cyber-Defence Campus, CH

Space Odyssey

Space Odyssey: An Experimental Software Security Analysis of Satellites

Johannes Willbold*, Moritz Schloegel*[‡], Manuel Vögele*, Maximilian Gerhardt*, Thorsten Holz[‡], Ali Abbasi[‡]

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Distinguished Paper Award

Abstract—Satellites are an essential aspect of our modern society and have contributed significantly to the way we live today, most notable through modern telecommunications, global positioning, and Earth observation. In recent years, and especially in the wake of the New Space Era, the number of satellite deployments has seen explosive growth. Despite its critical importance, little academic research has been conducted on satellite security and, in particular, on the security of onboard firmware. This lack likely stems from by now outdated assumptions on achieving security by obscurity, effectively preventing meaningful research on satellite firmware.

In this paper we first provide a taxonomy of threats

in 2022 [2]. The vast majority of these satellites form megaconstellations like *Starlink*, which plans to launch more than 40,000 satellites in the coming years [3].

Small satellites [4] are at the heart of this *New Space Era* as their size and the widespread use of Commercial off-the-shelf (COTS) components makes them affordable even for small institutions. Furthermore, they cover a broad spectrum of use cases ranging from commercial applications (like Earth observation, machine-to-machine communication, and Internet services) to research applications, such as technology testing, weather and earthquake forecasting, and even interplanetary missions [5]–[8].

44th IEEE Symposium on Security and Privacy (S&P)

Applications















Technology Testing







Radiation Belt





Radiation Belt





Radiation Belt

MEO

2k - 35k km





MEO 2k - 35k km



Radiation Belt





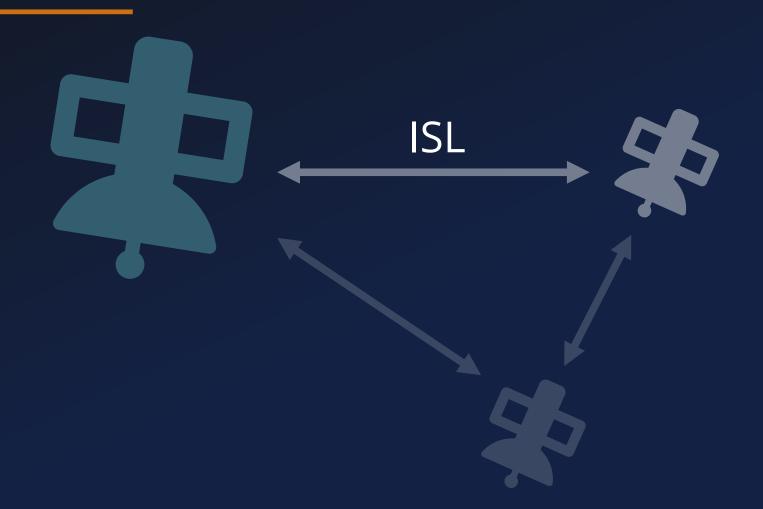
MEO 2k - 35k km



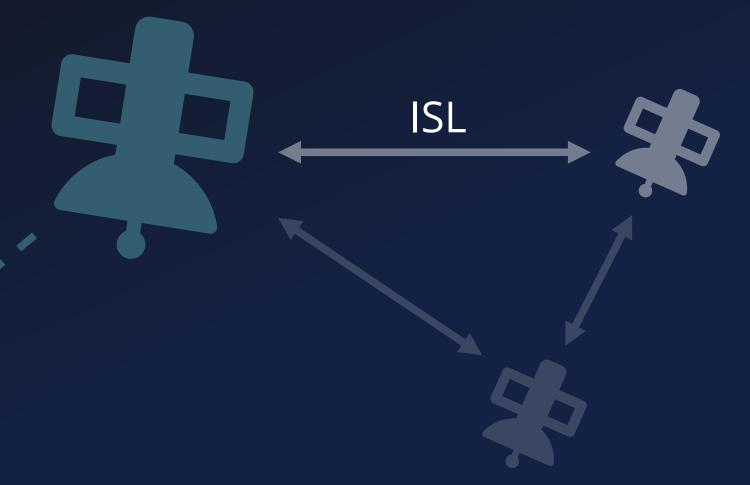
GEO 35786 km

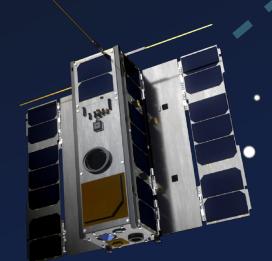
Radiation Belt



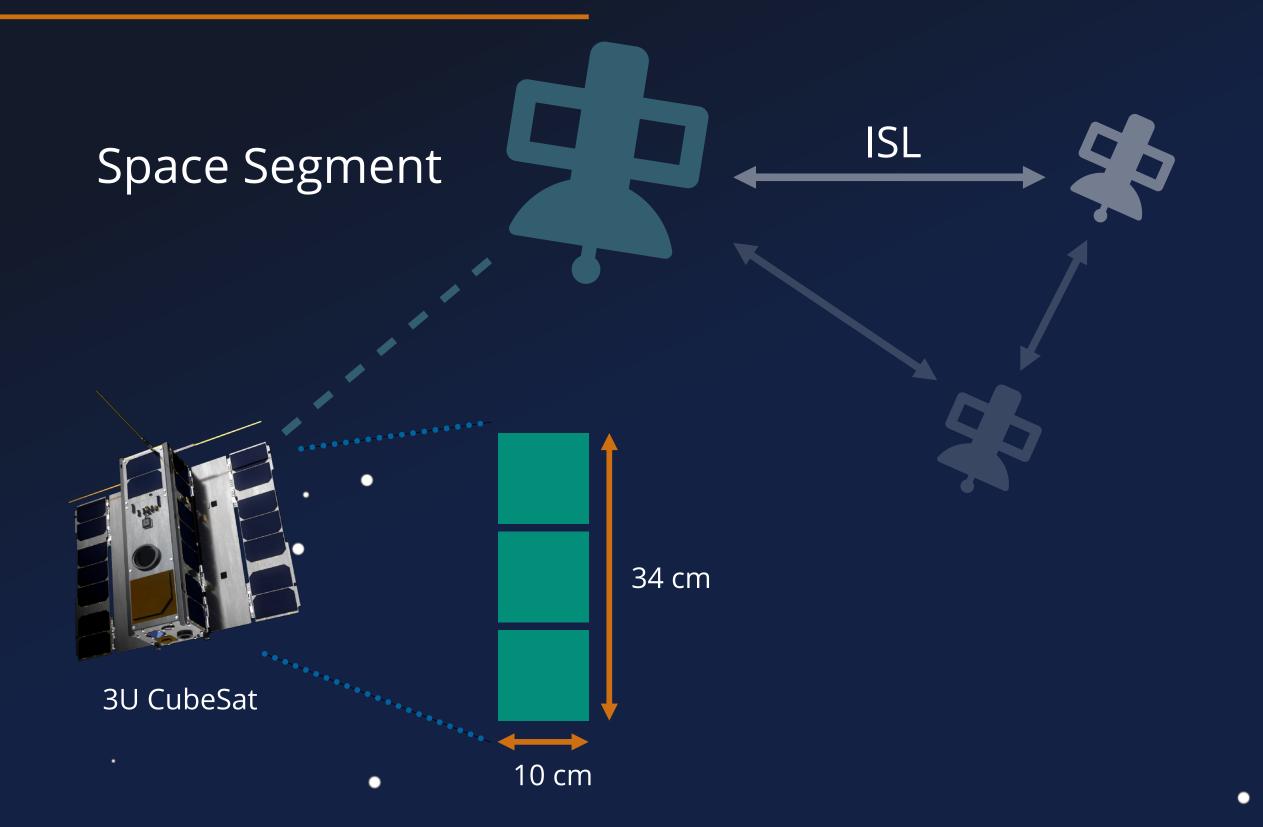


Space Segment



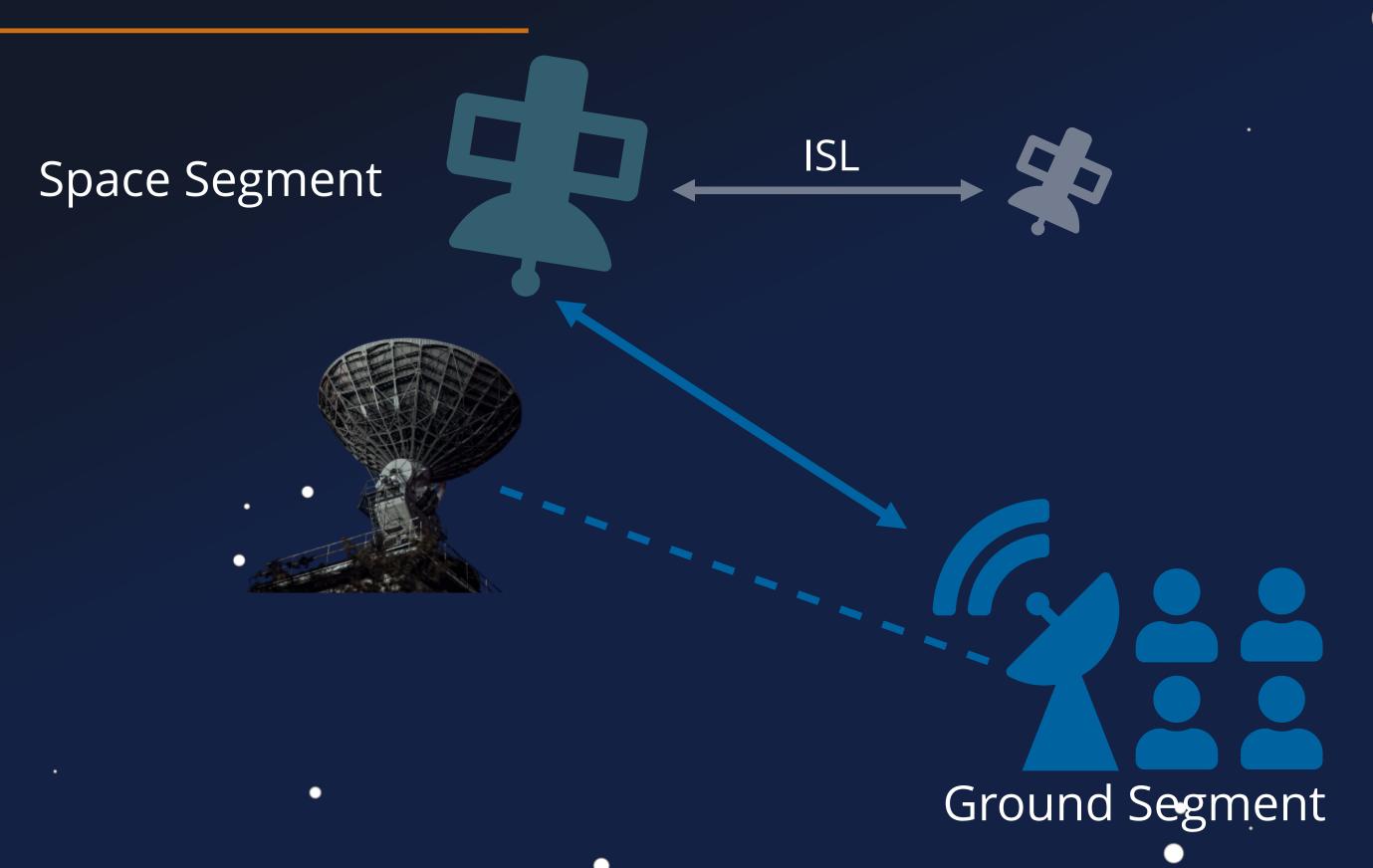


3U CubeSat











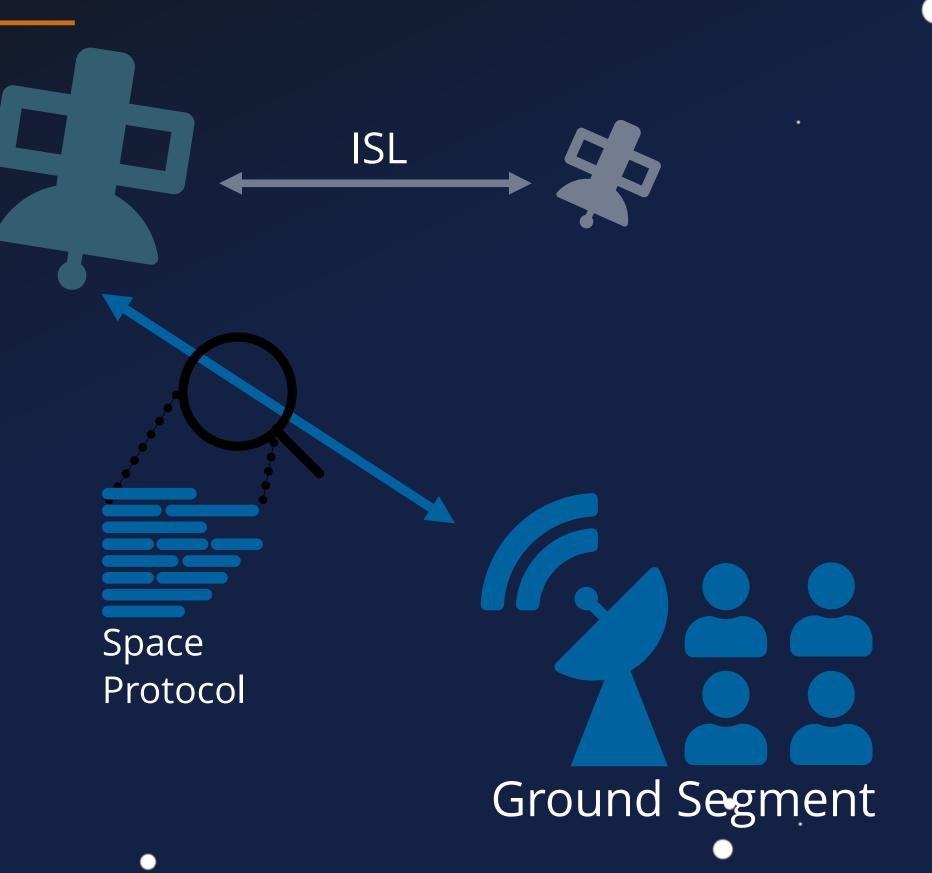


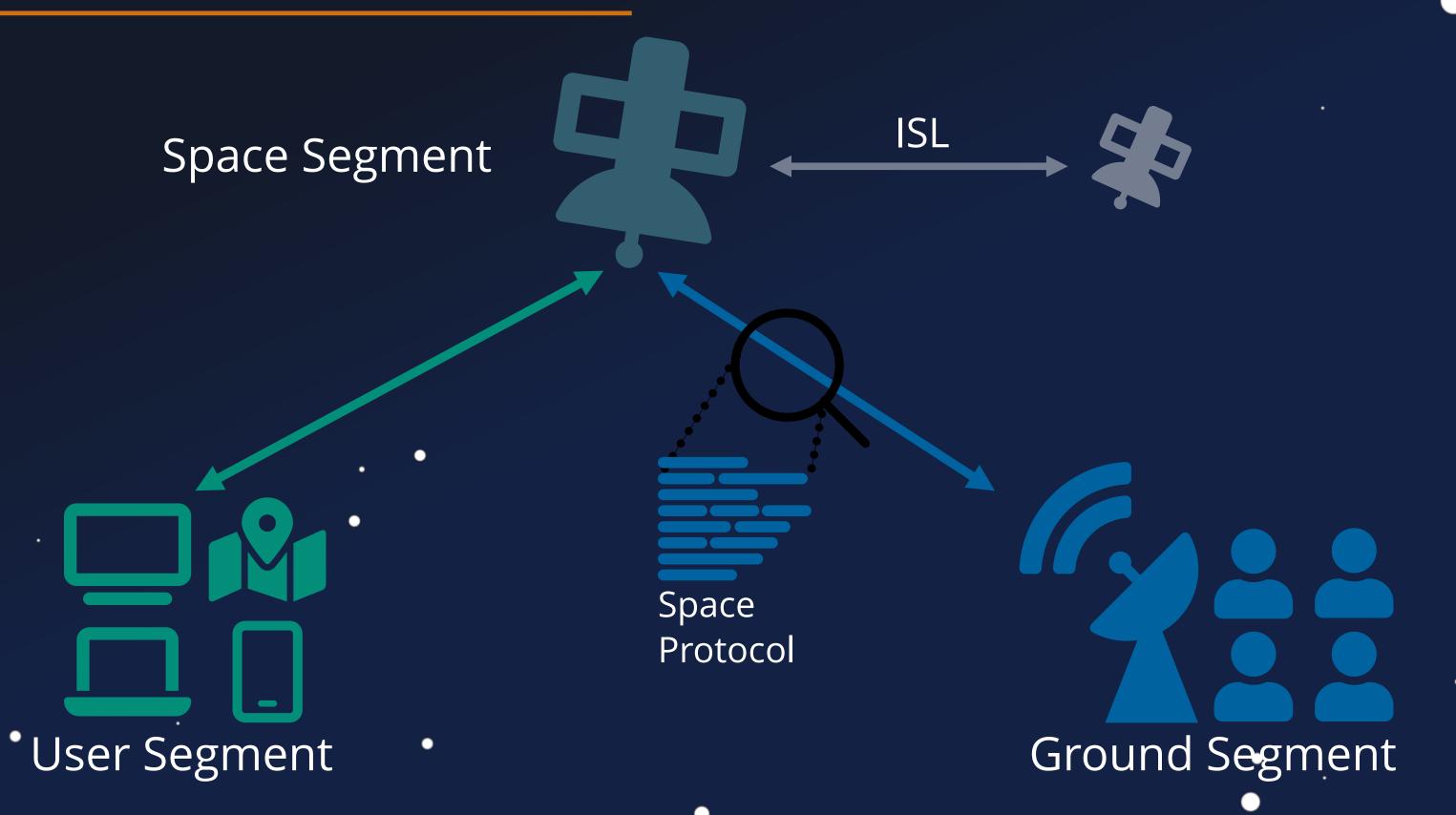










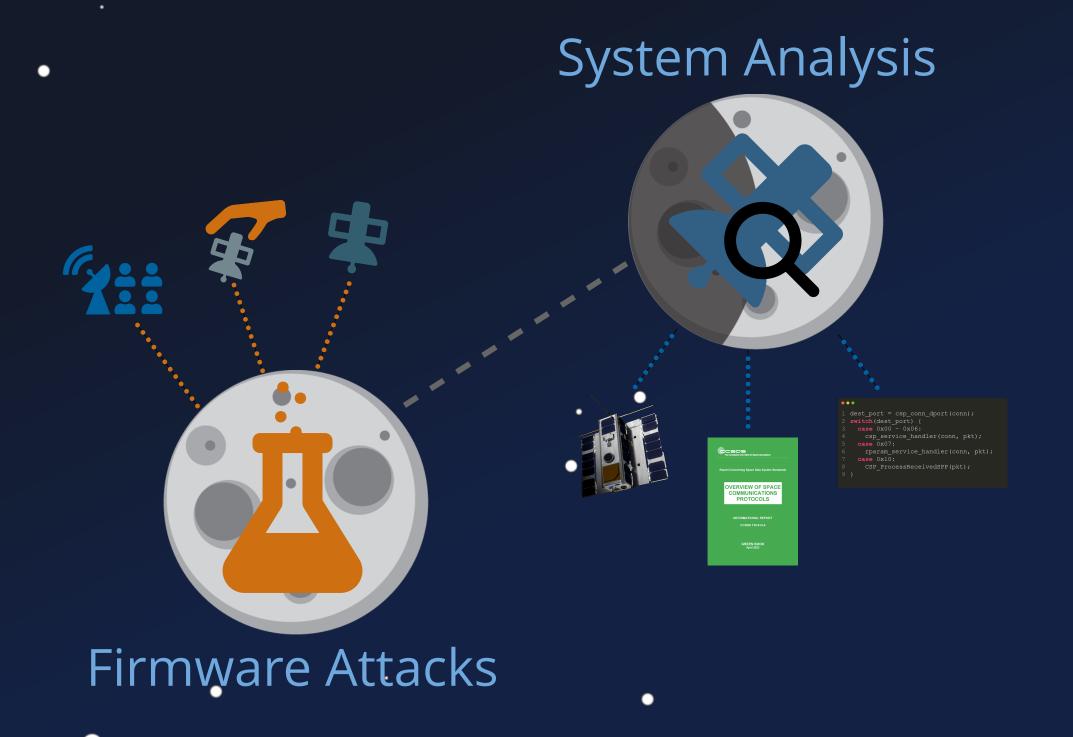


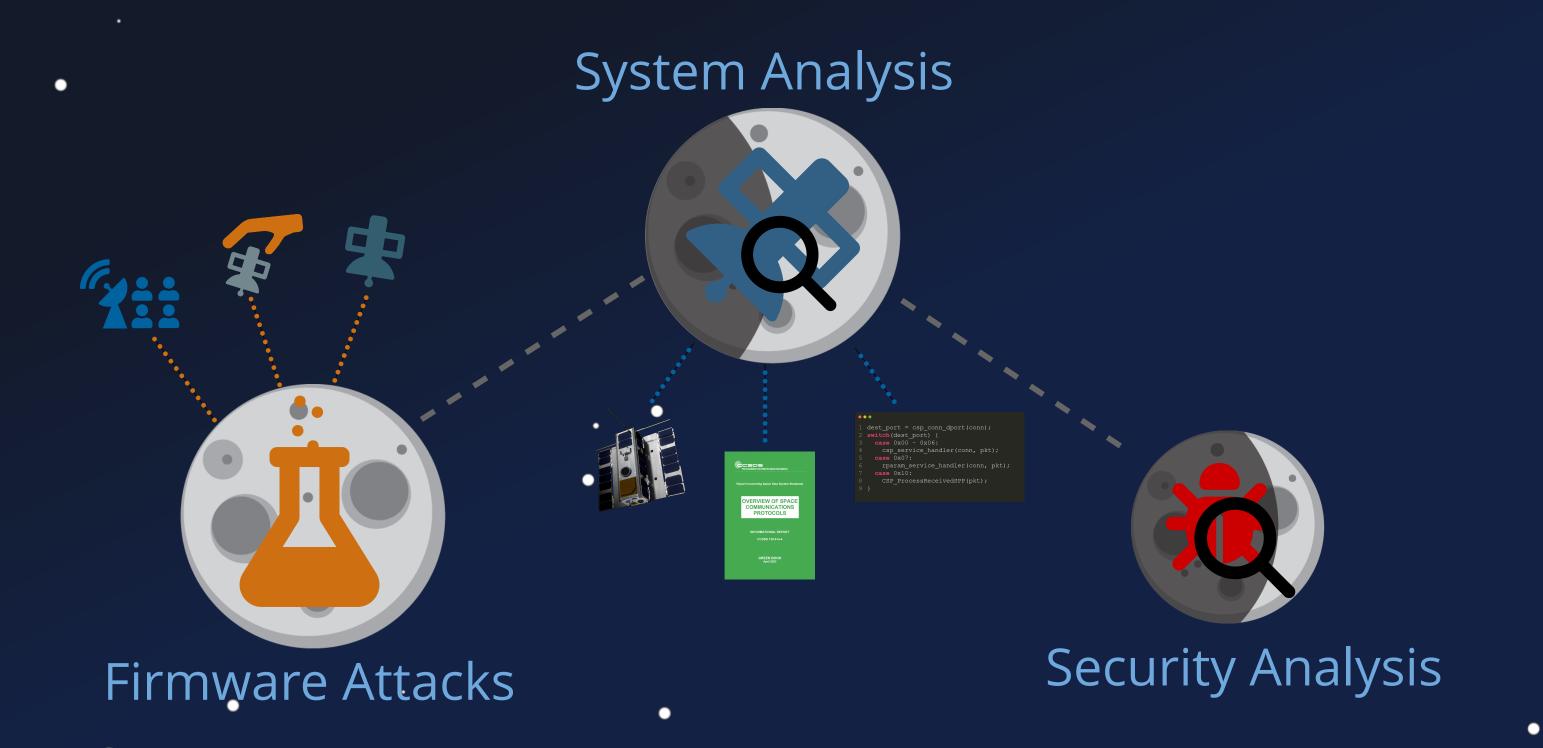


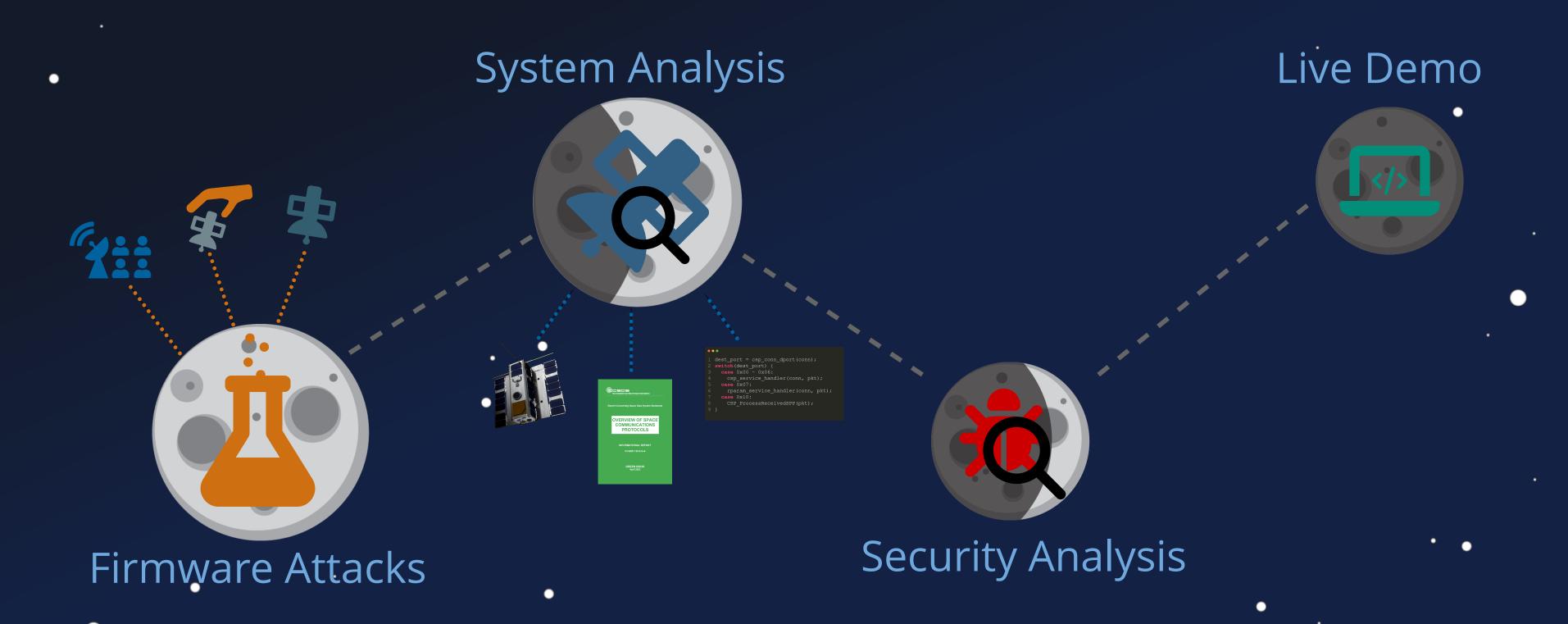


System Analysis

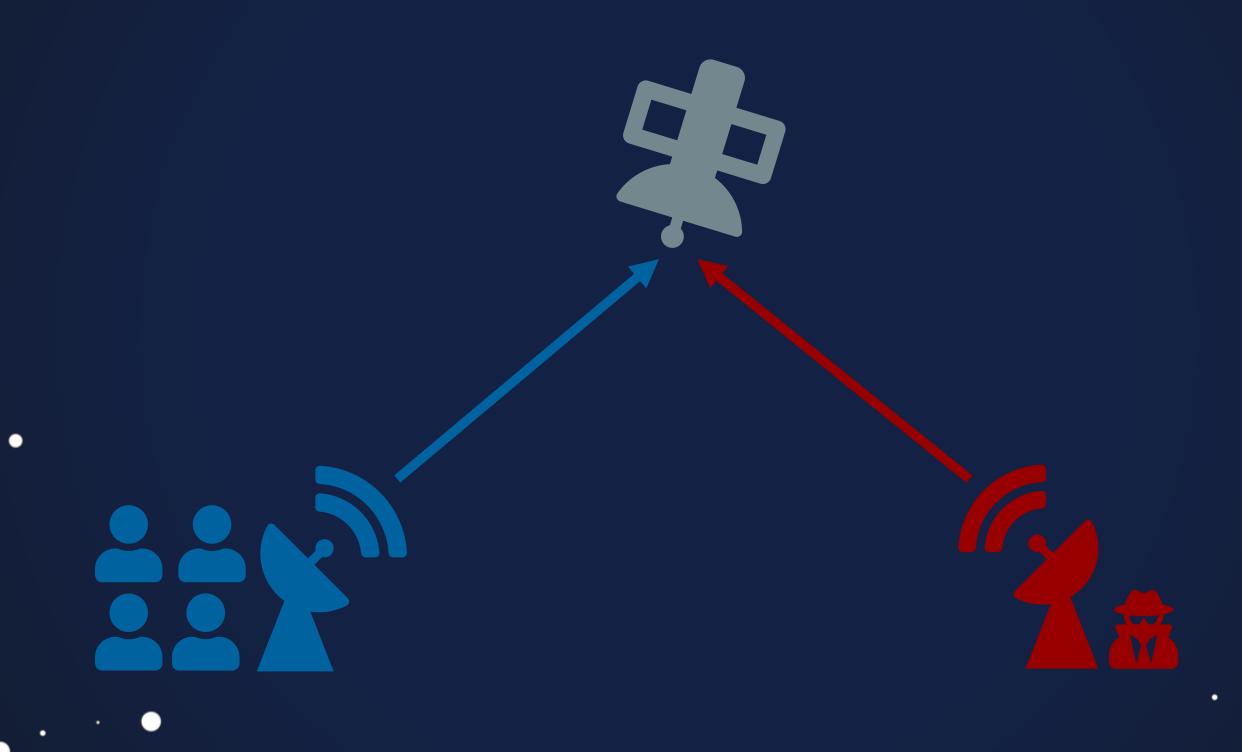




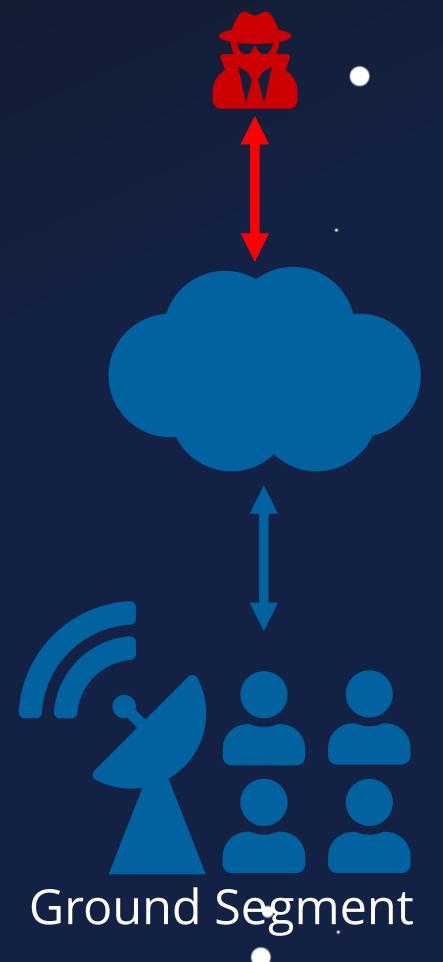




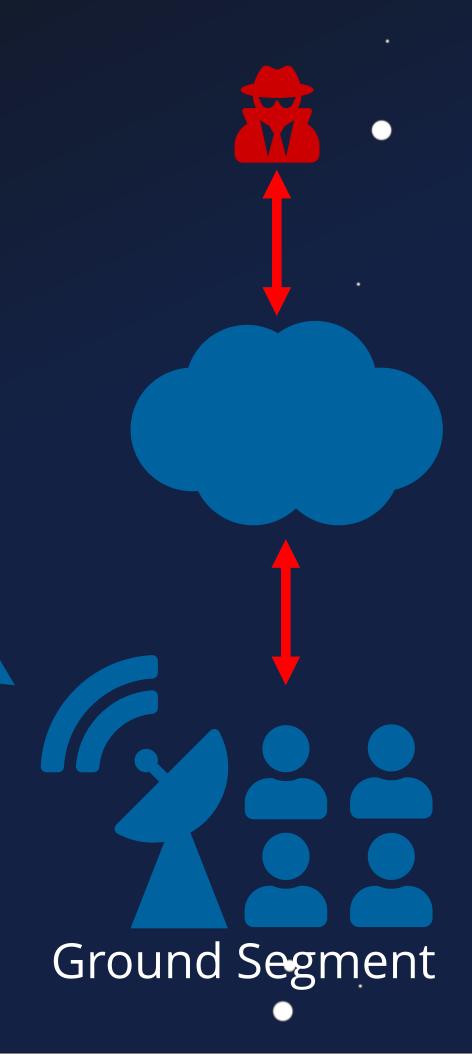
Firmware Attacks



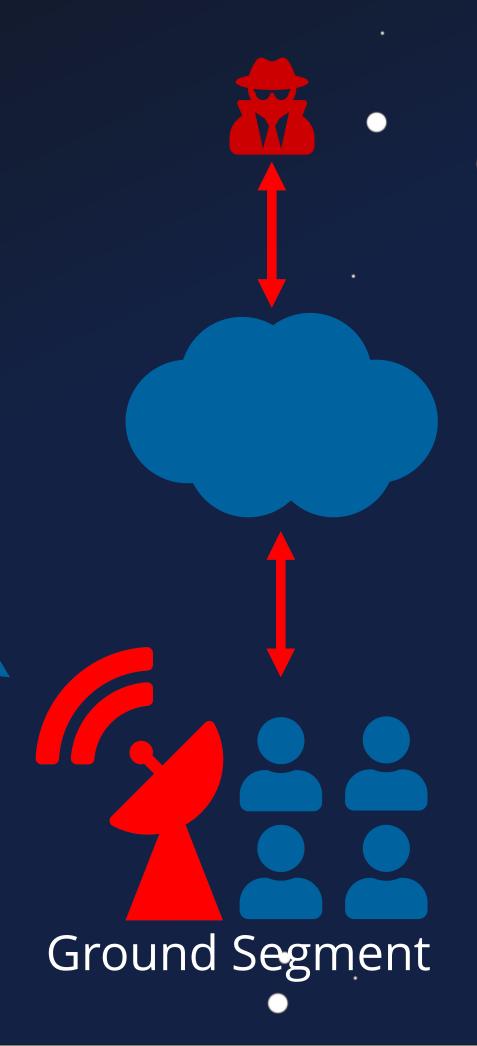




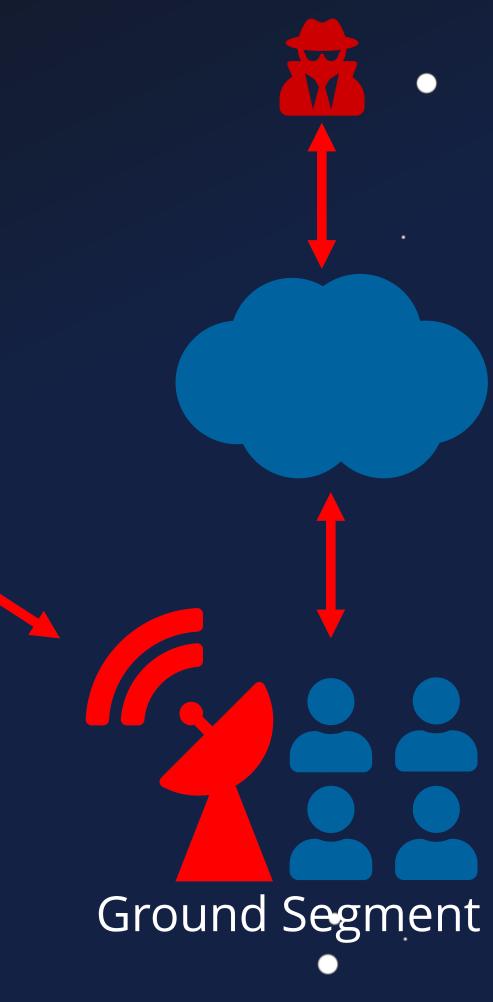






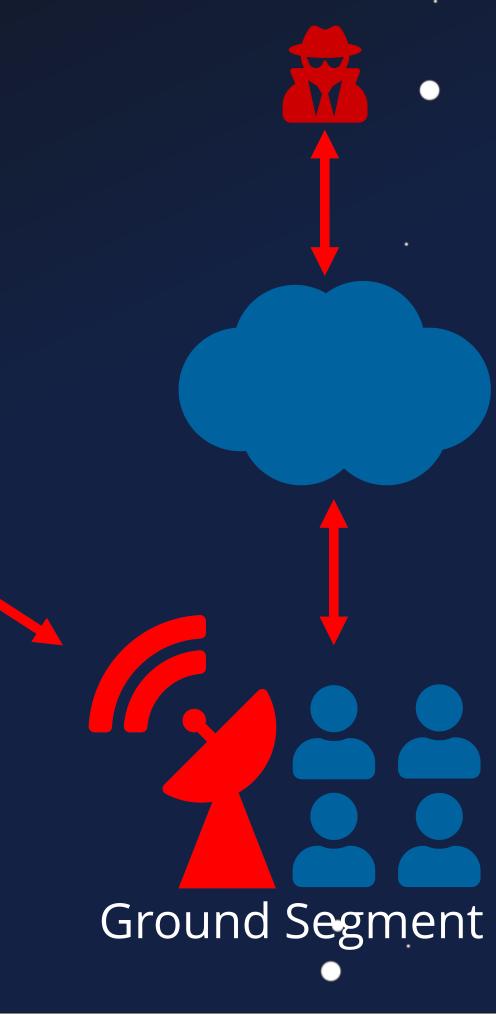


Space Segment



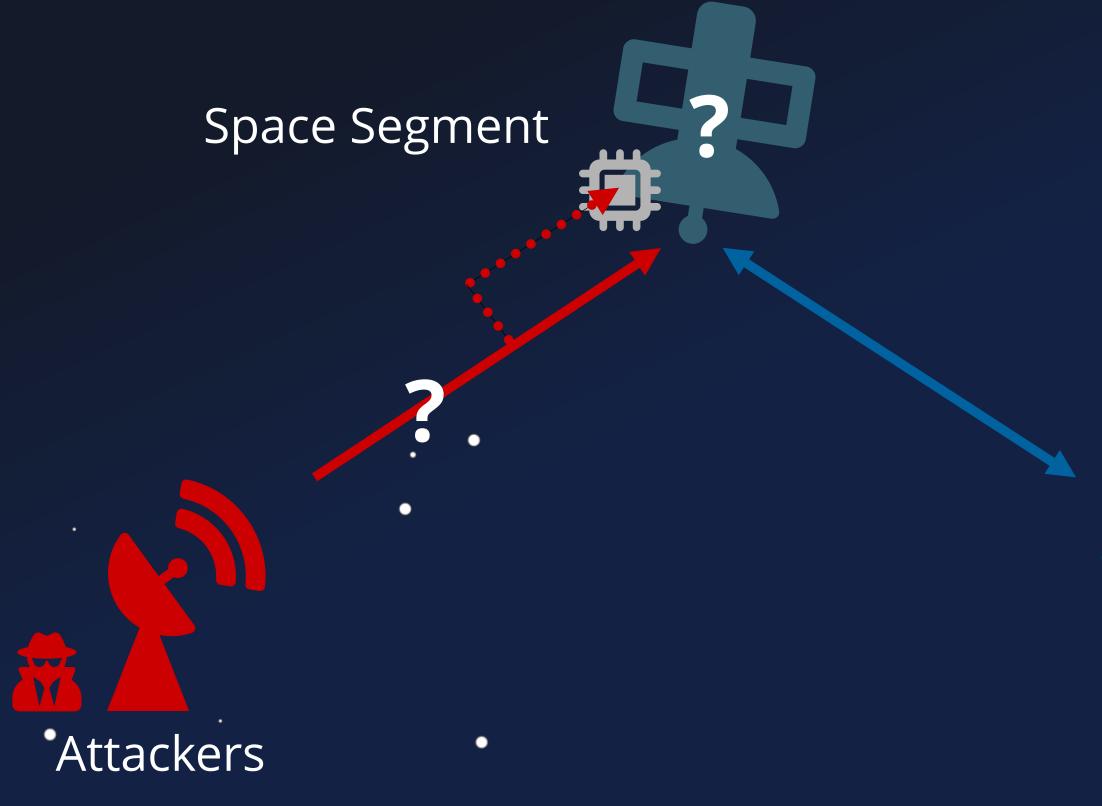
*User Segment

Space Segment



*User Segment

Firmware Attacks





Not so Novel



Report Concerning Space Data System Standards

SECURITY THREATS
AGAINST SPACE
MISSIONS

INFORMATIONAL REPORT

CCSDS 350.1-G-3

GREEN BOOK February 2022

Not so Novel



CCSDS REPORT CONCERNING SECURITY THREATS AGAINST SPACE MISSIONS

348 REPLAY

Applicable to: Space Segment, Ground Segment, Space-Link Communication.

Description: Transmissions to or from a spacecraft or between ground system computers can be intercepted, recorded, and played back at a later time.

Possible Mission Impact: If the recorded data were a command set from the ground to the spacecraft and they are re-transmitted to the state of the intended destination, they might be executed, potentially of the state of the s

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Applicable to: Space Segment, Ground Segment.

Description: Users, system operators, and programmers often make mistakes that can result in security problems. Users or administrators can install unauthorized or unvetted software that might contain bugs, viruses, or spyware, which could result in system instability. System operators might misconfigure a system resulting in security weaknesses. Programmers may introduce logic or implementation errors that could result in system vulnerabilities, or instability/reliability. Weaknesses may be discovered after a mission is operational, which external threat agents might attempt to exploit to inject instructions, software, or configuration changes.

Possible Mission Impact: Software threats could result in loss of data and safety issues of loss of spacecraft control, unauthorized spacecraft control, or loss of mission.

3.4.10 C THORIZED ACCESS

Applicable to: Space Cround Segment

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Possible Mission Impact: An access control breach would allow an unauthorized entity to take control of a ground system or a ground system network, shut down a ground system, upload unauthorized commands to a spacecraft, execute unauthorized commands aboard a crewed mission, obtain unauthorized data, contaminate archived data, or completely shut down a mission. If weak access controls are in place, unauthorized access might be obtained. Interception of data might result in unauthorized access because identities, identifiers, or passwords might be obtained. Social engineering could be employed to obtain identities, identifiers, passwords, or other technical details permitting unauthorized access.

CCSDS 350.1-G-3

Page 3-8

Februs

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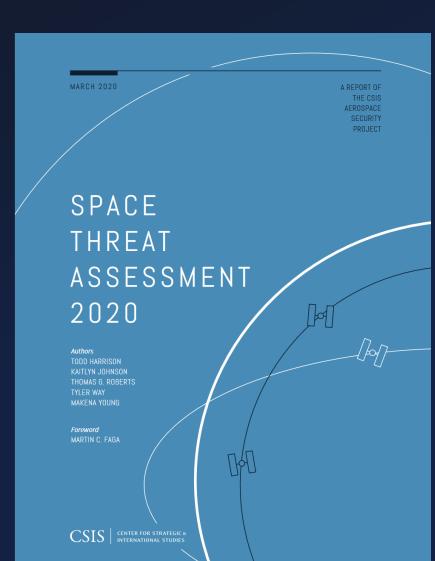
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MARCH 2020 SPACE THREAT ASSESSMENT 2020 CSIS | CENTER FOR STRATEGIC & INTERNATIONAL STUDIES



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CSIS



Cyberattacks can be used to take control user terminals that connect to satellites | Counterspace weapons that are reversiarily require significant resources still pose a cyber threat.9

cyberattack on space systems can re-For example, if an adversary can seize tem, the attack could shut down all communications and permanently damage supply or damaging its electronics and impossible, because attackers can use a variety of methods to conceal their identity, such as using hijacked servers to launch an attack.

THREAT CHARACTERISTICS

The types of counterspace threats de scribed above have distinctly different characteristics that make them more suitable for use in some scenarios than others. As shown in Table 1, some types of counterspace threats are difficult to attribute or have fully reversible effects such as mobile jammers. High-powered lasers, for example, are "silent" and can carry out an attack with little public awareness that anything has happened Other types of counterspace weapons produce effects that make it difficult for successful, and some produce collateral damage that can affect space systems other than the one being targeted.

are all potential intrusion points for cy- ble, difficult to attribute, and have limited berattacks. Cyberattacks can be used to public awareness are ideally suited for sitmonitor data traffic patterns (i.e., which | uations in which an opponent may want users are communicating), to monitor the to signal resolve, create uncertainty in the data itself, or to insert false or corrupted mind of its opponent, or achieve a fait acdata in the system. While cyberattacks | compli without triggering an escalatory require a high degree of understanding of response. For example, an adversary that systems being targeted, they do not wants to deter the United States from intervening in a situation may believe that duct. Cyberattacks can be contractto private groups or individuals, for escalation (i.e., not trigger the very neans that a state or non-state ac- thing it is trying to prevent) while creating t lacks internal cyber capabilities significant operational challenges for the Inited States that make the prospect of ntervention more costly and protracted. Conversely, counterspace weapons that useful to adversaries in many situations. plan operations with the confidence that duce collateral damage in space, such as other nations against the attacker.

sult in data loss, widespread disruptions, have limited battle damage assessment and even permanent loss of a satellite. or that risk collateral damage may be less control of a satellite through a cyberat- Without reliable battle damage assesstack on its command and control sys- ment, for example, an adversary cannot the satellite by expending its propellant cessful. Furthermore, weapons that prosensors. Accurate and timely attribution large amounts of space debris, run the of a cyberattack can be difficult, if not risk of escalating a conflict and turning

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CSIS

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AFROSPACE REPORT NO.

Cybersecurity Protections for Spacecraft: A Threat Based Approach

April 29, 2021

Brandon Bailey Cyber Assessment and Research Department (CARD) Cybersecurity Subdivision (CSS)

Prepared for: U.S. GOVERNMENT AGENCY

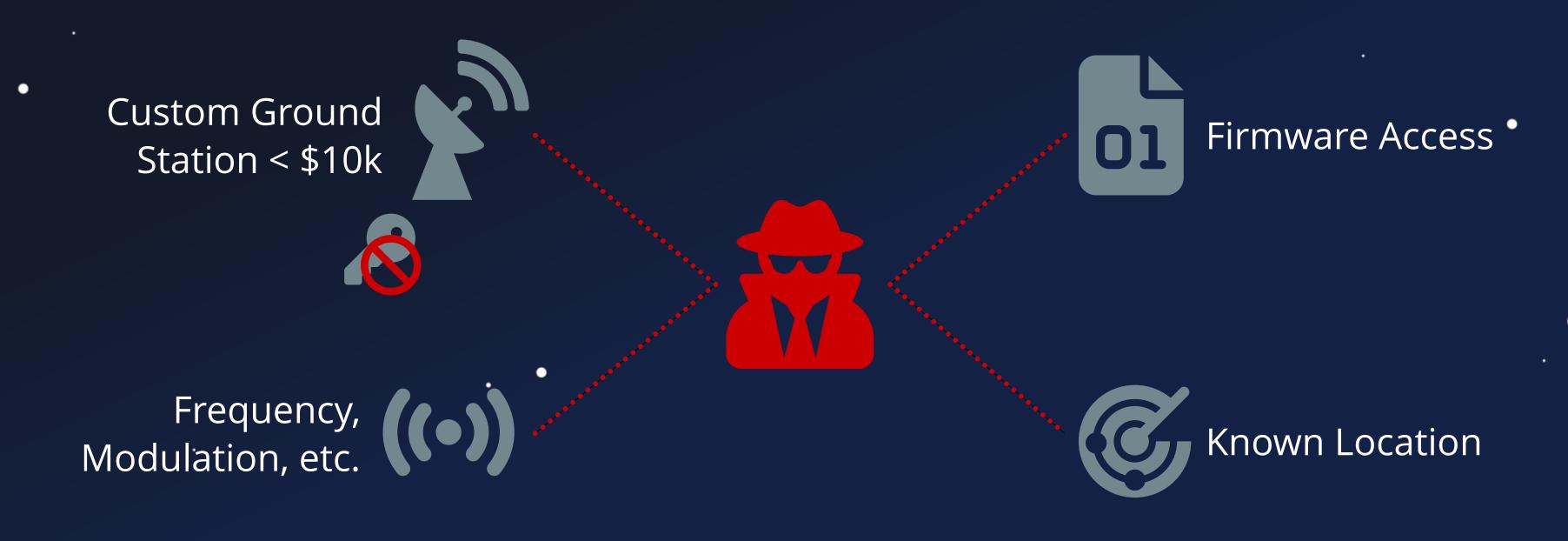
Contract No. FA8802-19-C-0001

Authorized by: Defense Systems Group

Distribution Statement A: Distribution Statement A: Approved for public release; distribution unlimited.



Attacker Model



TL;DR: We can talk to the satellite



Denial of Service



Denial of Service

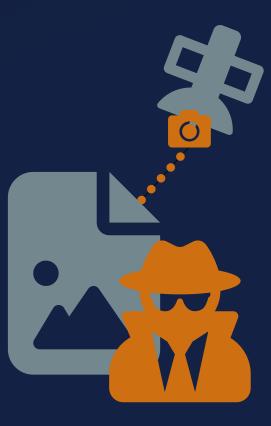






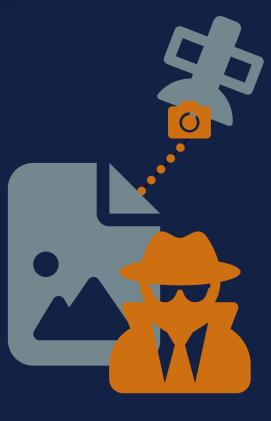


Seizure of Control



Malicious Data Interaction



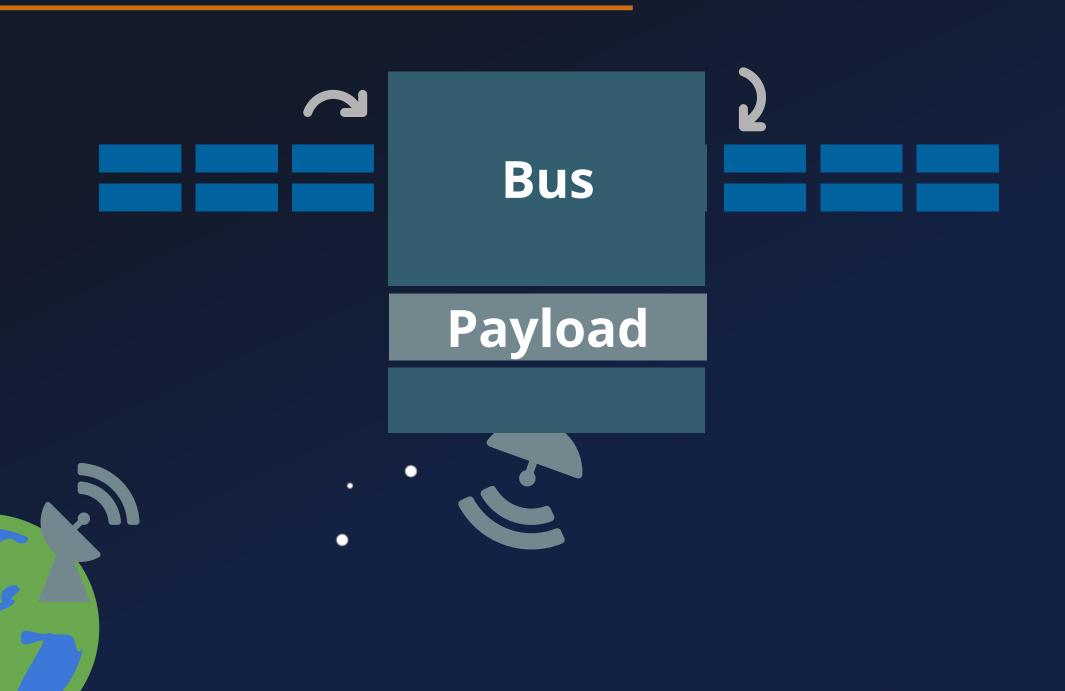


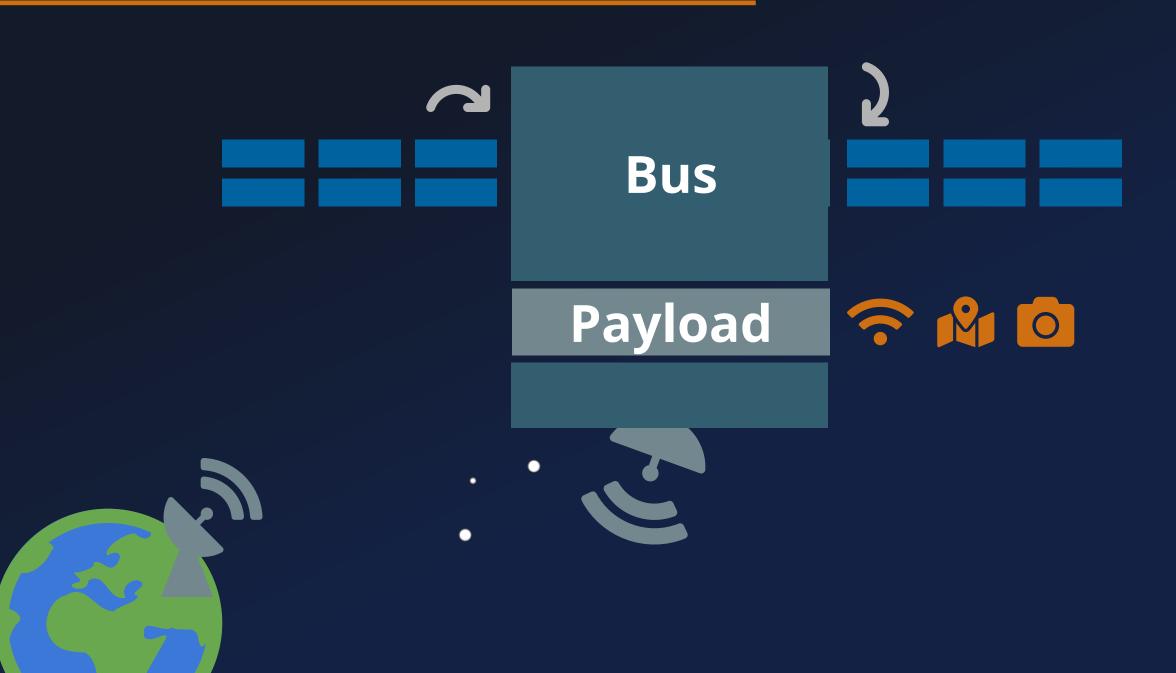
Malicious Data Interaction

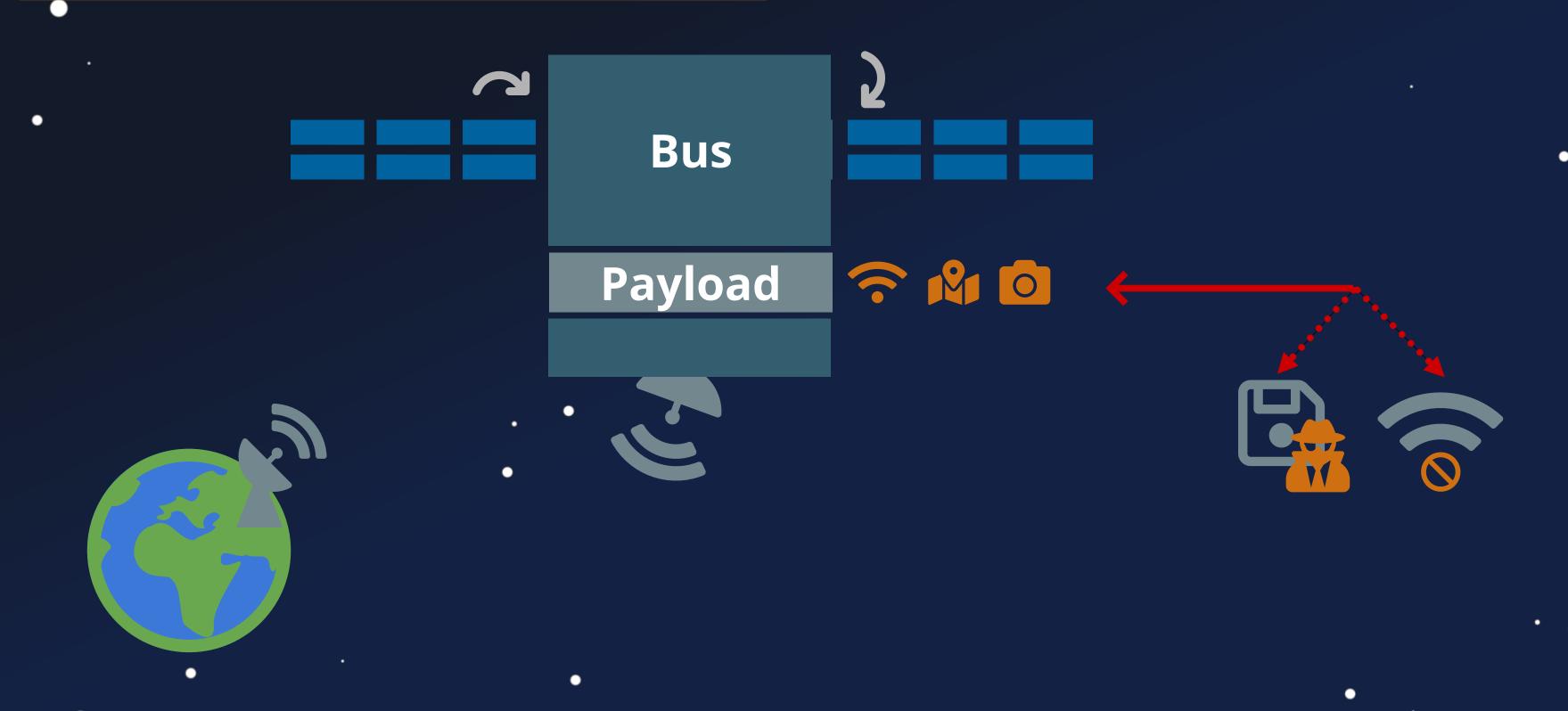


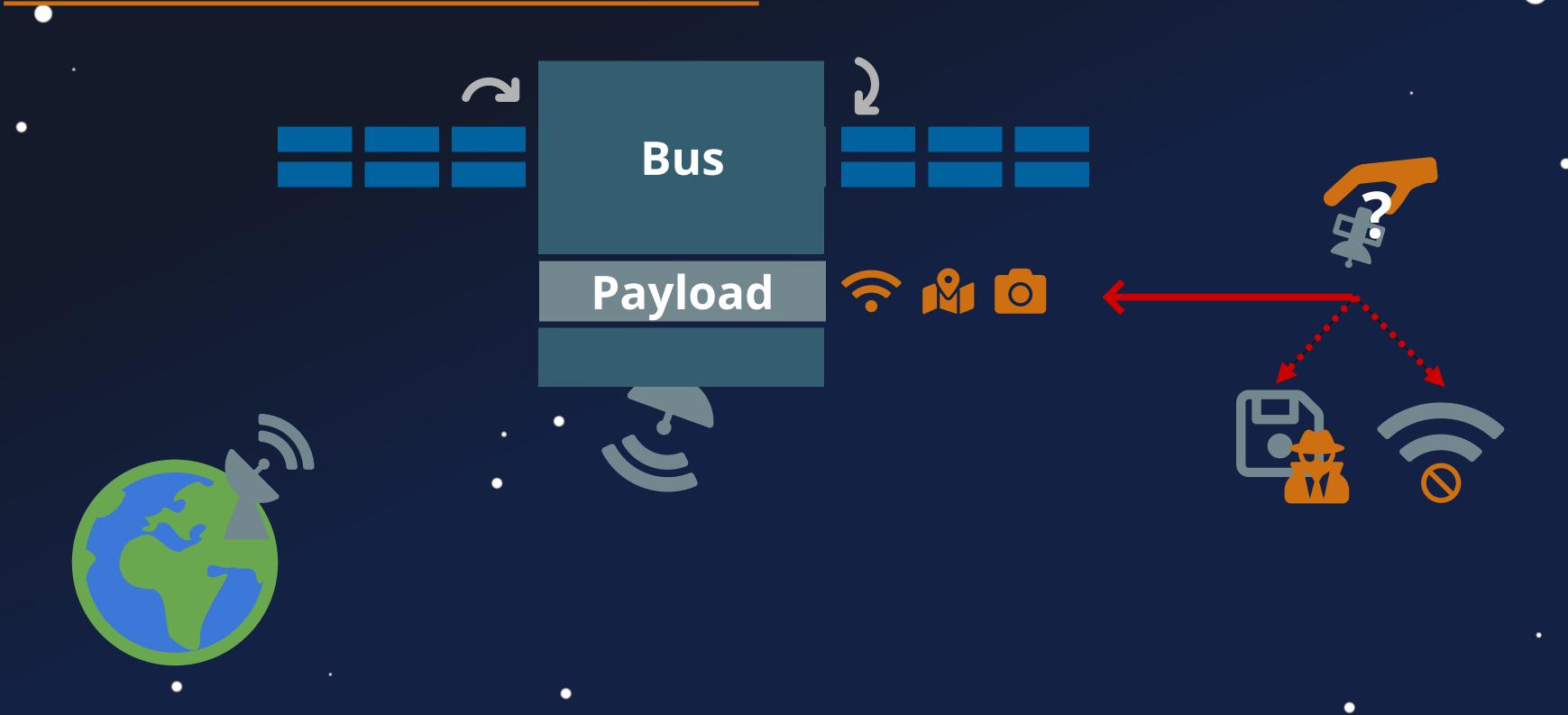
Seizure of Control

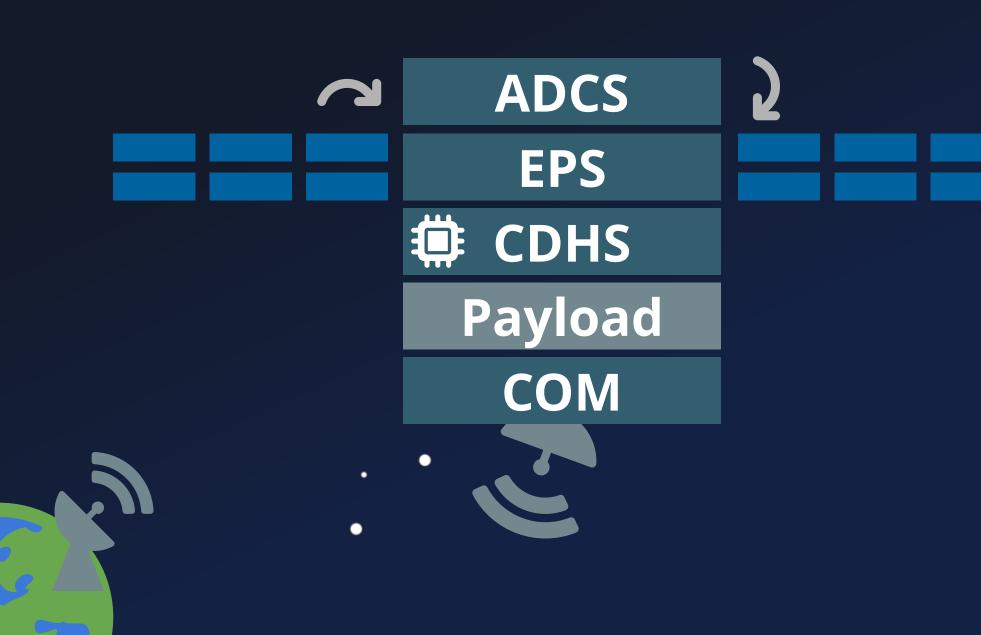


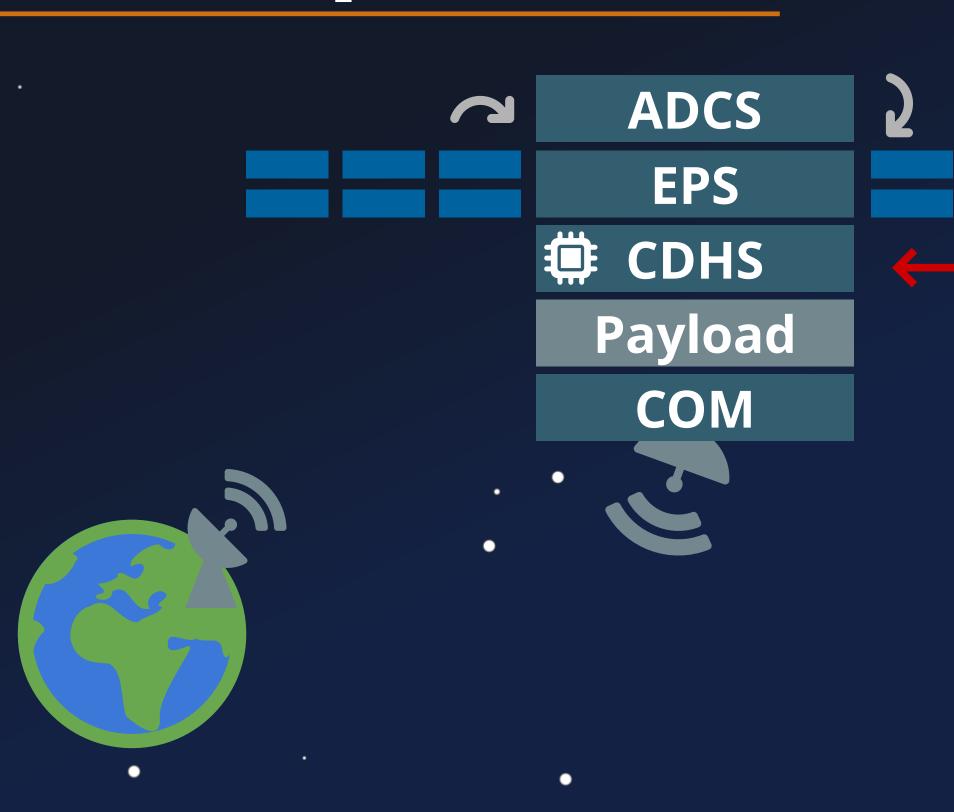












TC/TM Flow

Telecommand (TC)

Telemetry (TM)

COM

- Decode
- Authenticate
- Repackage



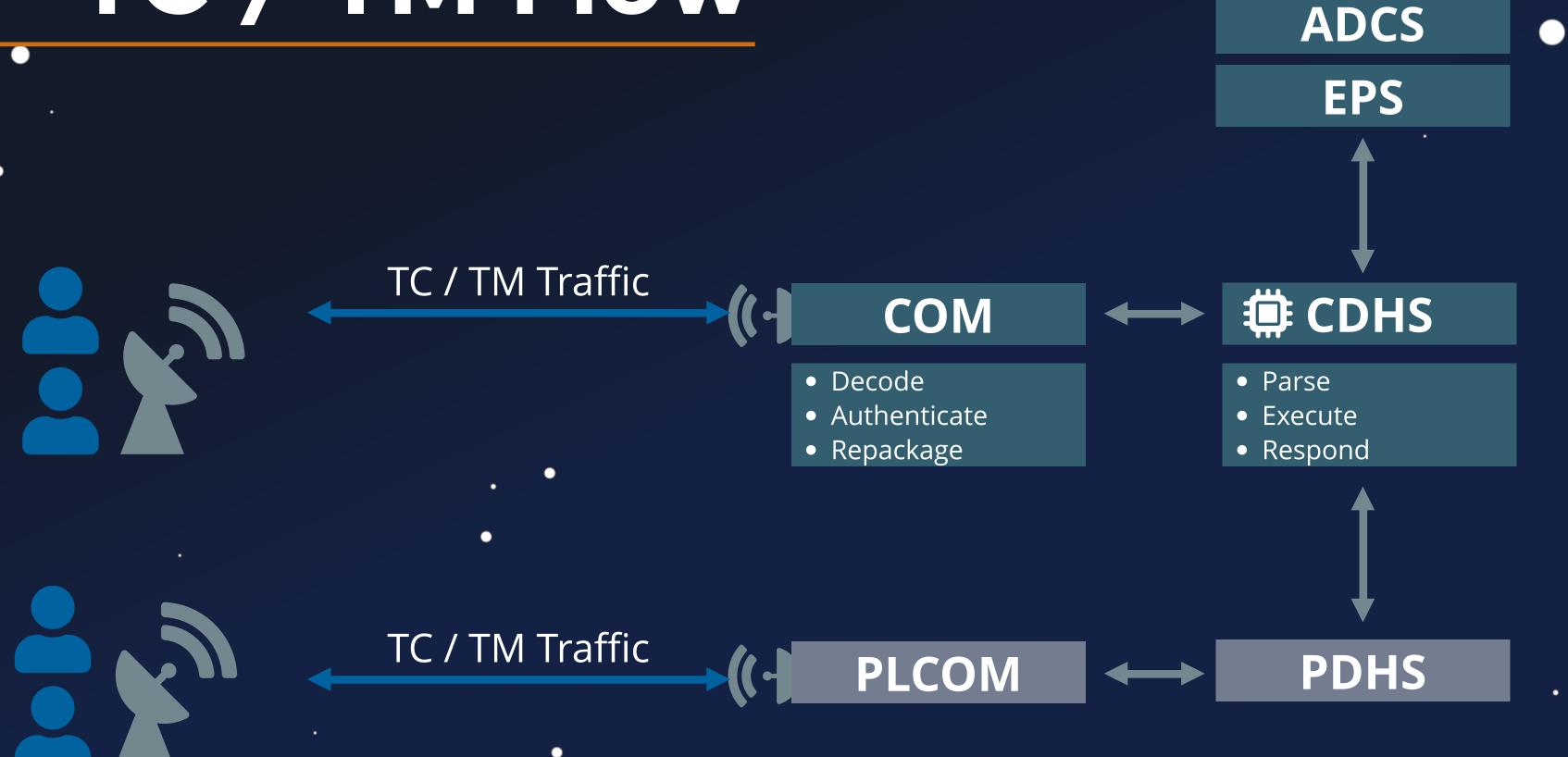
EPS

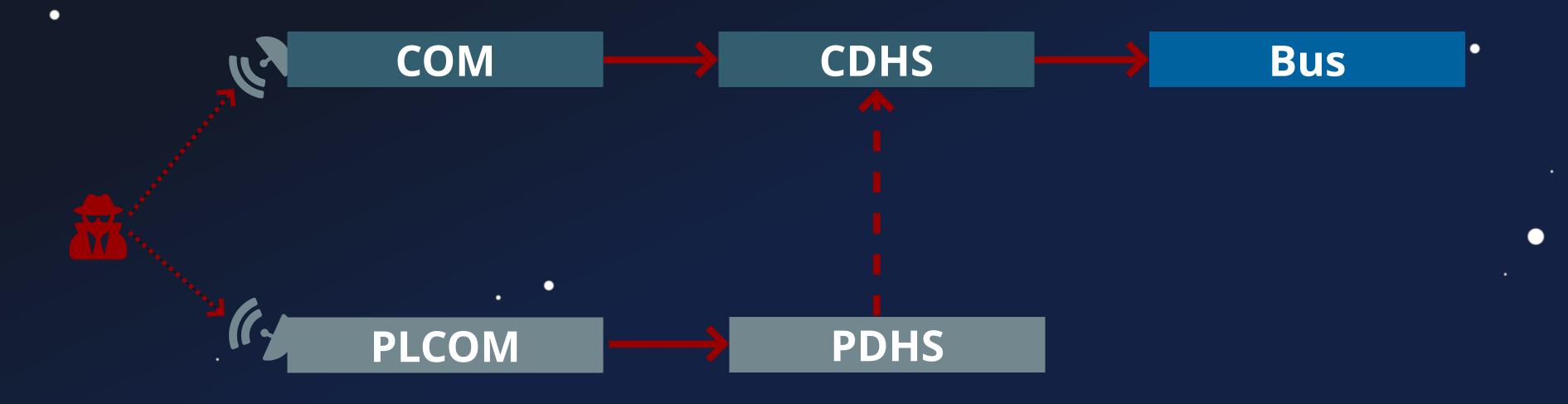


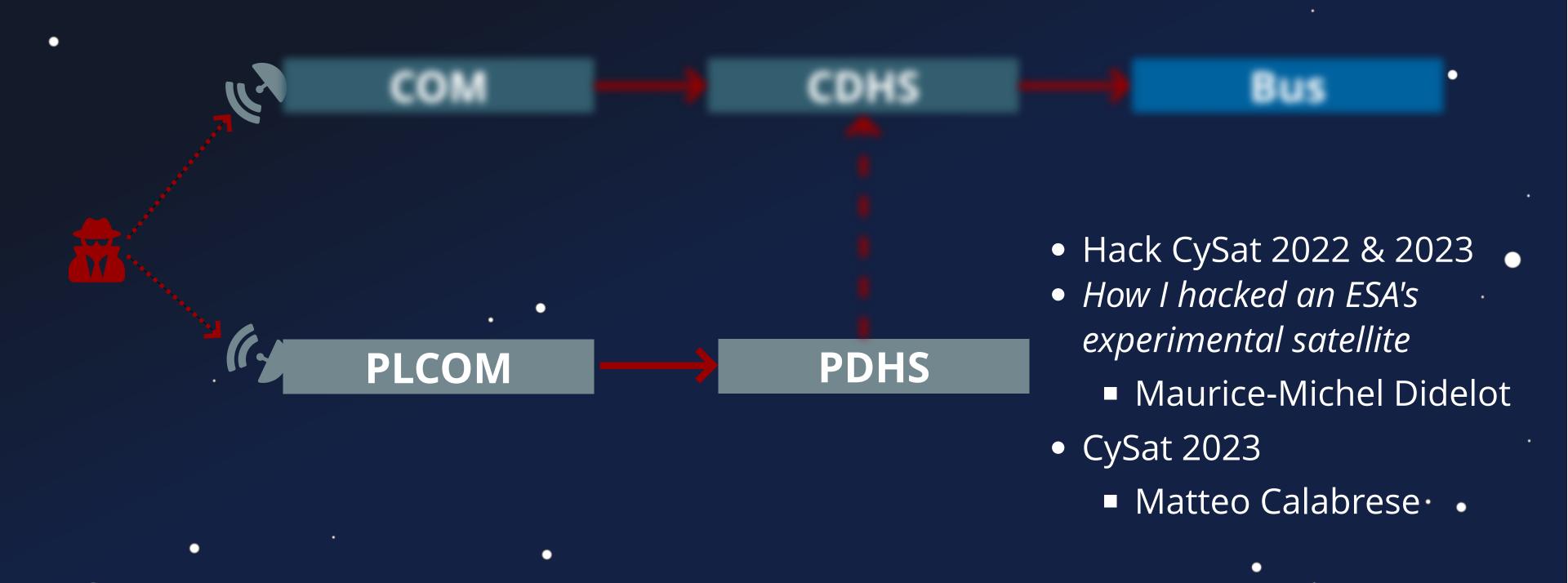
- Parse
- Execute
- Respond

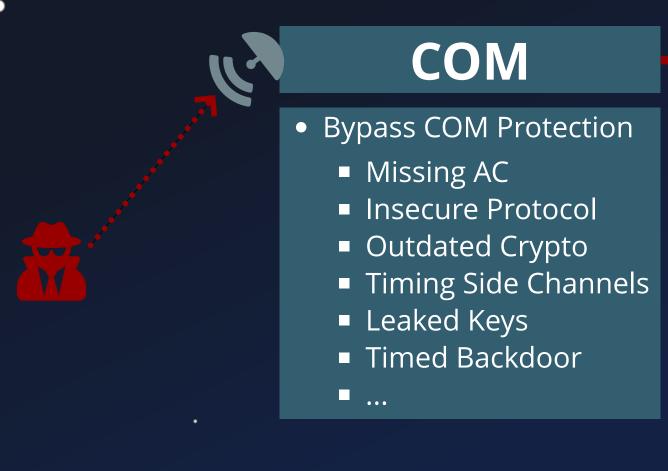
Payload

TC/TMFlow



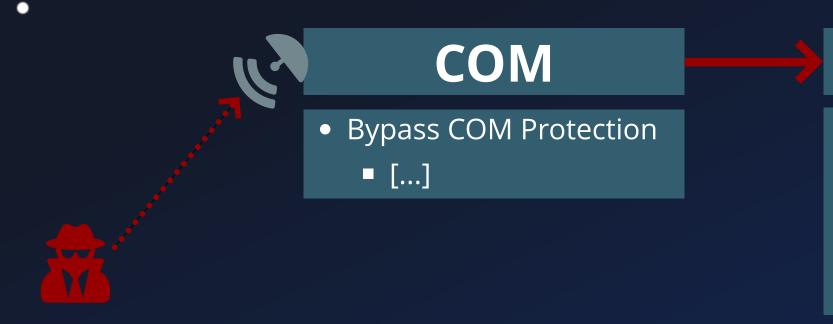






CDHS

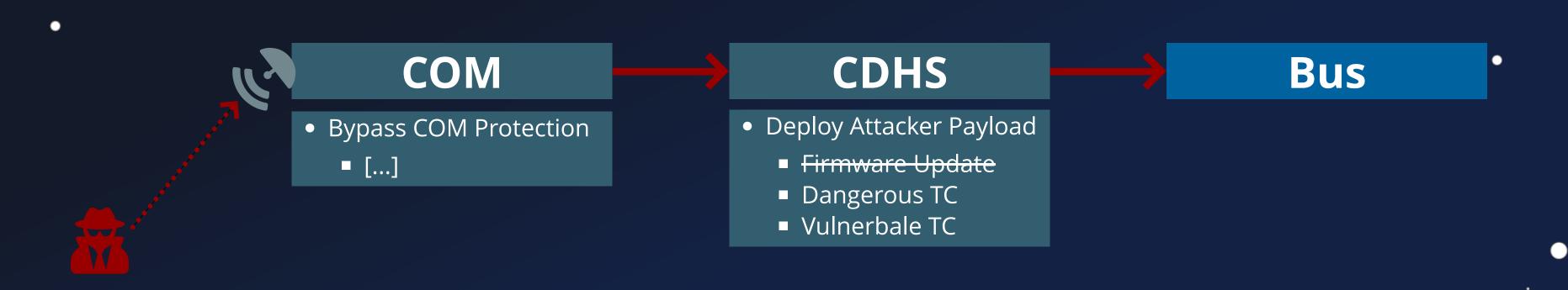
Bus



CDHS

- Deploy Attacker Payload
 - Firmware Update
 - Signed Image
 - Slow Upload
 - Complex System

Bus





COM

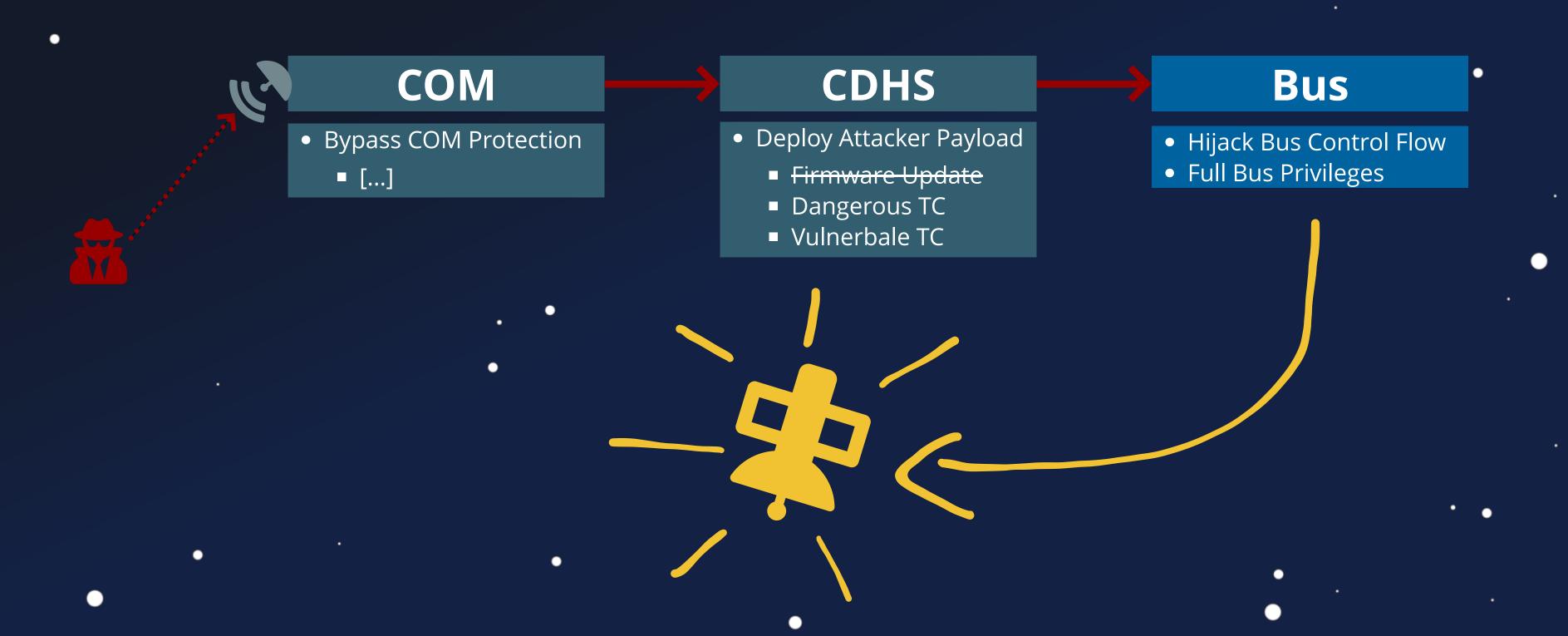
- Bypass COM Protection
 - **[...]**

CDHS

- Deploy Attacker Payload
 - Firmware Update
 - Dangerous TC
 - Vulnerbale TC

Bus

- Hijack Bus Control Flow
- Full Bus Privileges



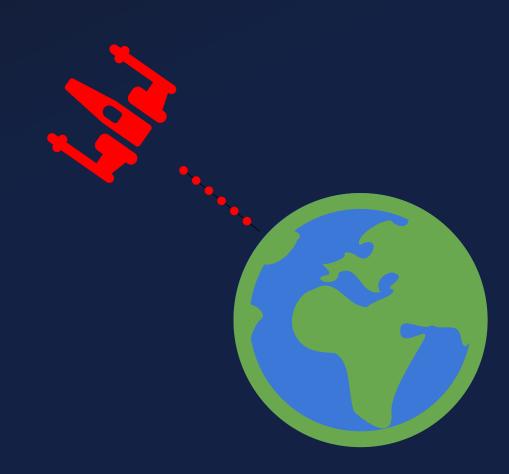
Objectives

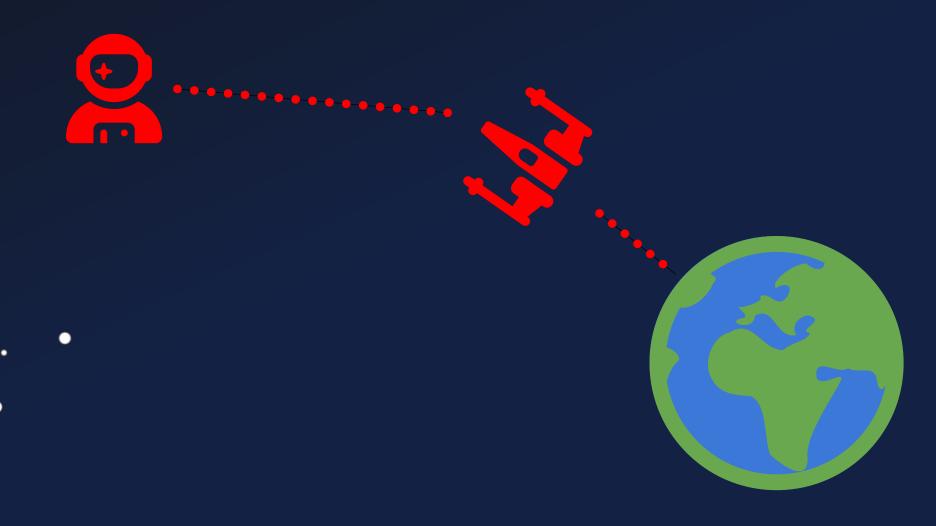




- 1 Bypass COM Protection
- 2 Dangerous / Vulnerable TC
- 3 Hijack Bus Control Flow
- 4 Full Bus Privileges



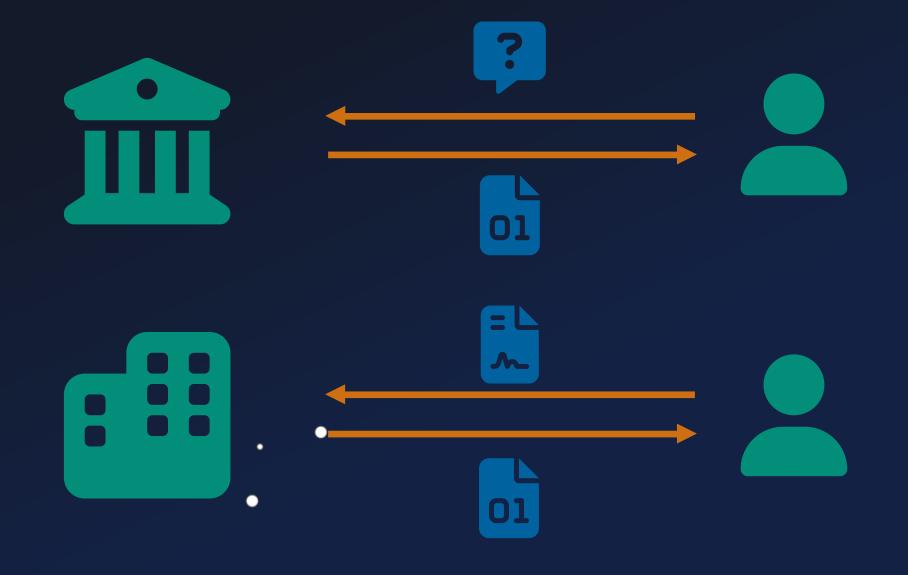


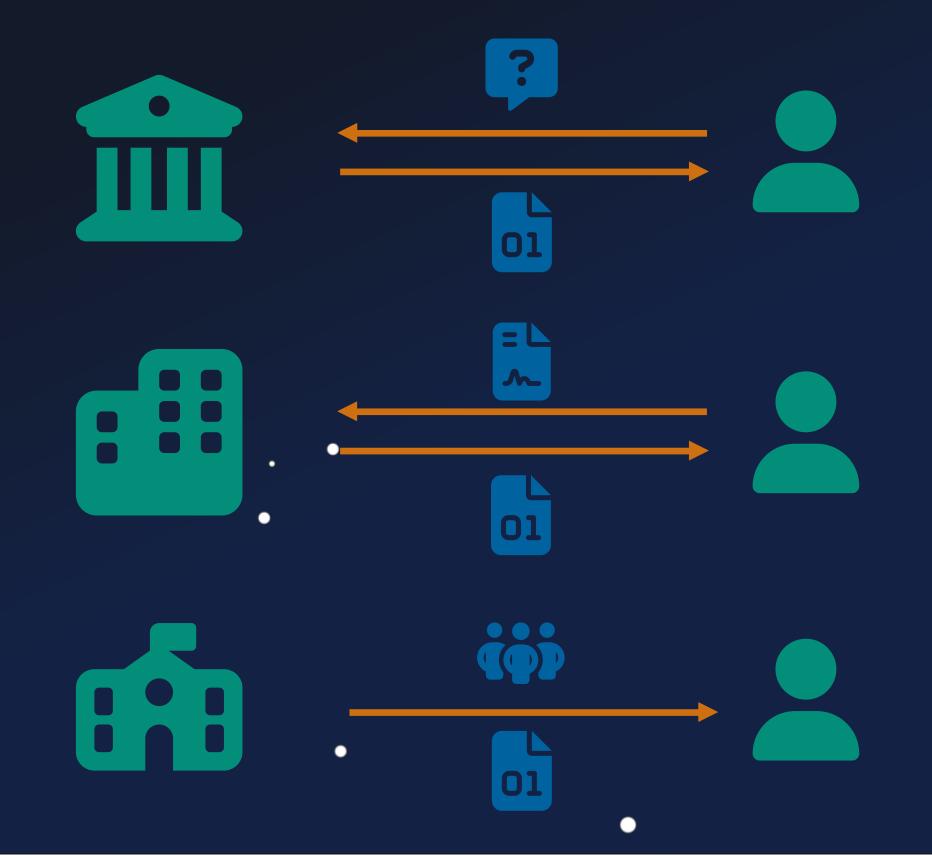


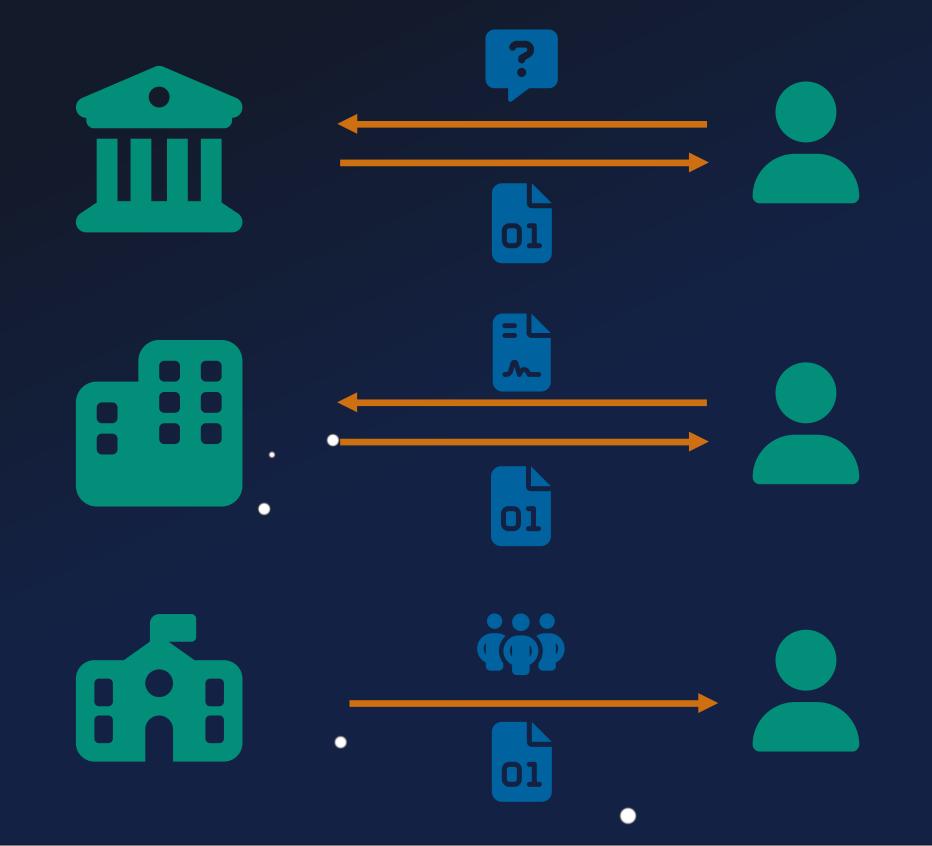






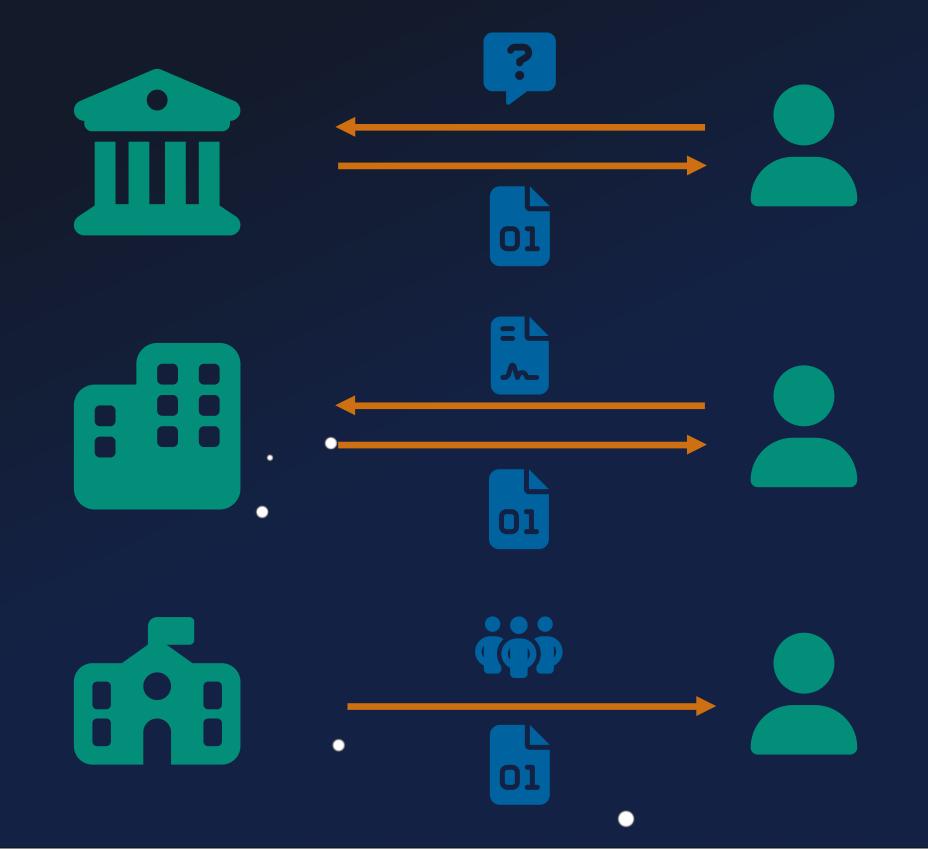








Security by Obscurity





Security by Obscurity



Result Publication



Manual Reverse Engineering



Manual Reverse Engineering

- Underlying system designs
- "Rare" Target architectures
- New protocols
- Redundancies



Manual Reverse Engineering

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Manual Vulnerability
Analysis



Manual Reverse Engineering

- Underlying system designs
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Manual Vulnerability
Analysis

- Followed TC data paths
- Missing security measures
- Dangerous TC actions
- Low hanging Fruits: memcpy, strcpy, etc.



Manual Reverse Engineering

- Underlying system designs
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Manual Vulnerability
Analysis



Automated Fuzz Testing

- Followed TC data paths
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Manual Vulnerability
Analysis

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- Low hanging Fruits: memcpy, strcpy, etc.



Automated Fuzz Testing

- Missing emulators
- Satellite-specific configurations
- More @ Typhoocon'23

System Analysis



OPS-Sat



Experimenter

Operated by ESA
Open for Research

S-/X-Band, SDR, Optical Rx., Camera, ...

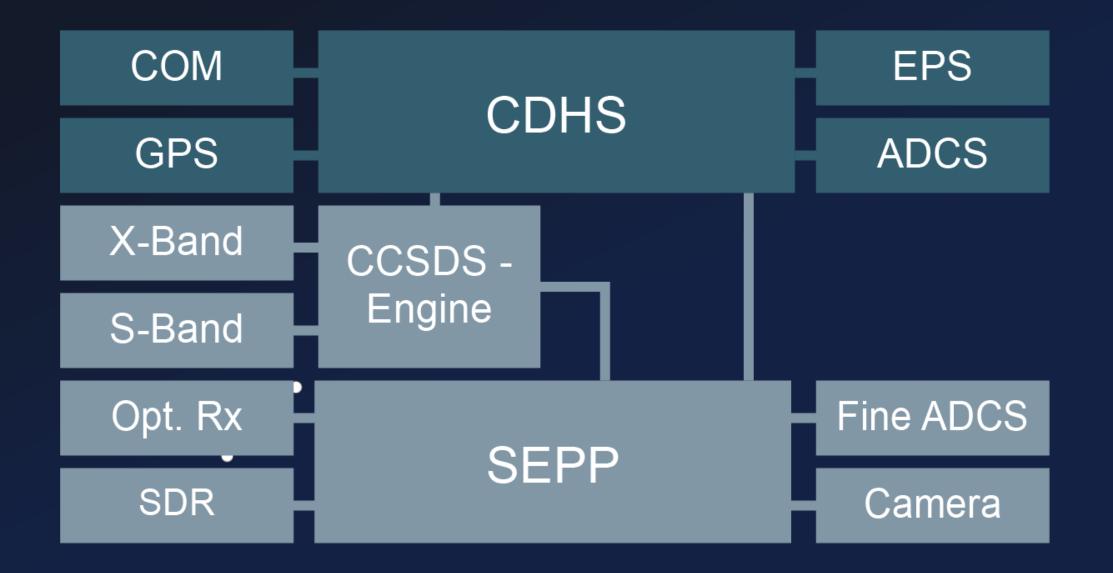
Peripherals

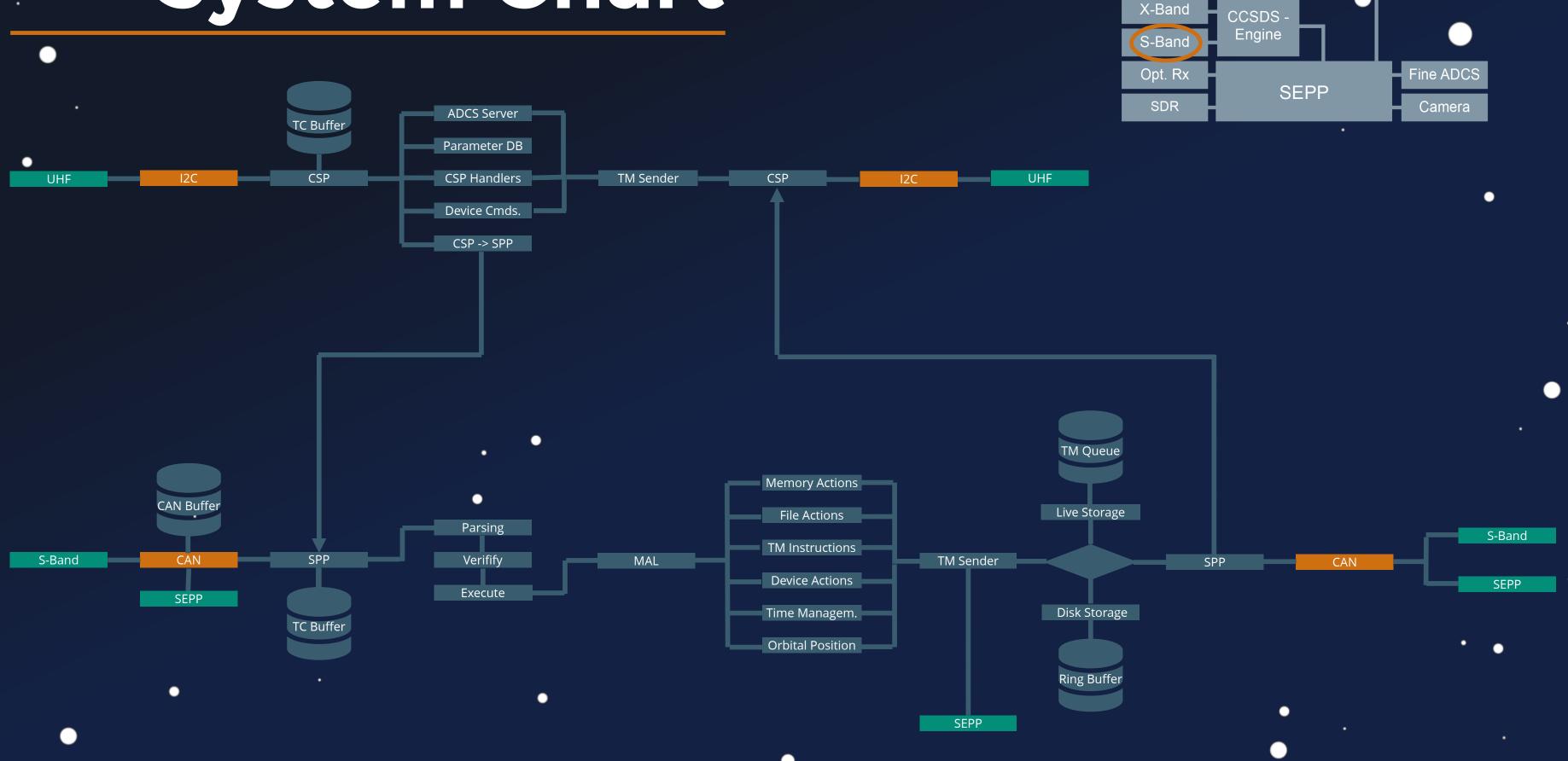
ARM-Based Linux + FPGA

Payload Plattform

December 2019

Launched



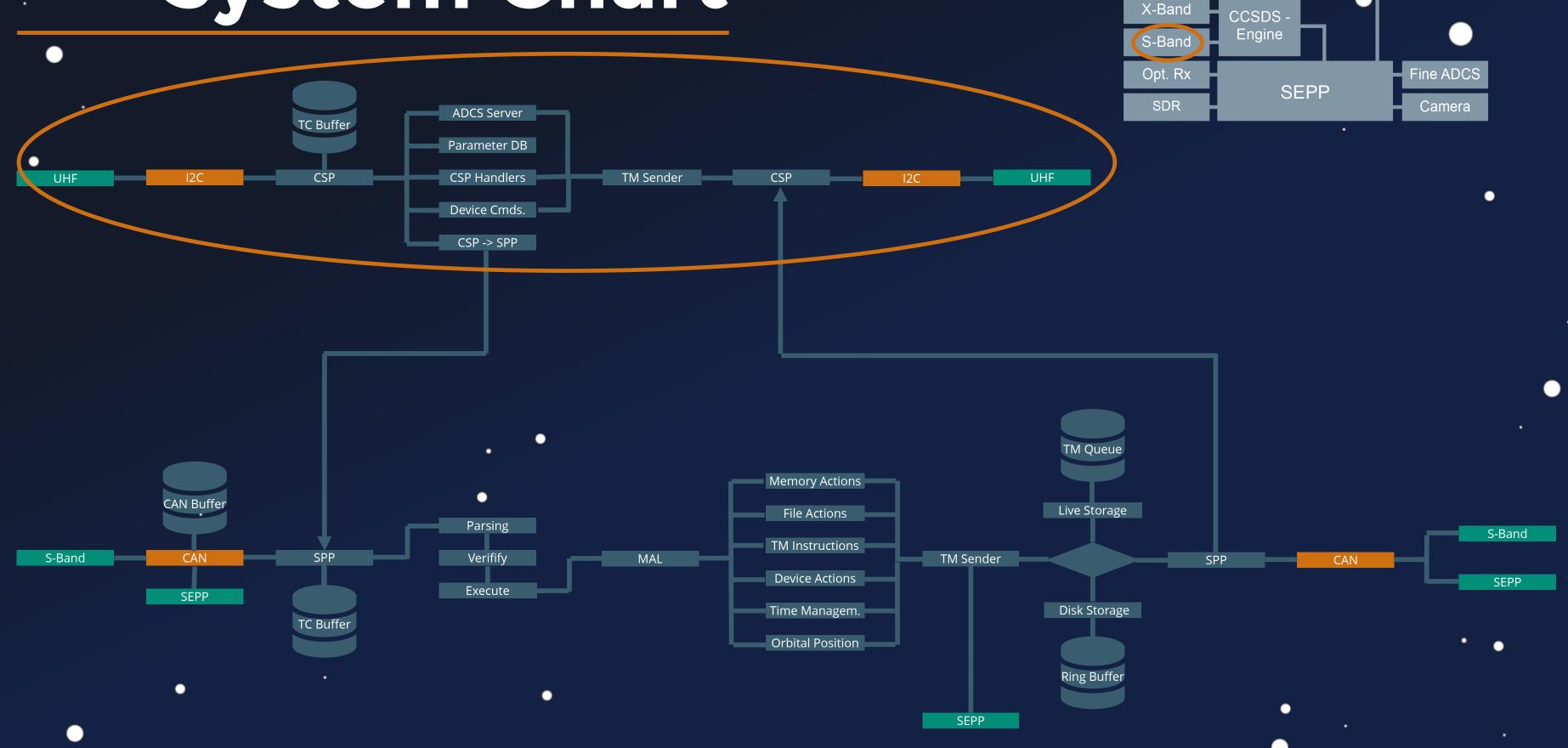


COM

GPS

CDHS

EPS

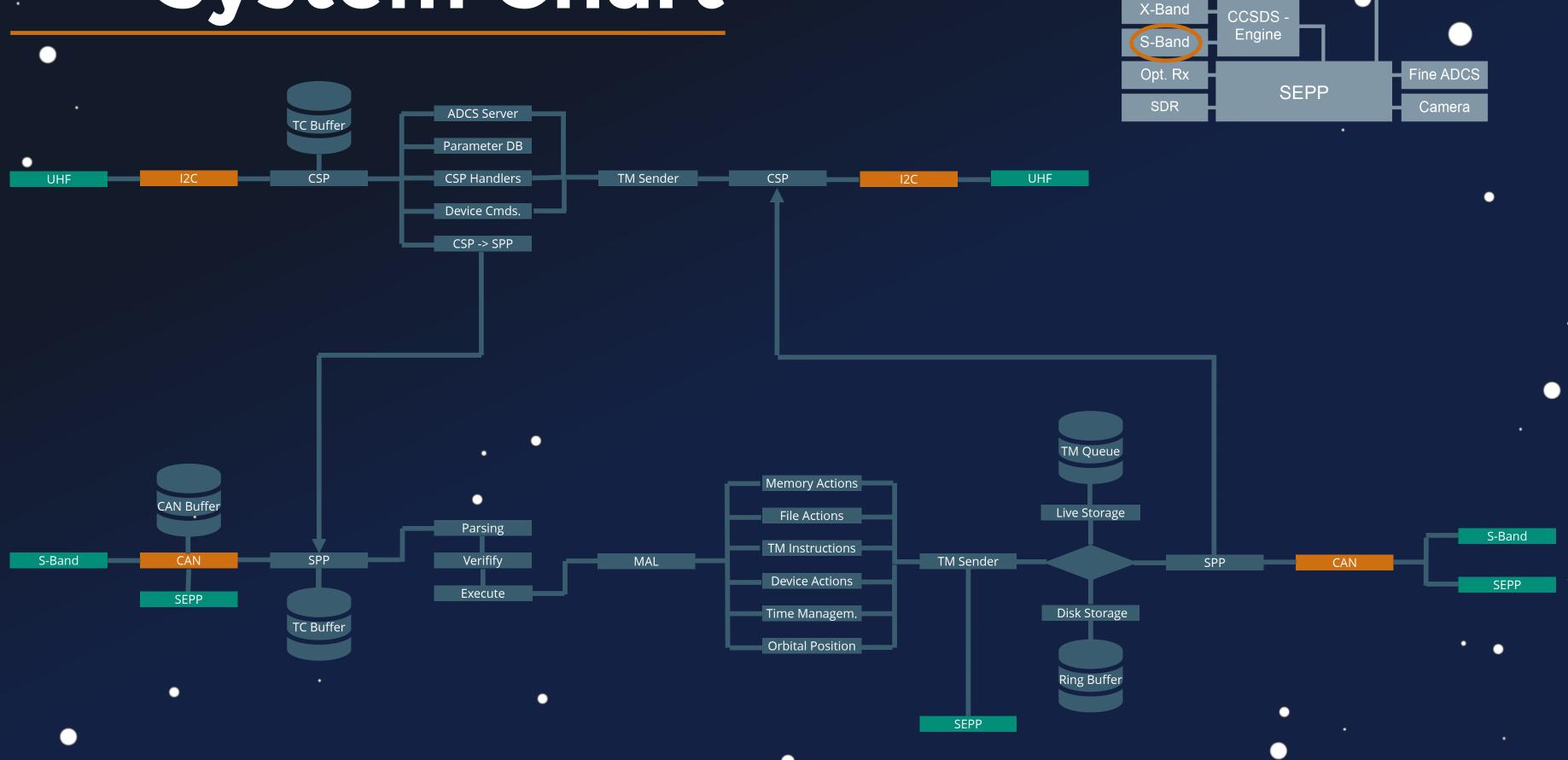


COM

GPS

CDHS

EPS

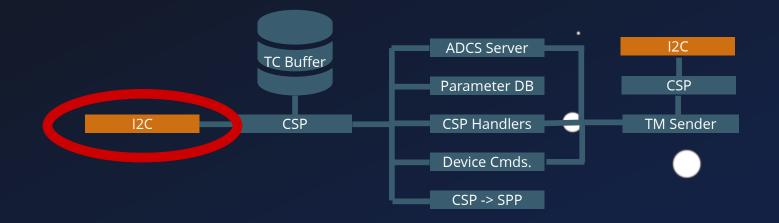


COM

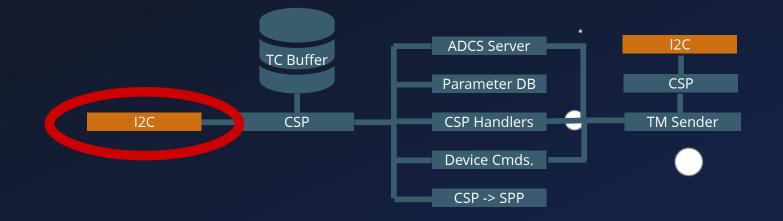
GPS

CDHS

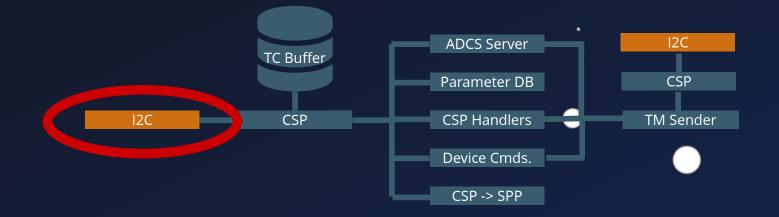
EPS



```
1 void csp i2c rx(i2c frame t *frame, void *pxTaskWoken) {
     if (frame) {
       frame len = frame->len - 4;
       if (frame len > 0xfc) {
         csp if i2c.frame = csp if i2c.frame + 1;
         csp buffer free isr(frame);
         return;
 8
 9
10
       frame->len = frame len;
11
       i2c rx csp packet = (csp_packet_t *) frame;
       h32 = csp ntoh32(frame->data[3] | frame->data[1] << 0x10
12
13
                           frame->data[0] << 0x18 | frame->data[2] << 8);
14
       frame->data[3] = (uint8_t)h32;
       frame->data[0] = (uint8_t)(h32 >> 0x18);
15
       frame->data[1] = (uint8_t)(h32 >> 0x10);
16
17
       frame->data[2] = (uint8_t)(h32 >> 8);
       csp qfifo write(i2c rx csp packet, &csp if i2c, pxTaskWoken);
18
19
20
     return;
21 }
```

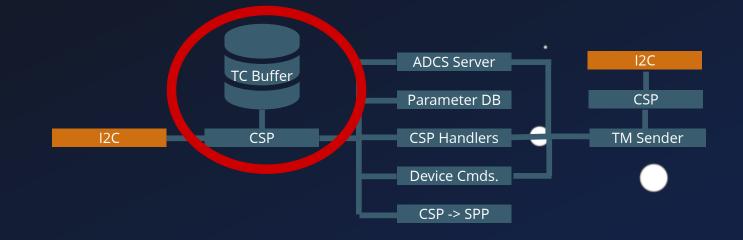


```
1 void csp i2c rx(i2c frame t *frame, void *pxTaskWoken) {
     if (frame) {
       frame ● ● ●
       if (f
             uint32 t csp ntoh32(uint32 t n32) {
         csr
                 return n32;
         csi
 8
         ret
 9
10
       fram∈
11
       i2c rx csp packet = (csp_packet_t *) frame;
       h32 = csp ntoh32(frame->data[3] | frame->data[1] << 0x10
12
                           frame->data[0] << 0x18 | frame->data[2] << 8);
13
14
       frame->data[3] = (uint8_t)h32;
15
       frame->data[0] = (uint8_t)(h32 >> 0x18);
       frame->data[1] = (uint8_t)(h32 >> 0x10);
16
       frame->data[2] = (uint8_t)(h32 >> 8);
17
18
       csp qfifo write(i2c rx csp packet, &csp if i2c, pxTaskWoken);
19
20
     return;
21 }
```



```
1 void csp i2c rx(i2c frame t *frame, void *pxTaskWoken) {
     if (frame) {
       frame ● ● ●
       if (f
             uint32 t csp ntoh32(uint32 t n32) {
         csr
                 return n32;
         cst
         ret
 9
10
       fram€
11
       i2c rx csp packet = (csp_packet_t *) frame;
       h32 = csp ntoh32(frame->data[3] | frame->data[1] << 0x10
12
                           frame->data[0] << 0x18 | frame->data[2] << 8);
13
14
       frame->data[3] = (uint8_t)h32;
       frame->data[0] = (uint8_t)(h32 >> 0x18);
15
       frame->data[1] = (uint8_t)(h32 >> 0x10);
16
17
       frame->data[2] = (uint8_t)(h32 >> 8);
18
       csp qfifo write(i2c rx csp packet, &csp if i2c, pxTaskWoken);
19
20
     return;
21 }
```





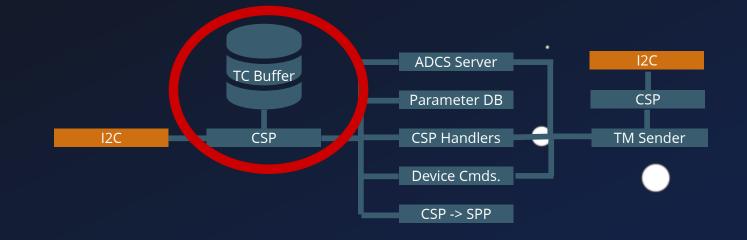
Cubesat Space Protocol (CSP) v1





	CSP Header 1.x																															
Bit offset	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	9
0	Priority Source			Destination Port				Source Port				F	Rese	erved	i	H M A C	X T E A	R D P	C R C													
32		Data (0 – 65,535 bytes)																														

Source: https://en.wikipedia.org/wiki/Cubesat_Space_Protocol



Cubesat Space Protocol (CSP) v1



Security Features

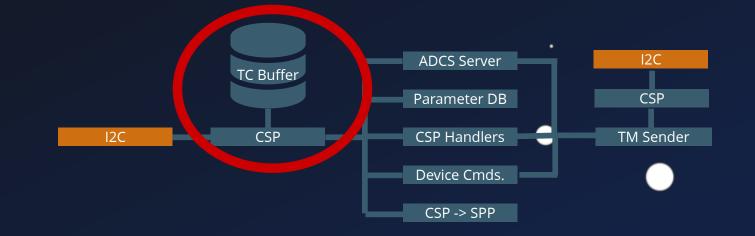
- HMAC-SHA1 Authentication
- XTEA Encryption Support



Security Issues

- 1. MAC comparison leaks timing data #44
 - memcmp to compare the digest
- 2. HMAC doesn't protect headers #45
 - Same problem for the CRC checks
- 3. XTEA encrypt packet nonce too predictable #162
 - const uint32_t nonce = (uint32_t)rand();

Authors: Issues fixed in libcsp v2



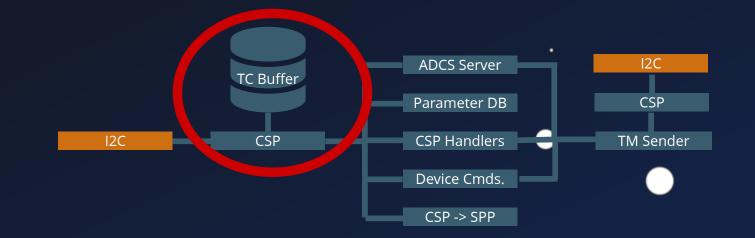
```
int csp_route_security_chek(...) {
  if (packet->id.flags & CSP_FXTEA) {
    csp_log_error("Received XTEA encrypted packet, but CSP was compiled without XTEA support. Discarding packet");
}

// ...

if (packet->id.flags & CSP_FHMAC) {
    csp_log_error("Received packet with HMAC, but CSP was compiled without HMAC support. Discarding packet");
}

// ...

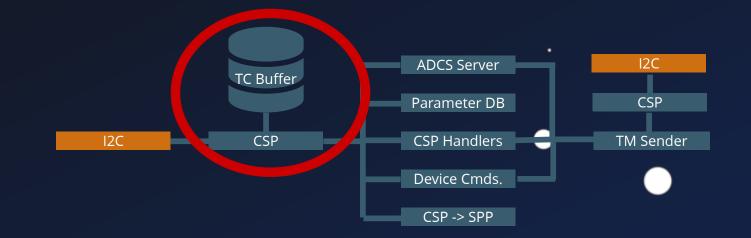
// ...
// ...
// ...
// ...
// ...
// ...
// ...
// ...
// ...
// ...
// ...
// ...
```





- "Default" Server
 - socket, bind, listen, accept

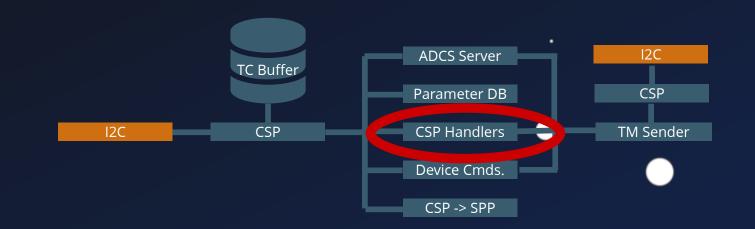
```
1 if (cspServerInitialised == false) {
     cspSocket = csp socket(0);
     if (!cspSocket) { return; }
     ret = csp bind(cspSocket, CSP ANY PORT);
     if (!ret) { return; }
     ret = csp listen(cspSocket, 10);
     if (!ret) { return; }
10
11
     cspServerInitialised = true;
12 }
13
   cspServerConn = csp accept(cspSocket, 10);
  if (cspServerConn) {
     while (request packet = csp read(cspServerConn,0), packet) {
       dest port = csp conn dport(cspServerConn);
17
       switch(dest port) {
18
19
20
21
     csp close(cspServerConn);
23 }
```





- "Default" Server
 - socket, bind, listen, accept

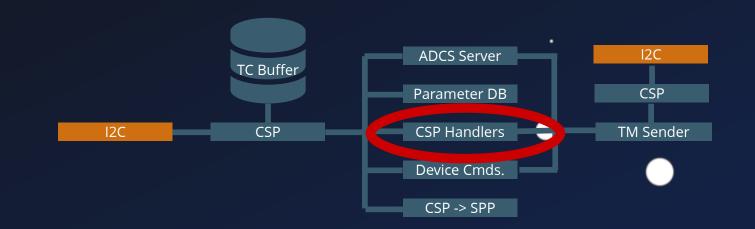
```
(cspServerInitialised == false) {
     cspSocket = csp_socket(0);
     if (!cspSocket) { return; }
     ret = csp bind(cspSocket, CSP ANY PORT);
     if (!ret) { return; }
     ret = csp_listen(cspSocket, 10);
     cspServerInitialised = true;
   cspServerConn = csp accept(cspSocket, 10);
   if (cspServerConn) 
     while (request packet = csp read(cspServerConn,0), packet) {
17
       dest port = csp conn dport(cspServerConn);
       switch(dest port) {
22
     csp close(cspServerConn);
```





- Network Info Handlers
- Ping
- OS Tasklist
- Remaining Memory
- System Reboot
- Current Time

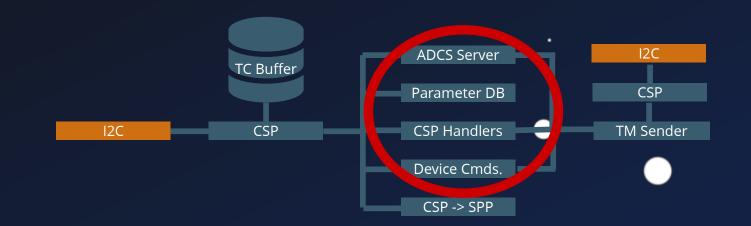
```
1 switch(csp conn dport(conn)) {
           case 0: // Network information handlers
           csp cmp handler(conn, packet);
           break;
       case 1: // Ping
           do csp debug(2, "SERVICE: Ping received");
           break;
       case 2: // OS Tasklist
           csp sys tasklist(str, size);
           csp send(conn, packet, 0);
           break;
13
       case 3: // Remaining Memory
           val = csp sys memfree();
14
15
16
           csp send(conn, packet, 0);
17
           break;
       case 4: // System Reboot
           if(packet->data[0..4] == BYTESEQ) { csp_sys_reboot(); }
20
21 }
```





- Network Info Handlers
- Ping
- OS Tasklist
- Remaining Memory
- System Reboot
- Current Time

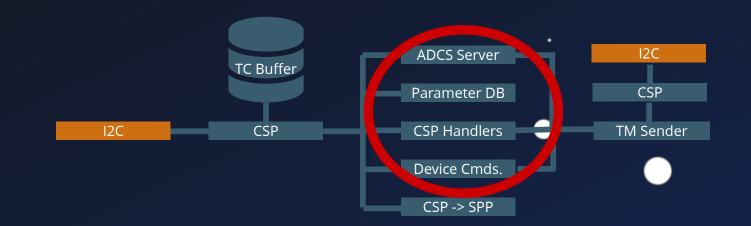
```
1 switch(csp conn dport(conn)) {
          csp_cmp_handler(conn, packet);
      case 1: // Ping
          do csp debug(2, "SERVICE: Ping received");
          csp sys tasklist(str, size);
          csp send(conn, packet, 0);
          val = csp sys memfree();
          csp_send(conn, packet, 0);
          if(packet->data[0..4] == BYTESEQ) { csp_sys_reboot(); }
```



Central Services

```
dest_port = csp_conn_dport(conn);
switch(dest_port) {
   case 0x00 - 0x06:
      csp_service_handler(conn, pkt);
   case 0x07:
      rparam_service_handler(conn, pkt);
   case 0x10:
      CSP_ProcessReceivedSPP(pkt);
}
```

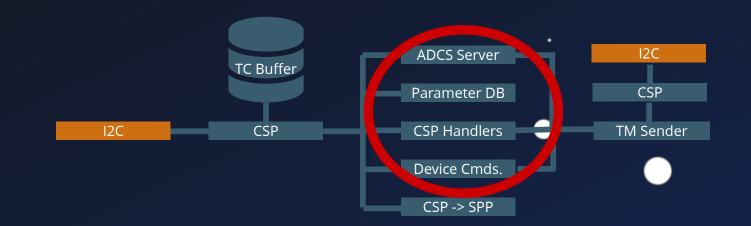
```
1 // csp listen, bind(0x14), accept
 2 switch(val) {
     case 0x1: // Set ADCS Mode
       memcpy(packet->data + 2, _adcs_mode, 7);
       packet->data[1] = '\0';
       packet->length = 0;
       goto send packet set len;
     case 0x1c:
       gs adcs gps on();
 9
10
       break;
     case '\x14': # Set ADCS Wheel position
11
       gs_adcs_wheels_diag(packet->data[2],&val0,&val1);
12
13
       packet->data[1] = '\0';
       h16 = util hton16(val0);
14
       packet->data[5] = (char)(h16 & 0xffff);
15
       packet->data[4] = (char)((h16 & 0xffff) >> 8);
16
       h16 = util hton16(val1);
17
       packet->data[7] = (char)(h16 & 0xffff);
18
       packet->data[6] = (char)((h16 & 0xffff) >> 8);
19
20
21
       packet->length = 0;
```



Central Services

```
dest_port = csp_conn_dport(conn);
switch(dest_port) {
   case 0x00 - 0x06:
      csp_service_handler(conn, pkt);
   case 0x07:
      rparam_service_handler(conn, pkt);
   case 0x10:
      CSP_ProcessReceivedSPP(pkt);
}
```

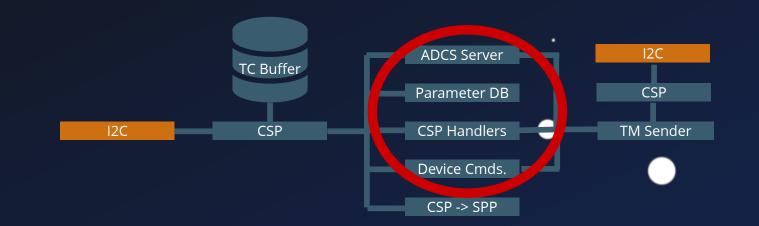
```
case 0x1: // Set ADCS Mode
       memcpy(packet->data + 2, _adcs_mode, 7);
       packet->data[1] = '\0';
       packet->length = 0;
       goto send packet set len;
     case 0x1c:
       gs_adcs_gps_on();
     case '\x14': # Set ADCS Wheel position
       gs_adcs_wheels_diag(packet->data[2],&val0,&val1);
       packet->data[1] = '\0';
       h16 = util hton16(val0);
       packet->data[5] = (char)(h16 & 0xffff);
       packet->data[4] = (char)((h16 & 0xffff) >> 8);
       h16 = util hton16(val1);
       packet->data[7] = (char)(h16 & 0xffff);
       packet->data[6] = (char)((h16 & 0xffff) >> 8);
       packet->length = 0;
```



Central Services

```
dest_port = csp_conn_dport(conn);
switch(dest_port) {
   case 0x00 - 0x06:
      csp_service_handler(conn, pkt);
   case 0x07:
      rparam_service_handler(conn, pkt);
   case 0x10:
      CSP_ProcessReceivedSPP(pkt);
}
```

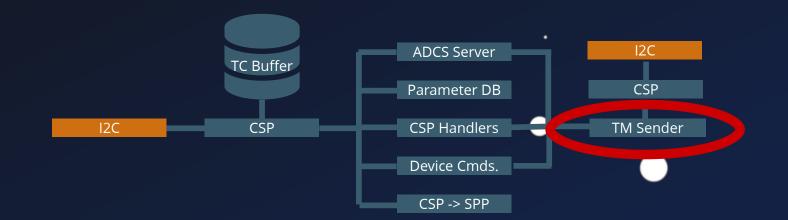
```
case 0x1: // Set ADCS Mode
      memcpy(packet->data + 2, _adcs_mode, 7);
      packet->data[1] = '\0';
       packet->length = 0;
       goto send packet set len;
     case 0x1c:
       gs adcs gps on();
 9
10
       break;
     case '\x14': # Set ADCS Wheel position
       gs_adcs_wheels_diag(packet->data[2],&val0,&val1);
       packet->data[1] = '\0';
       h16 = util hton16(val0);
       packet->data[5] = (char)(h16 & 0xffff);
       packet->data[4] = (char)((h16 & 0xffff) >> 8);
       h16 = util hton16(val1);
       packet->data[7] = (char)(h16 & 0xffff);
       packet->data[6] = (char)((h16 & 0xffff) >> 8);
       packet->length = 0;
```



Central Services

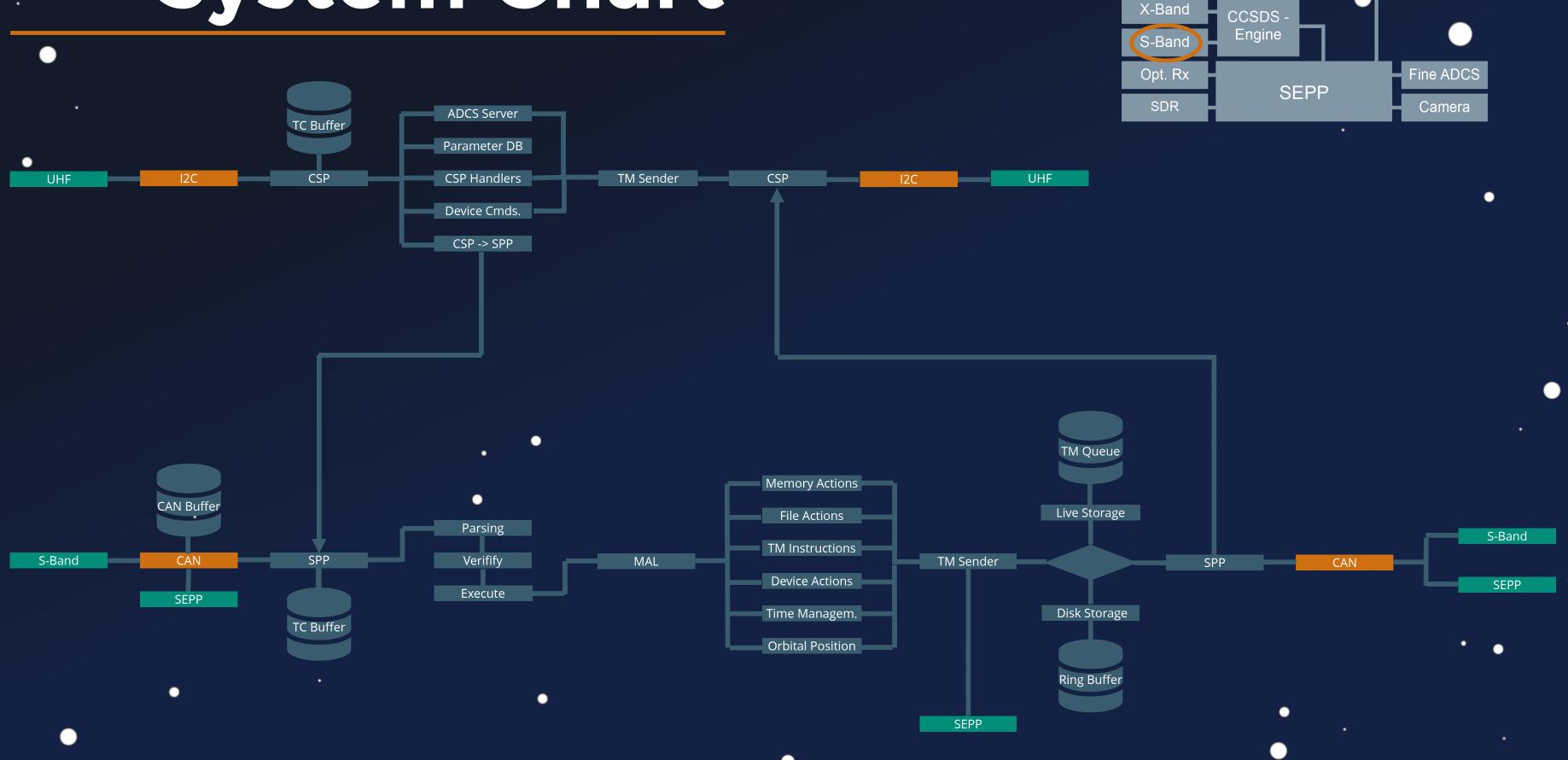
```
dest_port = csp_conn_dport(conn);
switch(dest_port) {
   case 0x00 - 0x06:
      csp_service_handler(conn, pkt);
   case 0x07:
      rparam_service_handler(conn, pkt);
   case 0x10:
      CSP_ProcessReceivedSPP(pkt);
}
```

```
switch(val) {
     case 0x1: // Set ADCS Mode
       memcpy(packet->data + 2, adcs mode, 7);
       packet->data[1] = '\0';
       packet->length = 0;
       goto send packet set len;
     case 0x1c:
       gs adcs gps on();
     case '\x14': # Set ADCS Wheel position
11
12
       gs_adcs_wheels_diag(packet->data[2],&val0,&val1);
       packet->data[1] = ' \setminus 0';
13
14
       h16 = util hton16(val0);
       packet->data[5] = (char)(h16 & 0xffff);
15
       packet->data[4] = (char)((h16 & 0xffff) >> 8);
16
17
       h16 = util hton16(val1);
       packet->data[7] = (char)(h16 & 0xffff);
18
       packet->data[6] = (char)((h16 & 0xffff) >> 8);
19
20
21
       packet->length = 0;
22
       goto send packet set len;
23 }
```



Sending Telemtry

```
1 send_packet_set_len:
2          *(char *)((int)&packet->length + 1) = len;
3 send_packet:
4          ret = csp_send(conn,packet,0);
5          if (!ret) goto failed;;
```

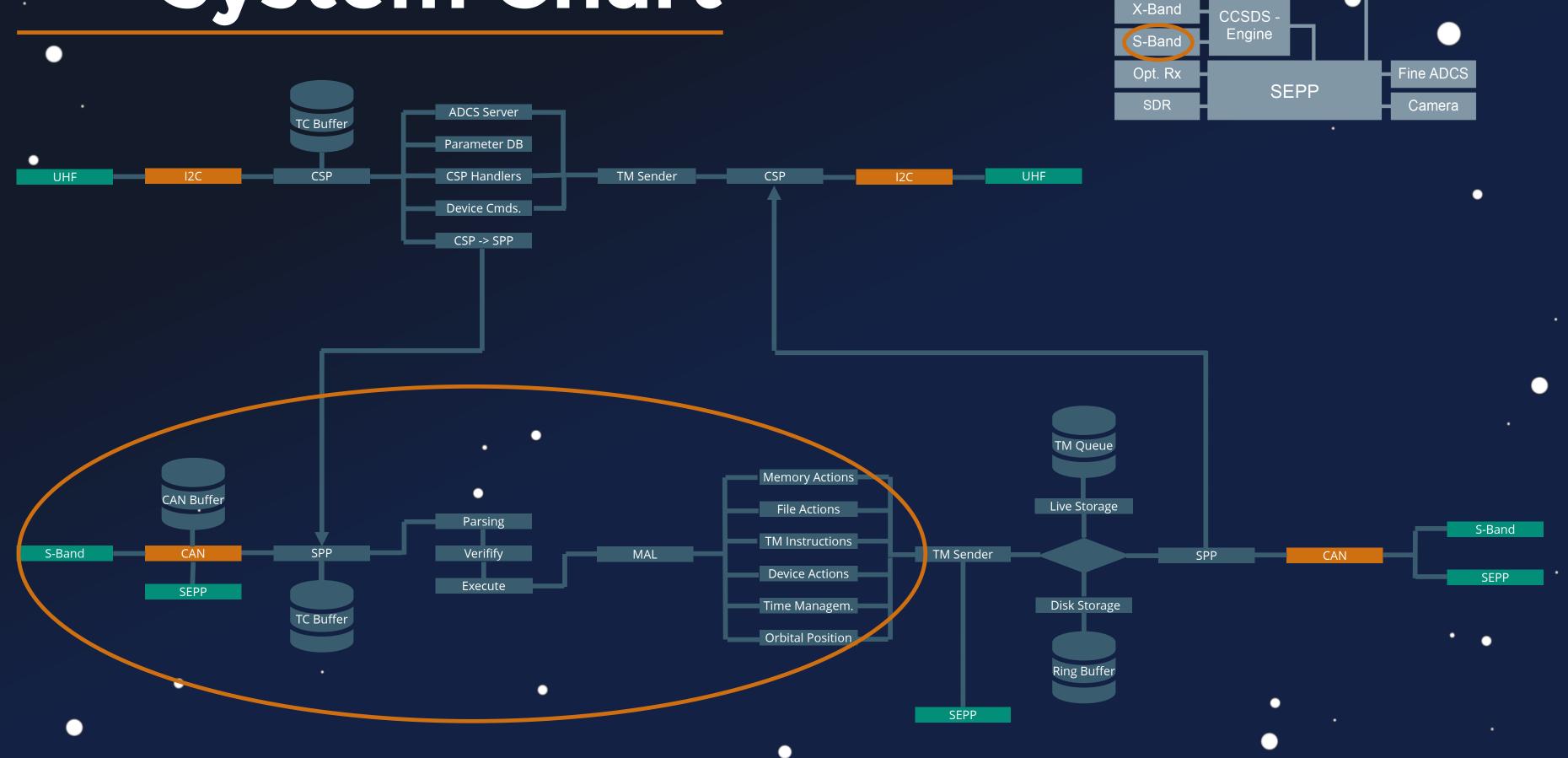


COM

GPS

CDHS

EPS



COM

GPS

CDHS

EPS



```
1 void can_rx_task_gmv(void) {
     if(frame type == START) {
       // Allocate packet
       if (curr_buf->packet == (CFP_Packet_t *)0x0) {
         tmp = csp buffer size();
         packet = (CFP_Packet_t *)csp_buffer_get(tmp - 0xe);
         curr_buf->packet = packet;
       } else { ... }
10
       curr buf->rx count = 0;
11
       curr buf->remain = frame_id >> 0xd & 0x1f;
12
13
       // Copy to Global Buffer
14
       memcpy(datablockGlobalRx.Data, &can frame.data, can frame.dlc);
       datablockGlobalRx.Size = can frame.dlc + datablockGlobalRx.Size;
15
16
17
18
     else if(frame type == CONTINUE) {
       can remain = frame id >> 0xd & 0x1f;
19
       // Check continous ID
20
```



```
1 void can_rx_task_gmv(void) {
     if(frame_type == START) {
      // Allocate packet
       if (curr buf->packet == (CFP_Packet_t *)0x0) {
         tmp = csp buffer size();
         packet = (CFP_Packet_t *)csp_buffer_get(tmp - 0xe);
         curr buf->packet = packet;
       } else { ... }
10
11
       curr buf->rx count = 0;
       curr buf->remain = frame id >> 0xd & 0x1f;
12
       // Copy to Global Buffer
13
       memcpy(datablockGlobalRx.Data, &can frame.data, can frame.dlc);
14
       datablockGlobalRx.Size = can frame.dlc + datablockGlobalRx.Size;
15
16
17
     else if(frame type == CONTINUE) {
       can remain = frame_id >> 0xd & 0x1f;
```

		bufferGlobal		
		34116161616		
±	d0108f98		undefine	??
		bufferGlobal2		
±	d0109380		undefine	
	d010947f		??	??
		tBufferSPP		
±	d0109480		undefine	??
		t_TC_PacketBuffer.	16356	
±	d0109868		undefine	
	d0109967		??	??
		TCPacketBuffer[0]. TCPacketBuffer	entryLength	
±	d0109968		COMTT_Pa	??
	d010fef8		??	??
	d010fef9		??	??
	d010fefa		??	??
	d010fefb		??	??



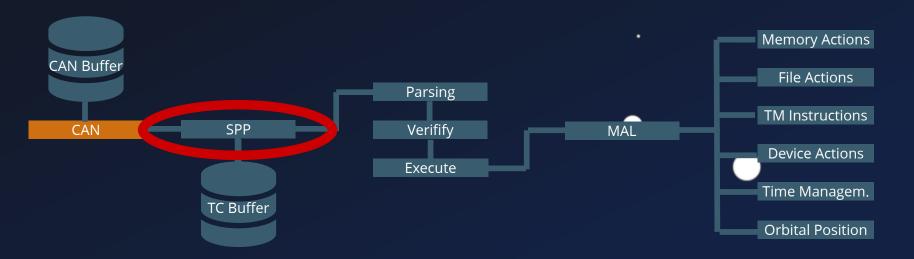
```
13.
       memcpy(datablockGlobalRx.Data, &can frame.data, can frame.dlc);
       datablockGlobalRx.Size = can frame.dlc + datablockGlobalRx.Size;
18
     else if(frame type == CONTINUE) {
19
       can remain = frame id >> 0xd & 0x1f;
20
       // Check continous ID
       if (can remain == curr buf->remain - 1) {
21
         curr buf->remain = can remain;
22
         curr buf->rx count = curr buf->rx count + (ushort)can frame.dlc;
23
         // Copy to Global Buffer
24
25
         memcpy(datablockGlobalRx.Data + datablockGlobalRx.Size,
26
                &can frame.data, can frame.dlc);
         datablockGlobalRx.Size = (uint)can frame.dlc + datablockGlobalRx.Size;
27
28
29
     else if(frame type == END) {
       can remain = frame id >> 0xd & 0x1f;
       if (can remain != curr buf->remain - 1) {
         memcpy(datablockGlobalRx.Data + datablockGlobalRx.Size,
```

		bufferGlobal		
±	d0108f98		undefine	??
		bufferGlobal2		
±	d0109380		undefine	
	d010947f	+DffCDD	??	??
		tBufferSPP		
±	d0109480		undefine	??
		t_TC_PacketBuffer.	16356	
±	d0109868		undefine	
	d0109967		??	??
		TCPacketBuffer[0]. TCPacketBuffer	entryLength	
±	d0109968		COMTT_Pa	??
	d010fef8		??	??
	d010fef9		??	??
	d010fefa d010fefb		?? ??	?? ??
	GOTOLELD		• •	

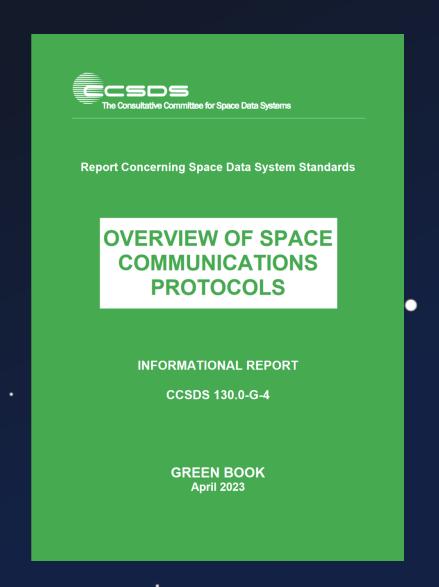


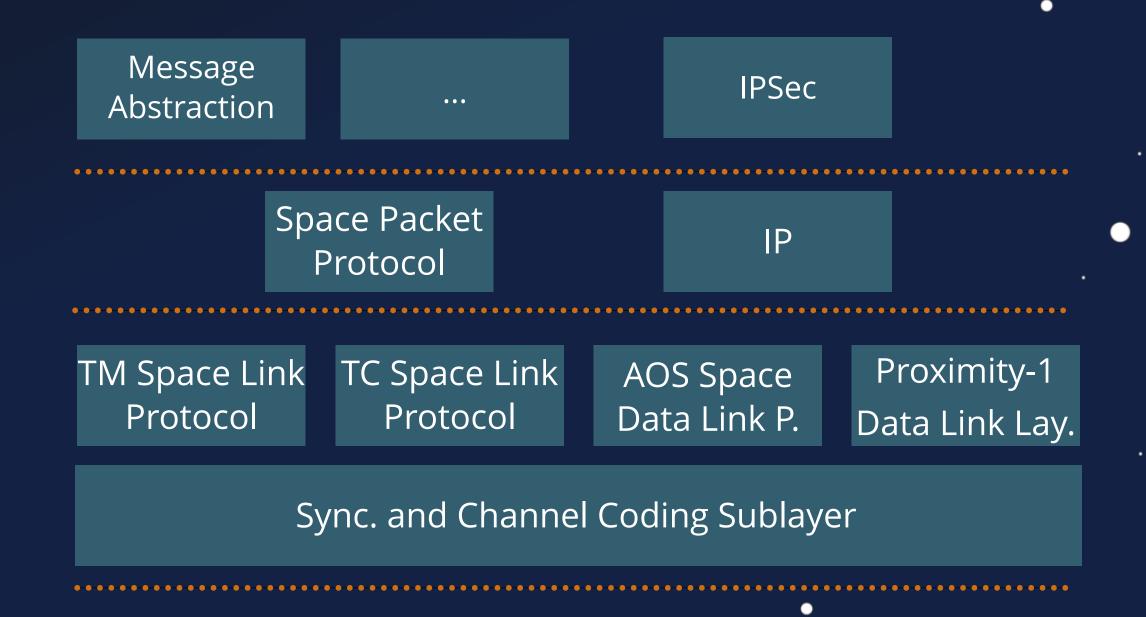
```
memcpy(datablockGlobalRx.Data + datablockGlobalRx.Size,
25
                &can frame.data, can frame.dlc);
         datablockGlobalRx.Size = (uint)can frame.dlc + datablockGlobalRx.Size;
30
31
     else if(frame type == END) {
32
       can remain = frame id >> 0xd & 0x1f;
33
       if (can remain != curr buf->remain - 1) {
         memcpy(datablockGlobalRx.Data + datablockGlobalRx.Size,
34
35
                &can frame.data, can frame.dlc);
         datablockGlobalRx.Size = can frame.dlc + datablockGlobalRx.Size;
36
37
         memcpy(datablockGlobalRxFinal.Data, datablockGlobalRx.Data,
                datablockGlobalRx.Size);
38
         datablockGlobalRxFinal.Size = datablockGlobalRx.Size;
39
40
         datablockGlobalFlag = 1;
         CAN AddPacketToCanStore(&datablockGlobalRxFinal);
41
```

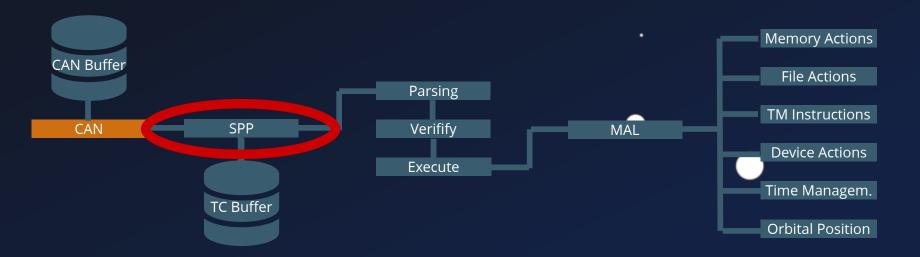
		bufferGlobal		
±	d0108f98		undefine	??
		bufferGlobal2		
		bulleIGIobal2		
+	d0109380		undefine	??
	d010947f		??	??
		tBufferSPP		
		CBUTTETSFF		
±	d0109480		undefine	??
		t TC DealestDuffer	16256	
		t_TC_PacketBuffer.	10350	
±	d0109868		undefine	??
	d0109967		??	??
		TCPacketBuffer[0].	entryl enath	
		TCPacketBuffer	circiycengen	
±	d0109968		COMTT_Pa	??
	d010fef8		??	??
	d010fef9		??	??
	d010fefa		??	??
	d010fefb		??	??



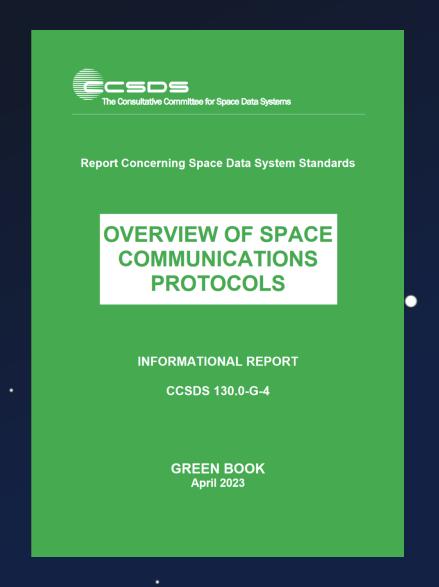
CCSDS - Protocol Stack

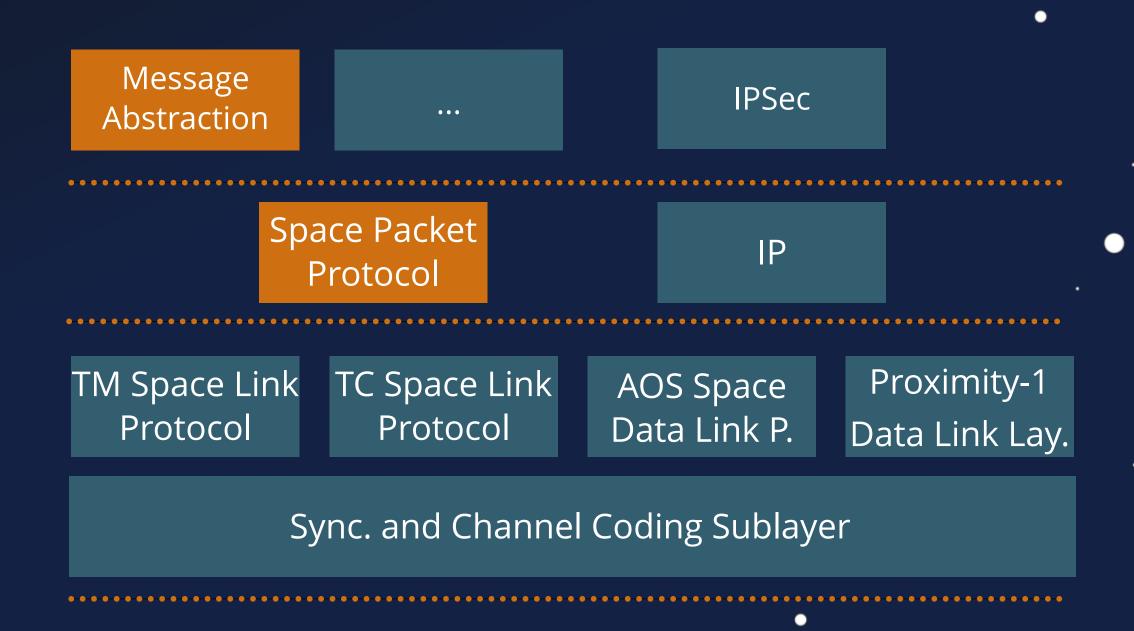


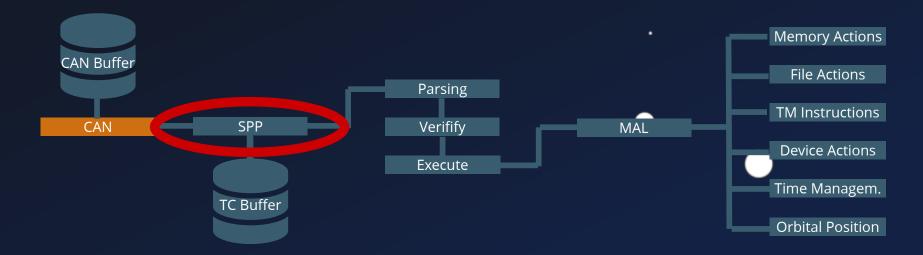




CCSDS - Protocol Stack

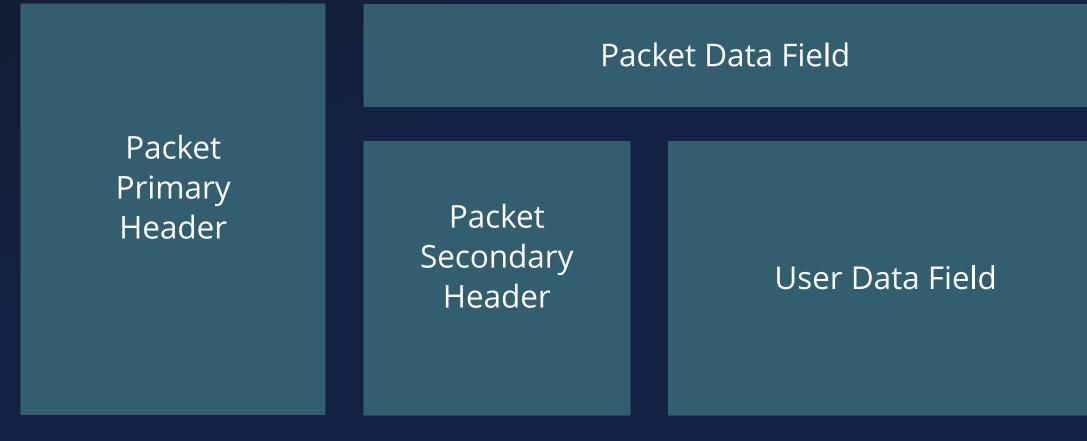




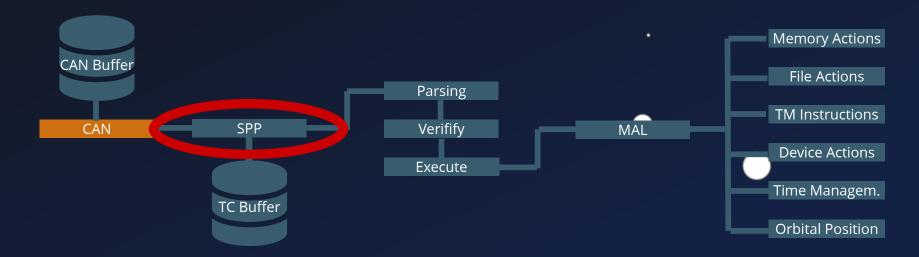


CCSDS - Space Packet Protocol (SPP)





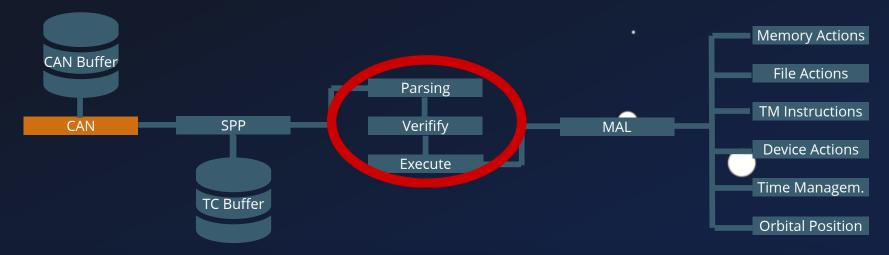
6 Bytes 1 - 65536 Bytes



CCSDS - Space Packet Protocol (SPP)



Packet Version Number	lde	Packet entificat	Packet Sequence Control			Packet Data	
Number	Packet Type	Sec. Header Flag	App. Process ID	Sequen. Flag	Sequen. Count		Length
3 bits	1 bit	1 bit	11 bits	2 bits	14 bits		16 bits

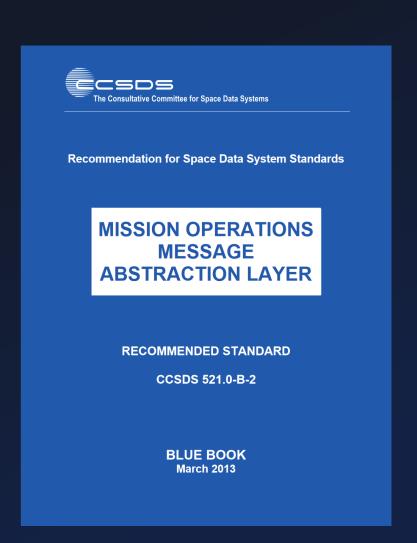


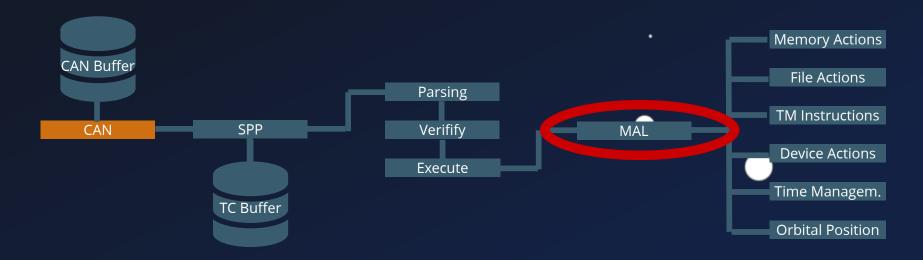
```
void TCTA_Cycle(void) {
TCMA_CleanTCBuffers();
TCMA_ReadCommand();
TCMA_VerifyCommand();
TCMA_ExecuteCommand();
return;
}
```

```
1 int TCMA ReadCommand(void) {
     packet = gRawPacketBuffer;
     ret = COMTT_GetReceivedTCPacket(&packet,0xff,&source_channel);
     if (ret == SUCCESS) {
       CKSM ComputeCRC(packet, &offset);
       do {
         currentState = &gTelecommandsInProcess[i].currentState;
         if(*currentState == EMPTY) {
10
           *currentState = READING;
11
           ret = SPP ReadSpacePacket(packet, packet.Size,
                          &gTelecommandsInProcess[i].telecommand)
12
13
           if(ret == SUCCESS) {
14
             // Read and set more fields ...
15
             *currentState = READ;
16
             i = 0x14;
17
           } else {
18
             *currentState = REJECTED;
19
20
       } while (i < 0x14);
21
22 }
```



CCSDS - Message Abstraction Layer (MAL)





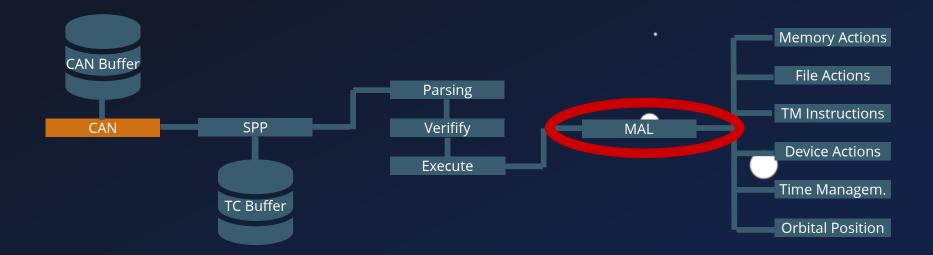
CCSDS - Message Abstraction Layer (MAL)

_							
	The Consultative Field		Type	Value			
		URI From	URI	Message Source URI			
Recommendati		Authentication Id	Blob	Source Authentication Identifier			
		URI To	URI	Message Destination URI			
		Timestamp	Time	Message generation timestamp			
	MISS	QoSlevel	QoSLevel	The QoS level of the message			
		Priority	UInteger	The QoS priority of the message			
	ABS1	Domain	List <identifier></identifier>	Domain of the message			
		Network Zone	Identifier	Network zone of the message			
		Session	SessionType	Type of session of the message			
	REC	Session Name	Identifier	Name of the session of the message			
		Interaction Type	InteractionType	Interaction Pattern Type			
		Interaction Stage	UOctet	Interaction Pattern Stag			
		Transaction Id	Long	Unique to consumer			
		Service Area	UShort	Service Are			
Servi		Service	UShort	Service			
Operation		Operation	UShort	Service Operation			
Area version		Area version	UOctet	Areaversion			
Is		Is Error Message	Boolean	'True' if this is an error message; else 'False			



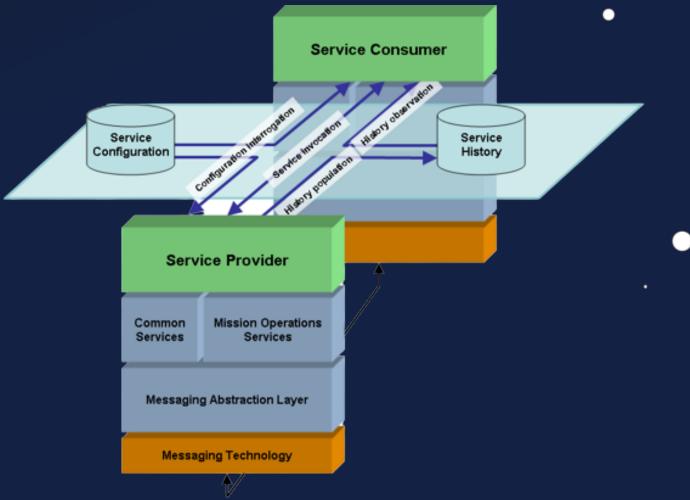
CCSDS - Message Abstraction Layer (MAL)

	csd	Field	Туре			Value			
The Consultative		URI From	URI			Source URI			
		Authentication Id	Blob			Source Authentication			
Recommendati		URI To	URI			Message Dest			
		Timestamp	Time			Message generation			
	MISS	QoSlevel	QoSLevel			The QoS level of t			
	MIOO	Priority	UInteger			The Oos priority of the massage			
	ABS1	Domain	List <identif< td=""><td></td><td>Name</td><td></td><td colspan="3">InteractionType</td></identif<>		Name		InteractionType		
		Network Zone	Identifier	Sho	ort Form Part		19		
		Session	SessionType		Ter om rare				
	REC	Session Name	Identifier	Enur	neration Value	Numeric Value	Comment		
		Interaction Type	InteractionT		SEND	1	Used for Send interactions.		
		Interaction Stage	UOctet			_			
		Transaction Id	Long		SUBMIT	2	Used for Submit interactions.		
		Service Area	UShort	I	REQUEST	3	Used for Request interactions.		
		Service	UShort		NWOKE	4	Head for Involve interestions		
	Operation UShort			INVOKE	4	Used for Invoke interactions.			
Area version UOctet Is Error Message Boolean		Area version	UOctet	P	ROGRESS	5	Used for Progress interactions.		
		Is Error Message	Boolean		PUBSUB	6	Used for Publish/Subscribe interactions.		
			100000			Coca for 1 donsil/Subscribe interaction			

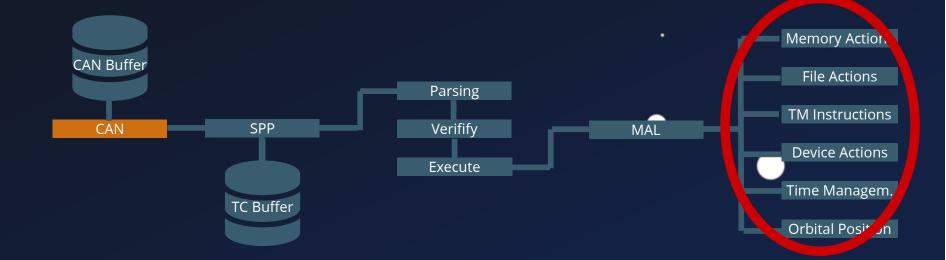


CCSDS - Message Abstraction Layer (MAL)

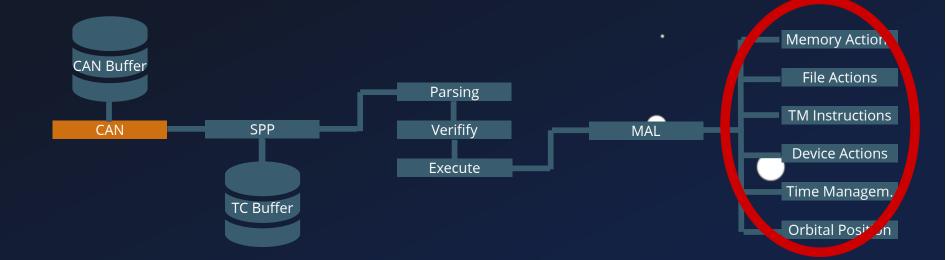
	The Consultative	Field	Type		Value				
		URI From	URI	URI		Message S	Source URI		
		Authentication Id	Blob	Blob		Source Authentication	n Identifier		
Reco	mmendati	URI To	URI	URI		Message Desti	nation URI		
		Timestamp	Time		Message generation timestamp				
	MISS	QoSlevel	QoSLevel			The QoS level of t	he message		
		Priority	UInteger			The Oos priority of t	ha massaga		
		Domain	List <identif< td=""><td></td><td colspan="3">Name InteractionTy</td><td></td></identif<>		Name InteractionTy				
		Network Zone	Identifier	She	Short Form Part	19			
	REC	Session	SessionType						
		Session Name	Identifier	Enur	meration Value	Numeric Value	Co	omment	
		Interaction Type	InteractionT		SEND	1	Used for Send int	eractions.	
		Interaction Stage	UOctet						
		Transaction Id	Long		SUBMIT	2	Used for Submit	ıbmit interactions.	
		Service Area	UShort]	REQUEST	3	Used for Request interactions.		
		Service	UShort						
		Operation	UShort		INVOKE	4	Used for Invoke interactions.		
		Area version	UOctet	P	ROGRESS	5	Used for Progress	s interactions.	
	•	Is Error Message	Boolean		DUDGUD		II 4 f D1.1 1 /		
					PUBSUB	6	Used for Publish/	Subscribe interactions.	



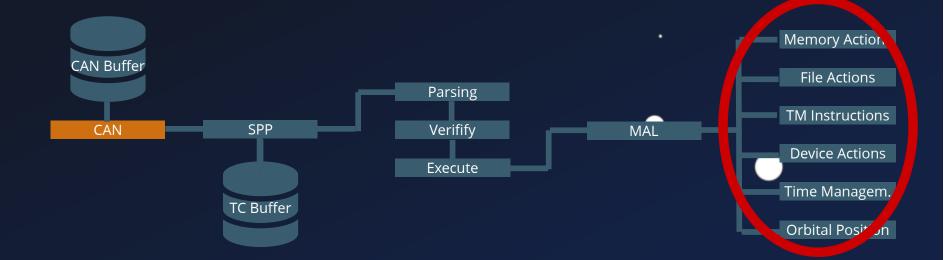
https://en.wikipedia.org/wiki/Message_Abstraction_Layer



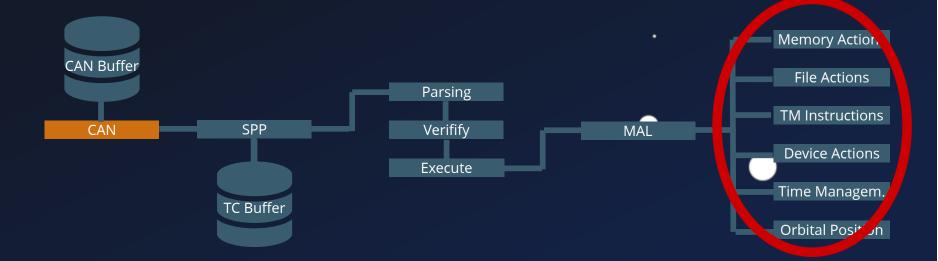
```
1 if (serviceArea == 0x20001) {
     if ((operation & 0xfffffff00) == 0x18100) { PUBSUB MonitorEvent(msg); }
   } else if (serviceArea == 0x40001) {
     if ((operation & 0xffffff00) == 0x18100) { SUBMIT SubmitAction(msg); }
   } else if (serviceArea == 0x4a000f) {
     operation = operation & 0xffffff00;
   if (operation == 0x10100) { SUBMIT_CreateFile(msg); }
     if (operation == 0x20100) { SUBMIT_RemoveFile(msg); }
11
    if (operation == 0x30100) { REQUEST WriteFile(msg); }
     if (operation == 0x50100) { PROGRESS ReadFile(msg); }
13
14 }
15 // ...
16
```



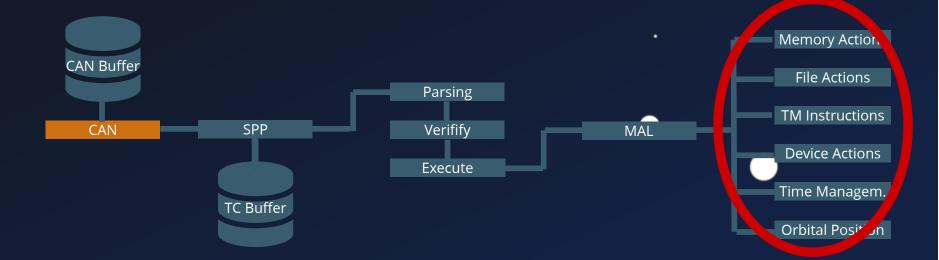
```
1 void SUBMIT_CreateFile(MAL Message t *pMessage) {
     msq = (pMessage->body).data;
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &report acceptance);
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &unused str);
       if(ret == SUCCESS) {
         // Inform about Acceptance
         COMActivityTracking PublishAcceptanceEvent(...);
10
11
12
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &boolVal);
13
     if(ret == SUCCESS) {
14
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &filename);
       if(ret == SUCCESS) {
15
         strcpy(full filename, "/flash/");
16
         strncpy(full filename + 7, filename.character, filename.length);
17
         full filename[filename.length + 7] = 0;
18
19
         file handle = fopen(full filename, "r");
20
```



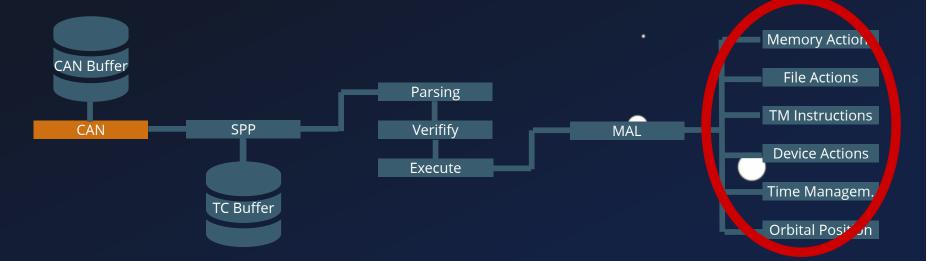
```
1 void SUBMIT CreateFile(MAL Message t *pMessage) {
     msq = (pMessage->body).data;
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &report acceptance);
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &unused str);
       if(ret == SUCCESS) {
         // Inform about Acceptance
         COMActivityTracking PublishAcceptanceEvent(...);
10
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &boolVal);
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &filename);
       if(ret == SUCCESS) {
         strcpy(full filename, "/flash/");
         strncpy(full filename + 7, filename.character, filename.length);
         full filename[filename.length + 7] = 0;
         file handle = fopen(full filename, "r");
```



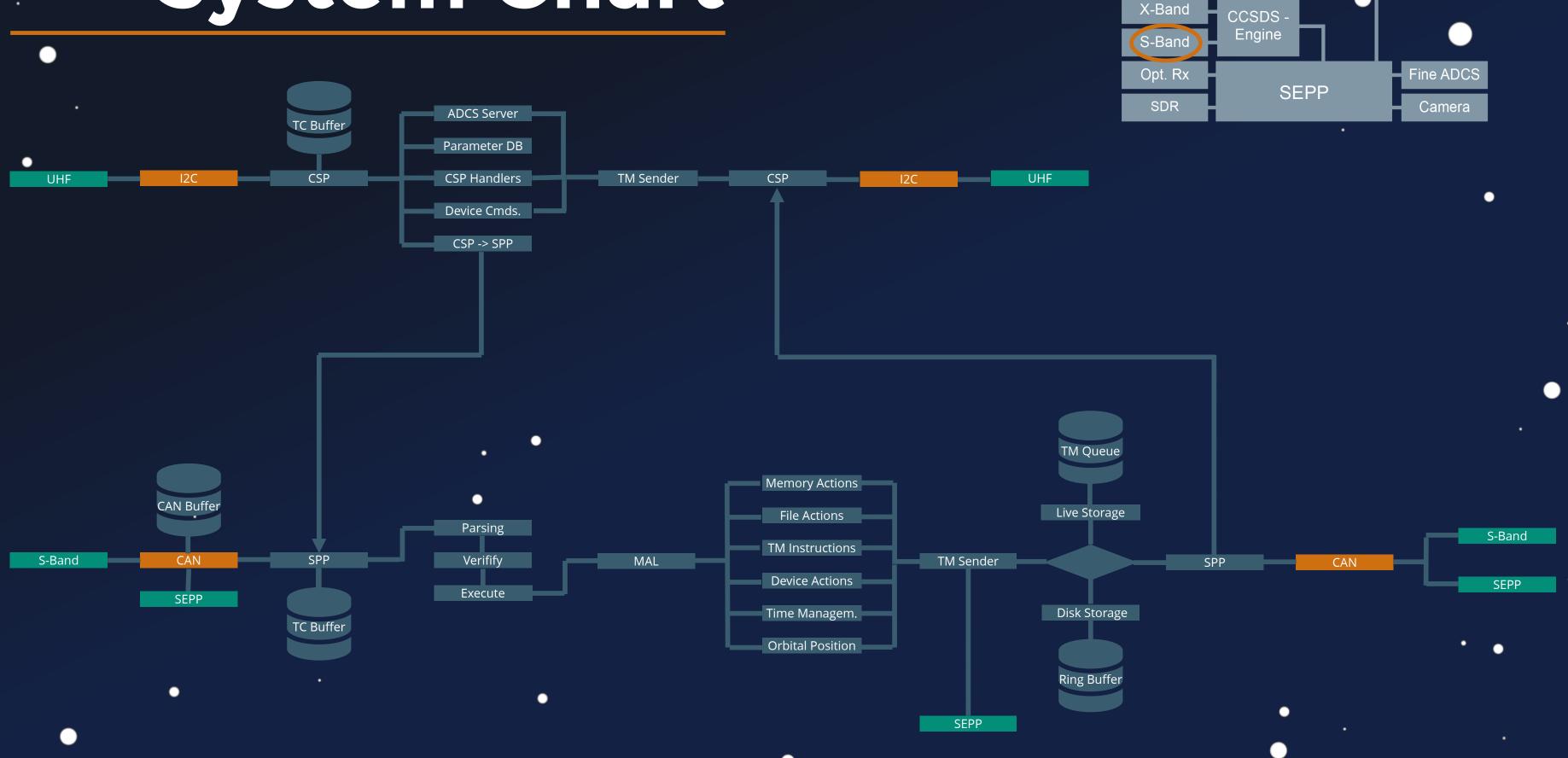
```
ret = MAL keadBoolean(msg, &oliset,(pmessage->Dody).length, &report acceptance);
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &unused str);
       if(ret == SUCCESS) {
         COMActivityTracking PublishAcceptanceEvent(...);
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &boolVal);
12
13
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &filename);
14
15
       if(ret == SUCCESS) {
         strcpy(full filename, "/flash/");
         strncpy(full filename + 7, filename.character, filename.length);
         full filename[filename.length + 7] = 0;
         file handle = fopen(full filename, "r");
         MAL WriteUInteger(...);
         MAL WriteBoolean(...);
```



```
COMActivityTracking PublishAcceptanceEvent(...);
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &boolVal);
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &filename);
       if(ret == SUCCESS) {
         strcpy(full filename, "/flash/");
16
17
         strncpy(full filename + 7, filename.character, filename.length);
         full filename[filename.length + 7] = 0;
18
         file handle = fopen(full filename, "r");
19
         MAL WriteUInteger(...);
         MAL WriteBoolean(...);
         MOSManager_SendMessage(&outputMessage_SUBMIT_CreateFile);
```



```
COMACTIVITYTE TACKING PUBLISHACCEPTANCE EVENT (...);
• • •
     ret = MAL ReadBoolean(msg, &offset,(pMessage->body).length, &boolVal);
     if(ret == SUCCESS) {
       ret = MAL ReadString(msg, &offset, (pMessage->body).length, &filename);
       if(ret == SUCCESS) {
         strcpy(full filename, "/flash/");
         strncpy(full_filename + 7,filename.character, filename.length);
         full filename[filename.length + 7] = 0;
         file handle = fopen(full filename, "r");
22
         MAL_WriteUInteger(...);
23
         MAL WriteBoolean(...);
24
         MOSManager_SendMessage(&outputMessage_SUBMIT_CreateFile);
```



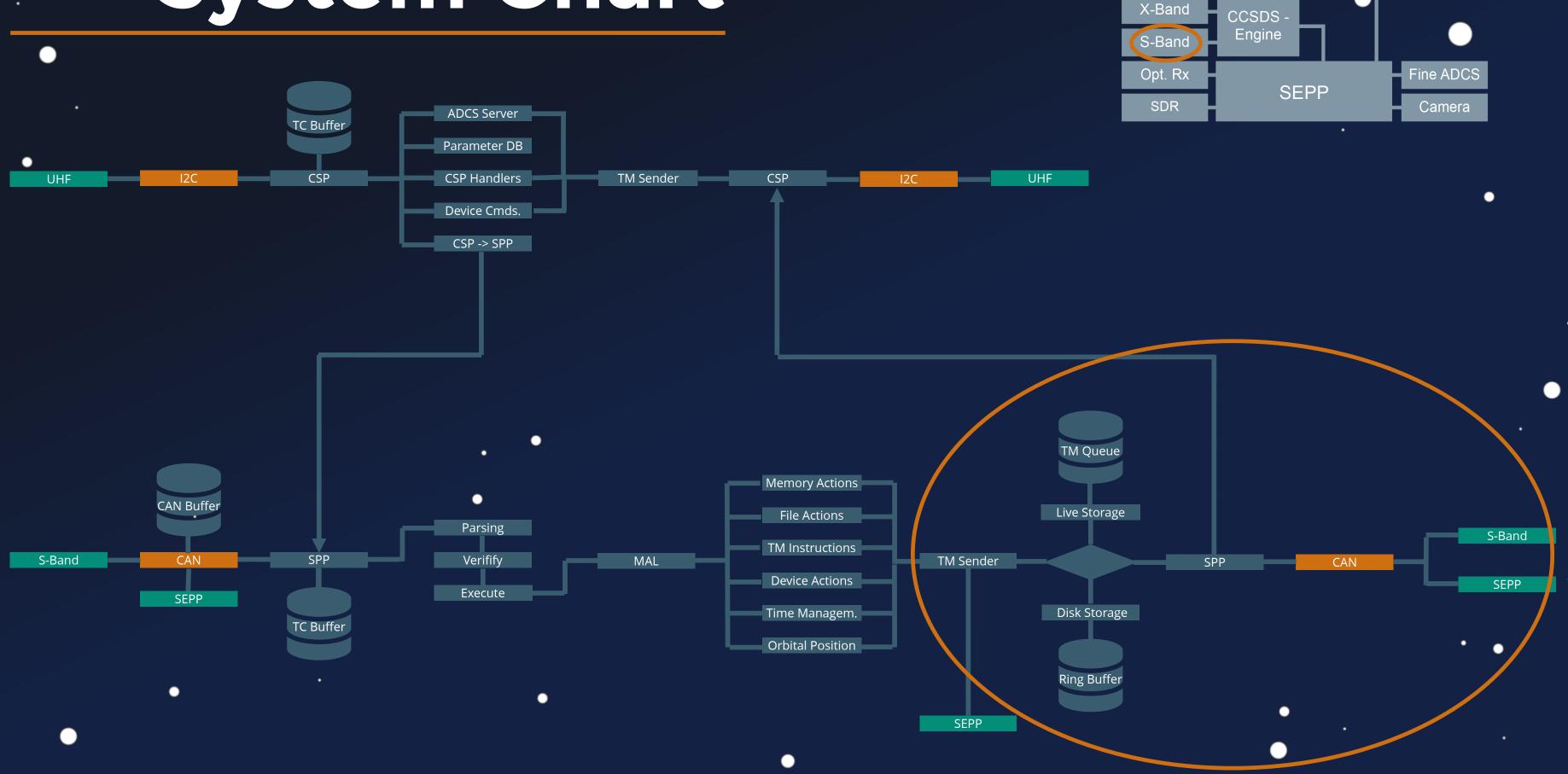
COM

GPS

CDHS

EPS

ADCS



COM

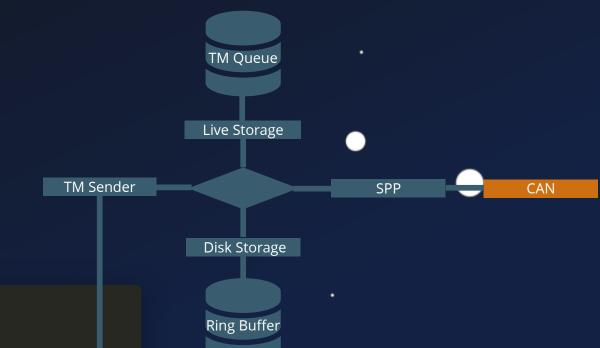
GPS

CDHS

EPS

ADCS

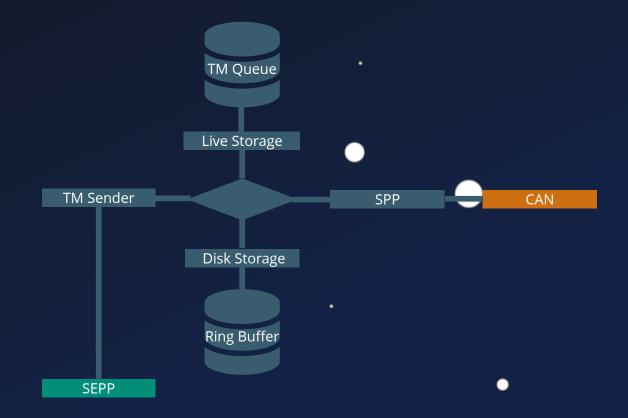
Telemetry



```
1 void MOSManager SendPacket(SPP Packet t *pPacket) {
     ret = SPP GetPacketType(pPacket, &packet type);
                                                                                      SEPP
     if (ret == SUCCESS) {
       if (packet_type == SPP_PACKETTYPE_TC) {
         tc_routing = pPacket->primaryHeader.packetID | pPacket->primaryHeader.packetSC;
       else {
         tc_routing = (pPacket->secondaryHeader).areaVersion | /* ... */;
 9
       if (tc_routing == /* ... */) {
10
         TMPK_CreatePacket(pPacket,&tmpPacket);
11
         CAN_SendFrameToSEPP(&tmpPacket,0);
12
13
14
       else {
15
         SVTM SendPacket(pPacket);
16
17
18
     return;
19
```

Telemetry

```
void SVTM_SendPacket(SPP_Packet_t *packet) {
TMMN_SendPacket(packet);
return;
}
```



Telemetry

```
TM Queue

Live Storage

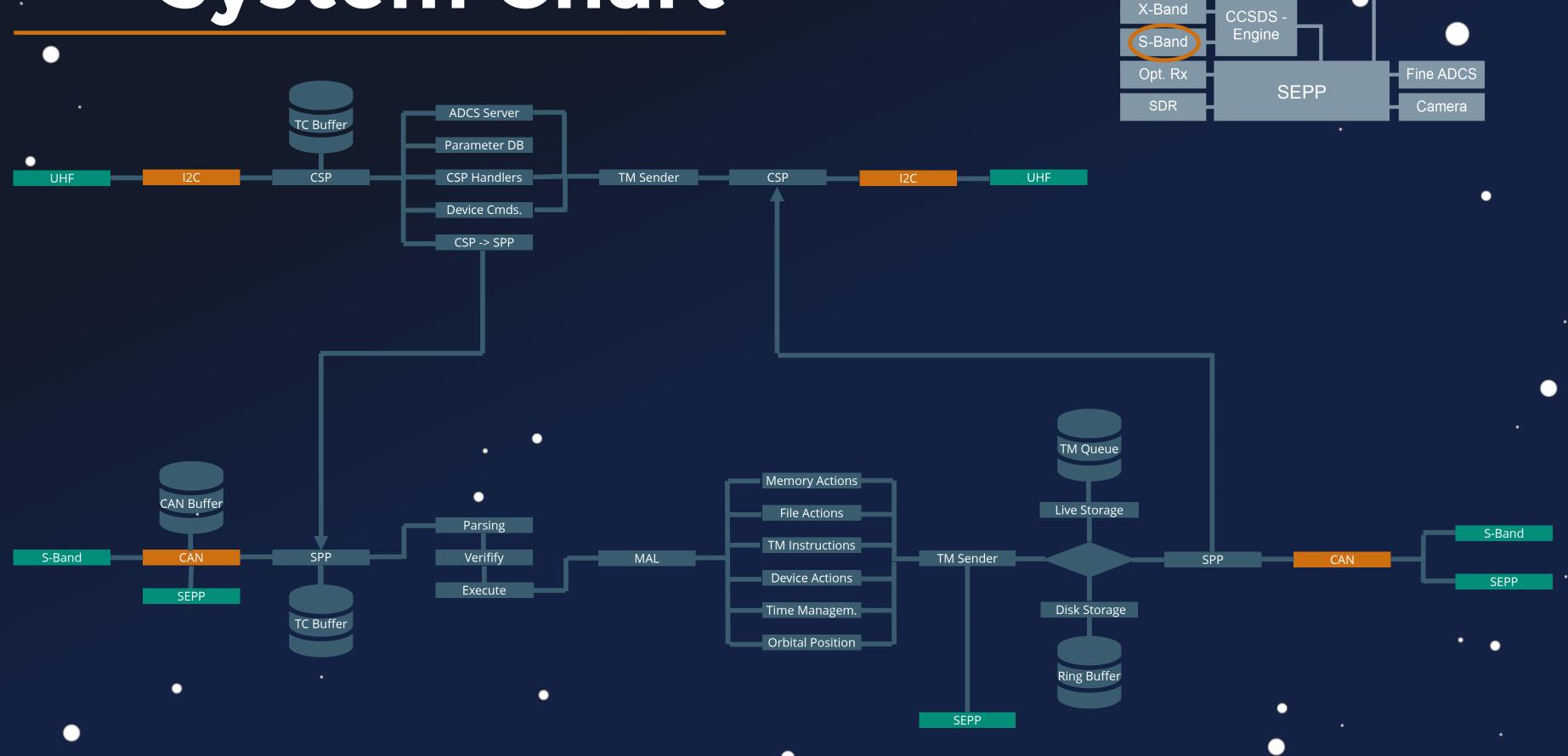
TM Sender

SPP

CAN

Disk Storage
```

```
1 void TMMN_SendPacket(SPP_Packet_t *packet) {
     SSOS_LockMutex(tmmn_MutexId);
     if (gSendPackets != '\x01') {
       TMPS_StopPSPackets();
     if ((packet->route == ROUTE_UHF) | (gSendPackets == '\x01')) {
       TMLI_AddPacketToLiveStore(packet);
10
     else {
11
12
       TMPS_AddPacketToPacketStore(packet);
13
14
     SSOS_UnlockMutex(tmmn_MutexId);
     return;
15
16 }
17
```



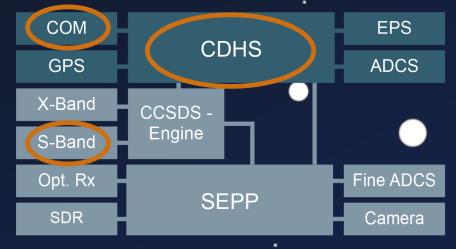
COM

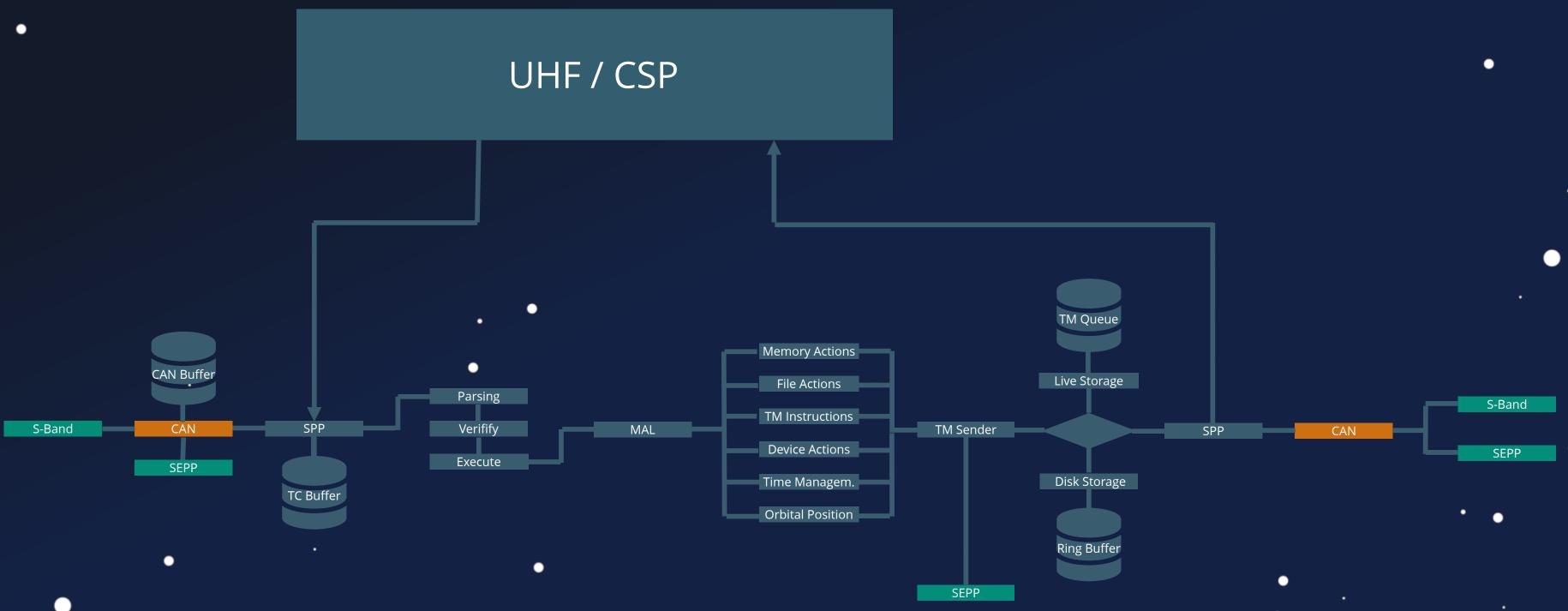
GPS

CDHS

EPS

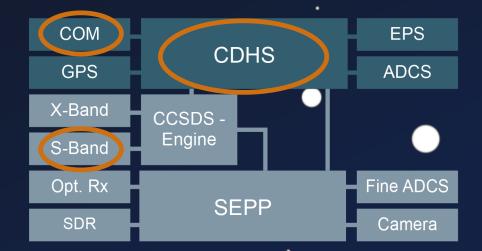
ADCS





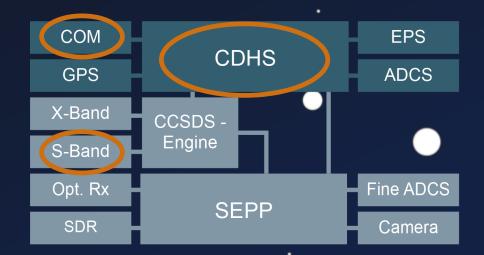
CSP vs SPP Stack





CSP vs SPP Stack







CSP-Stack User

UHF / CSP



Used by Operators

CSP-Stack User



Used by Operators



Specific GS Location



Used by Operators



Specific GS Location



10-20 mins

SPP-Stack User

S-Band + SEPP / SPP



Used by Payload & Experimentors

SPP-Stack User

S-Band + SEPP / SPP



Used by Payload & Experimentors



Specific GS Location

SPP-Stack User

S-Band + SEPP / SPP



Used by Payload & Experimentors



Specific GS Location



Unknown Time

Security Analysis



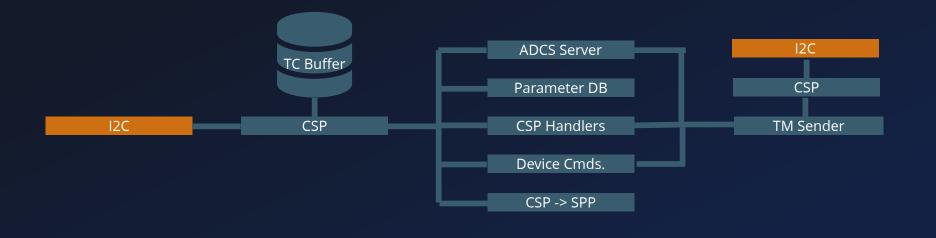


Objectives





- 1 Bypass COM Protection
- 2 Dangerous / Vulnerable TC
- 3 Hijack Bus Control Flow
- 4 Full Bus Privileges



- 1. Bypass COM Protection
 - Compiler-disabled Auth. + Enc.

```
1 int csp_route_security_chek(...) {
     if (packet->id.flags & CSP FXTEA) {
       csp_log_error("Received XTEA encrypted packet, but CSP
   was compiled without XTEA support. Discarding packet");
     if (packet->id.flags & CSP FHMAC) {
       csp_log_error("Received packet with HMAC, but CSP was
   compiled without HMAC support. Discarding packet");
10
11
12
13 }
```

- 1. Bypass COM Protection
 - Compiler-disabled Auth. + Enc.

```
1 int csp_route_security_chek(...) {
     if (packet->id.flags & CSP_FXTEA) {
       csp log error("Received XTEA encrypted packet, but CSP
   was compiled without XTEA support. Discarding packet");
     if (packet->id.flags & CSP FHMAC) {
       csp_log_error("Received packet with HMAC, but CSP was
   compiled without HMAC support. Discarding packet");
10
11
12
13 }
```

- 1. Bypass COM Protection
 - Compiler-disabled Auth. + Enc.

```
int csp_route_security_chek(...) {
   if (packet->id.flags & CSP_FXTEA) {
      csp_log_error("Received XTEA encrypted packet, but CSP was compiled without XTEA support. Discarding packet");
   }

// ...

if (packet->id.flags & CSP_FHMAC) {
   csp_log_error("Received packet with HMAC, but CSP was compiled without HMAC support. Discarding packet");
}

// ...

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```

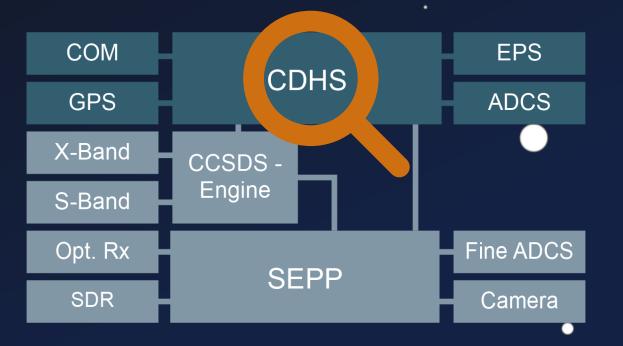
- 1. Bypass COM Protection
 - Compiler-disabled Auth. + Enc.
- 2. Dangerous / Vulnerable TC

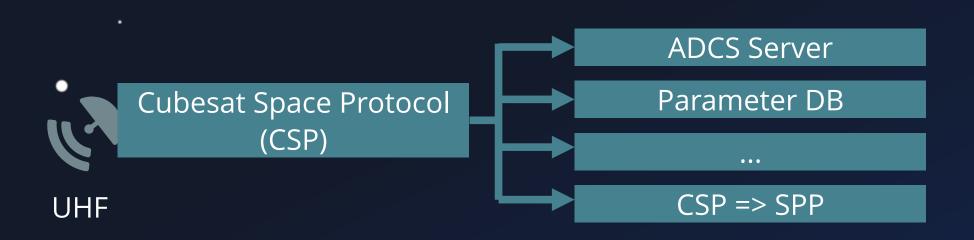
```
1 int sch_handler_set_raw_memory(scheduler_cmd_t* pCmd) {
     raw_mem_access_cmd_t* pAddr = pCmd->pCmdArgs;
     char* pWriteData;
     if (pAddr) {
       if (g_sch_exec_mode != 1 ) {
         /* exception and return */
 8
       char* pWriteData = &pAddr->start of data buf;
       if (pAddr->filesystem_target) {
10
11
12
       } else {
13
         memcpy(pAddr->targetAddr,
14
                &pAddr->start_of_data_buf,
                pAddr->writeLength);
15
16
17
18
19
```

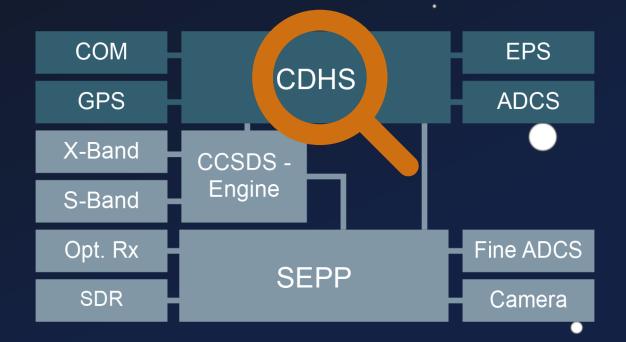
- memcpy as TC
 - Config Changes
 - Quick/Hot Patching
 - Debugging

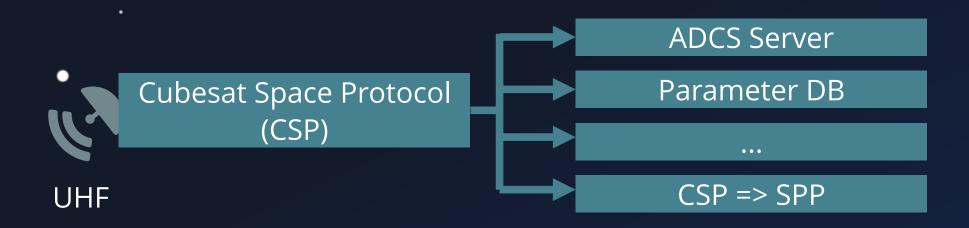
```
1 int sch handler set raw memory(scheduler cmd t* pCmd) {
     raw_mem_access_cmd_t* pAddr = pCmd->pCmdArgs;
     char* pWriteData;
     if (pAddr) {
      if (g_sch_exec_mode != 1 ) {
       char* pWriteData = &pAddr->start of data buf;
       if (pAddr->filesystem_target) {
         memcpy(pAddr->targetAddr,
13
                &pAddr->start_of_data_buf,
14
                pAddr->writeLength);
15
```

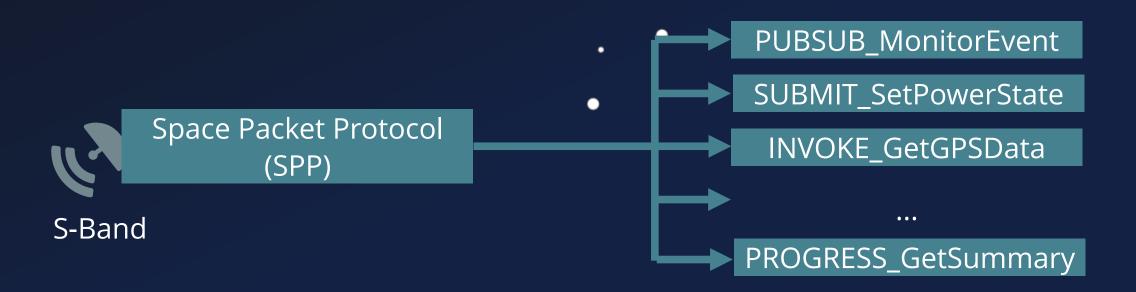
- memcpy as TC
 - Config Changes
 - Quick/Hot Patching
 - Debugging

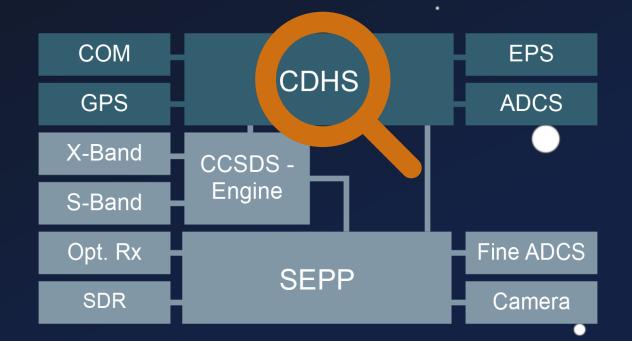


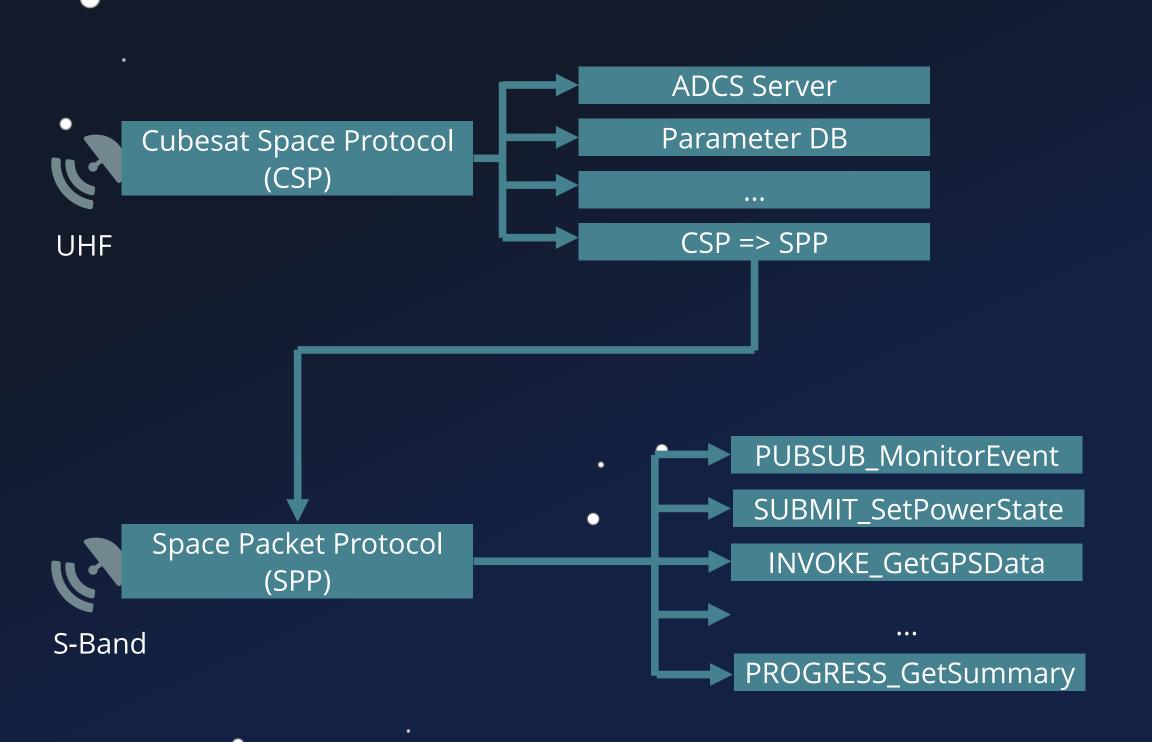


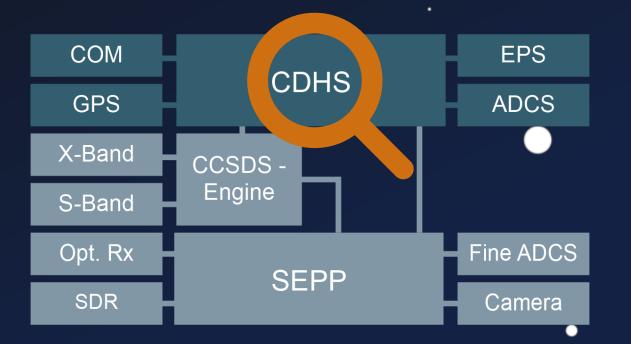


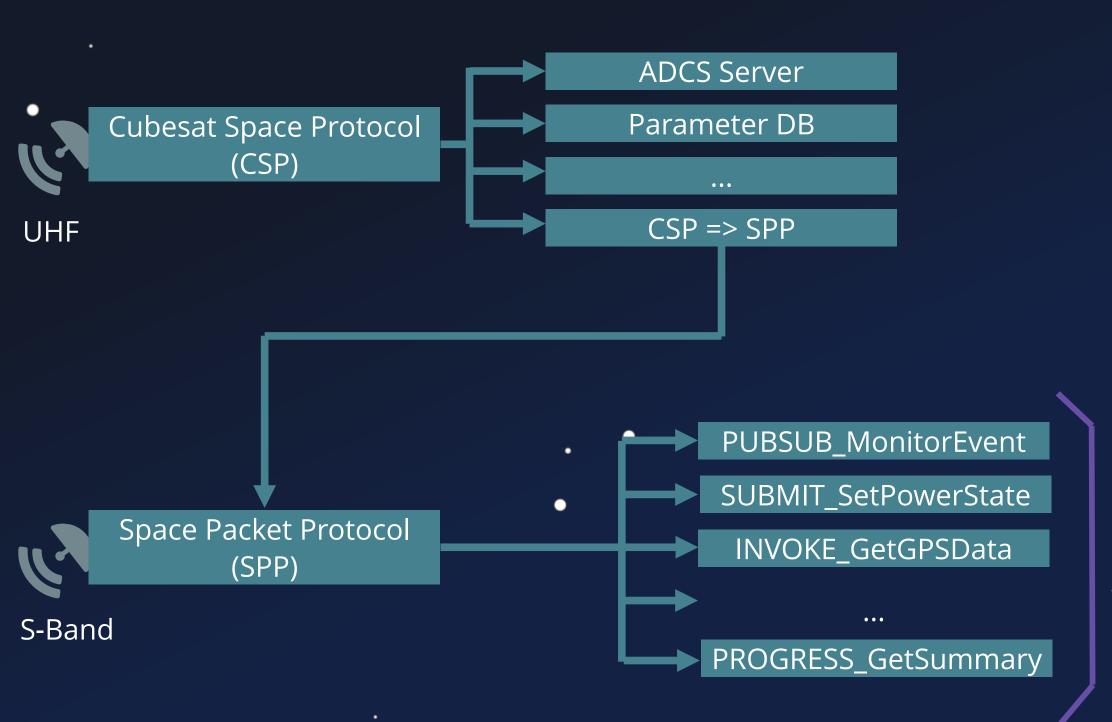


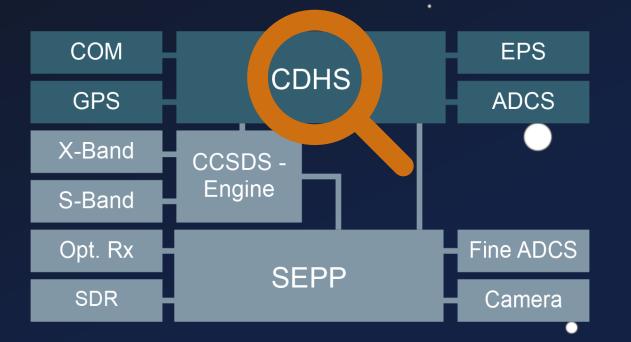




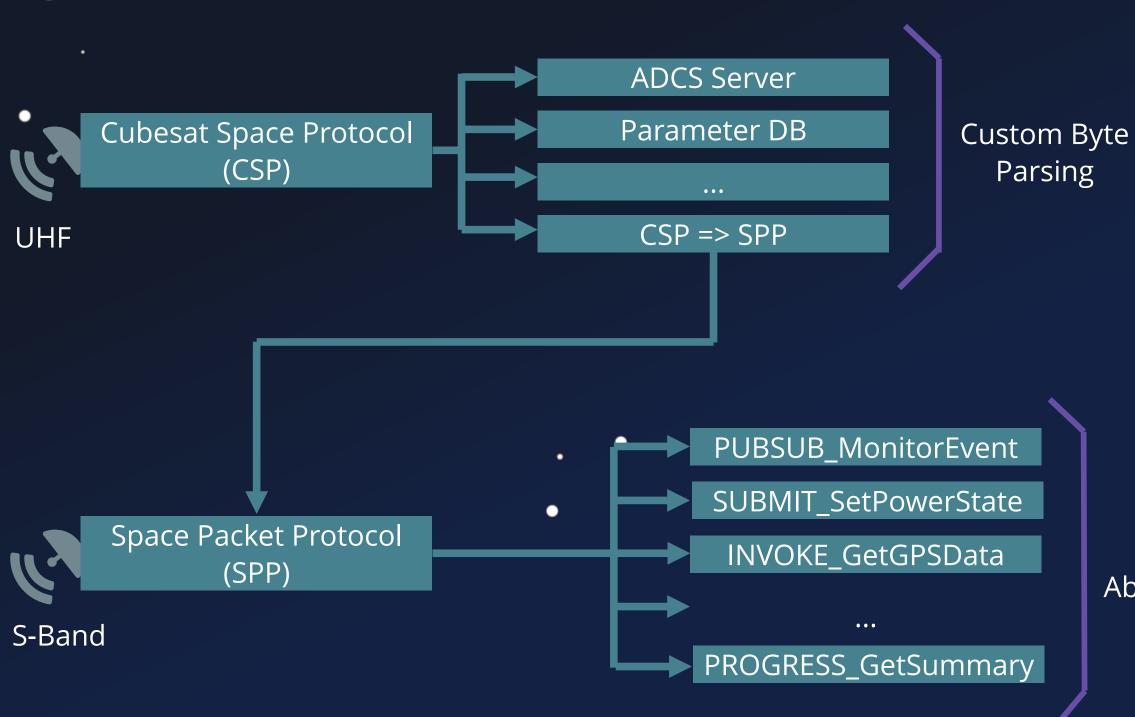


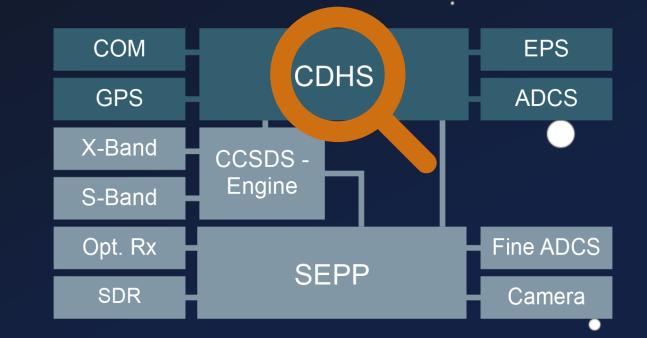




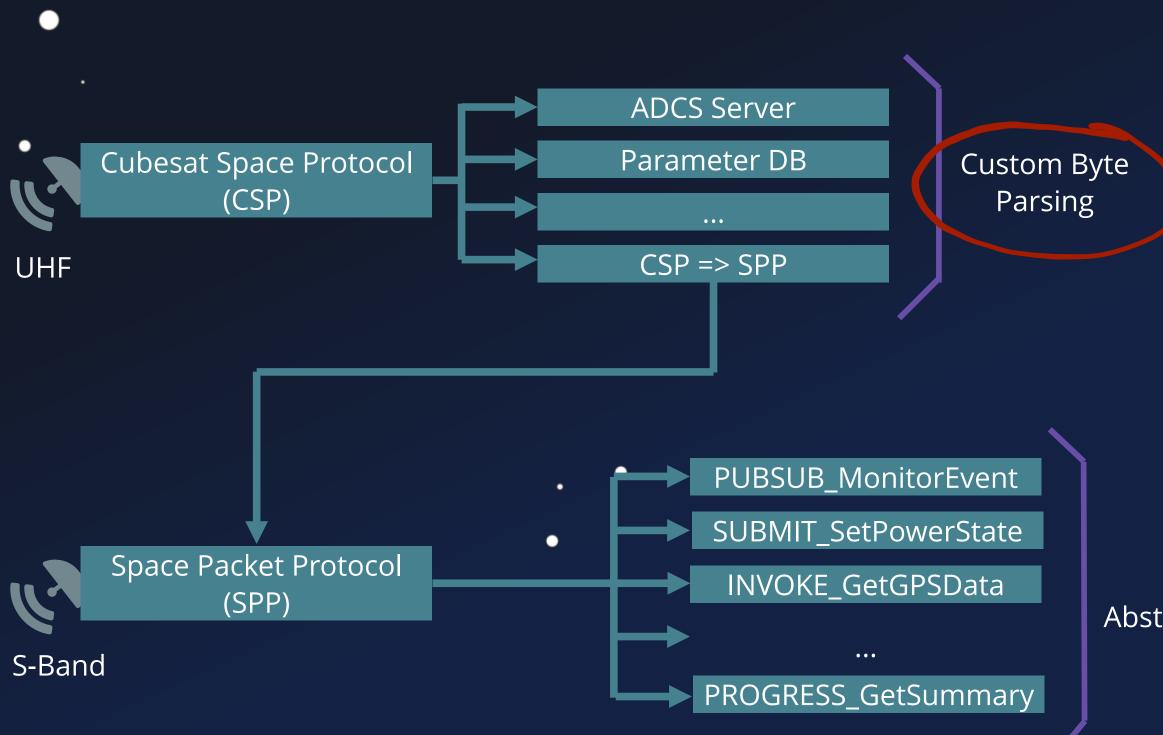


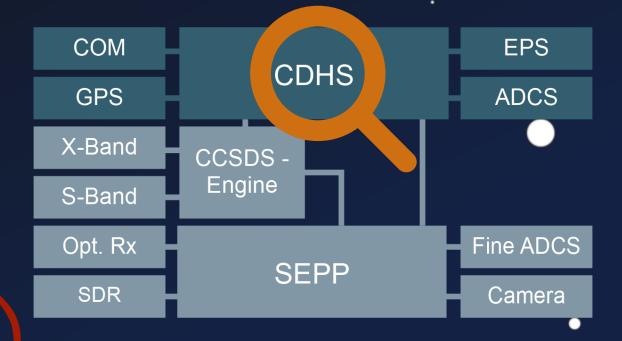
Message Abstraction Layer (MAL)





Message Abstraction Layer (MAL)



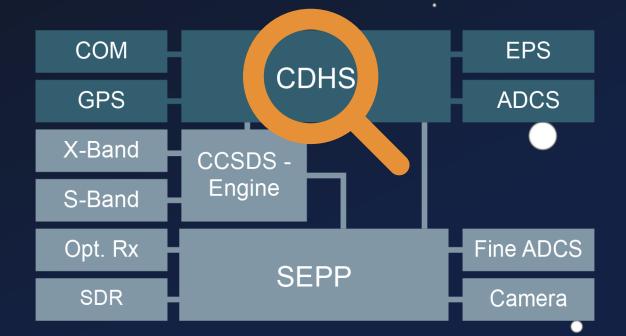


Message Abstraction Layer (MAL)

Cubesat Space Protocol (CSP)

ADCS Server

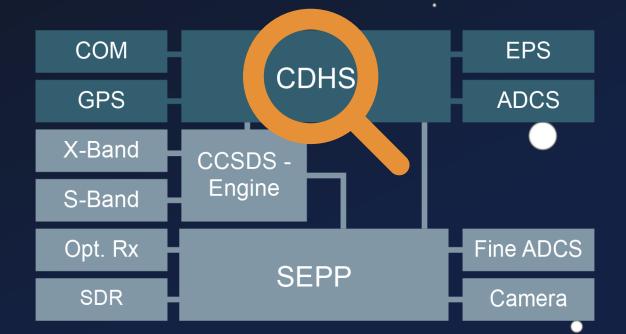
```
1 void task_adcs_servr() {
       char log_file_name [32];
      csp listen(socket, 10);
      csp_bind(socket, port);
  6
      do {
        do {
  9
           conn = csp accept(socket, 0xff);
 10
         } while (do wait for conn);
 11
         packet = csp_read(conn, 10);
 12
        if (packet) {
 13
 14
           packet data = packet->data;
           switch(*packet_data) {
 15
 16
 17
             case SET LOGFILE: {
 18
               packet_data = packet->data + 0xf;
               log file name[0] = ' \setminus 0';
 19
               strcat(log_file_name,packet_data);
 20
 21
 22
 23
 24
L25
```



Cubesat Space Protocol (CSP)

ADCS Server

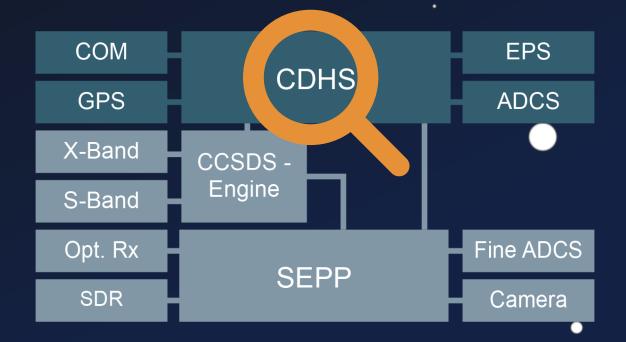
```
1 void task_adcs_servr() {
     char log_file_name [32];
     csp_listen(socket, 10);
     csp_bind(socket, port);
       do {
 9
         conn = csp accept(socket, 0xff);
10
       } while (do wait for conn);
11
       packet = csp_read(conn, 10);
12
       if (packet) {
         packet data = packet->data;
         switch(*packet_data) {
           case SET LOGFILE: {
             packet_data = packet->data + 0xf;
             log file name[0] = ' \setminus 0';
             strcat(log_file_name,packet_data);
```

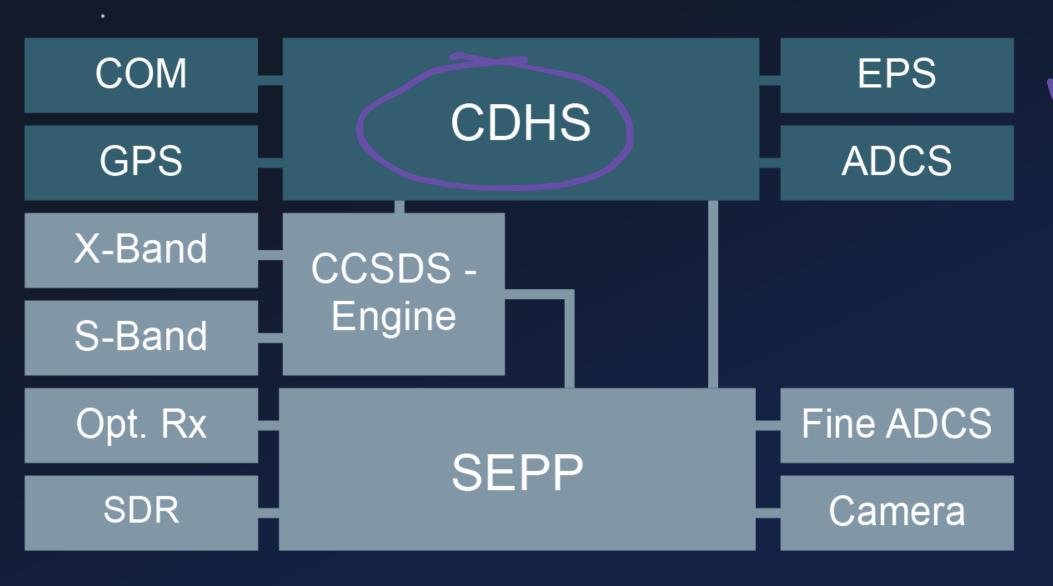


Cubesat Space Protocol (CSP)

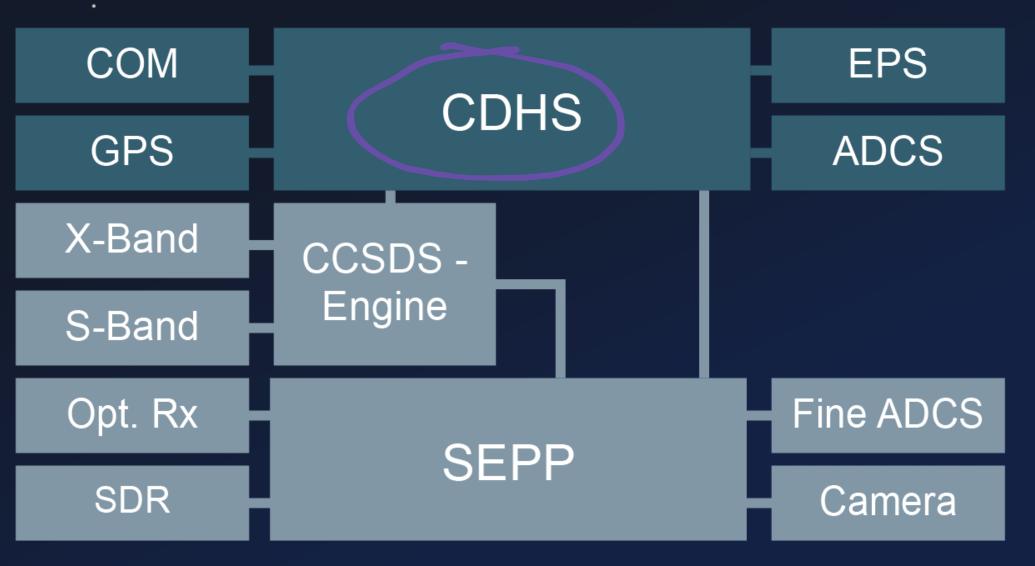
ADCS Server

```
1 void task_adcs_servr() {
     char log_file_name [32];
     csp_listen(socket, 10);
     csp_bind(socket, port);
         conn = csp accept(socket, 0xff);
       } while (do wait for conn);
       packet = csp read(conn, 10);
       if (packet) {
         packet data = packet->data;
         switch(*packet_data) {
           case SET LOGFILE: {
             packet data = packet->data + 0xf;
18
             log_file_name[0] = '\0';
19
             strcat(log_file_name,packet_data);
20
```

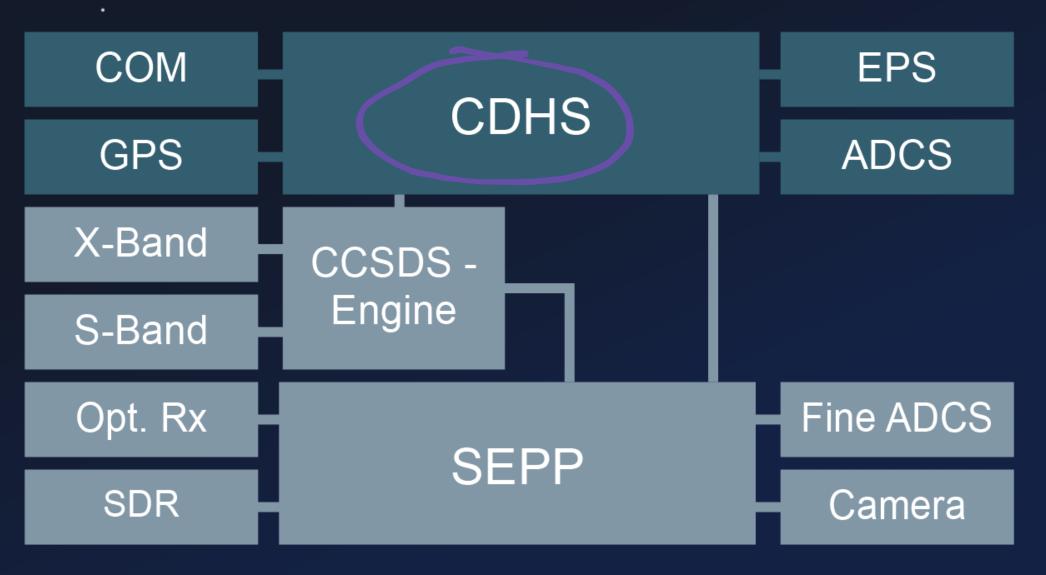




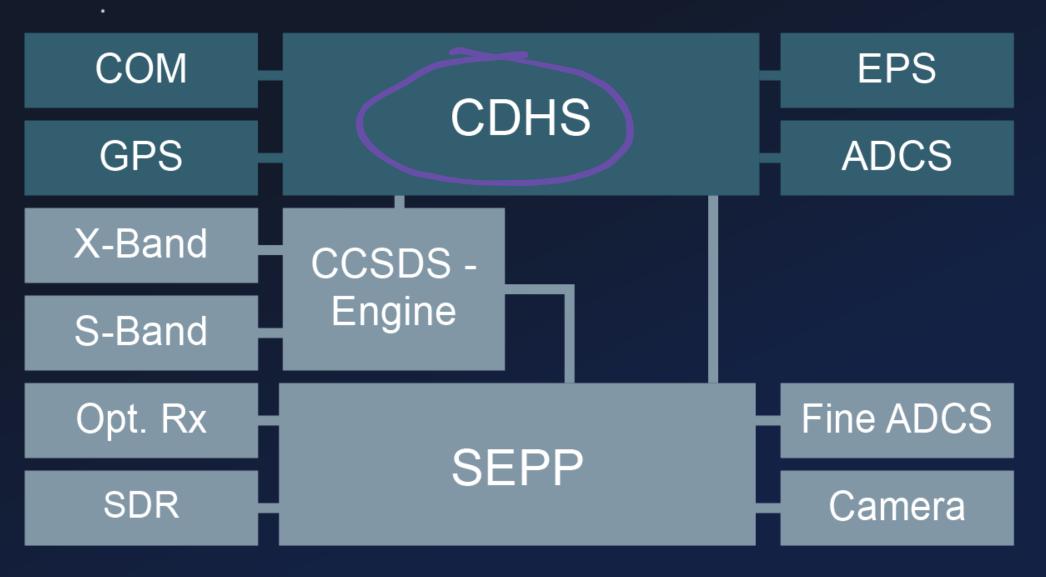
- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC



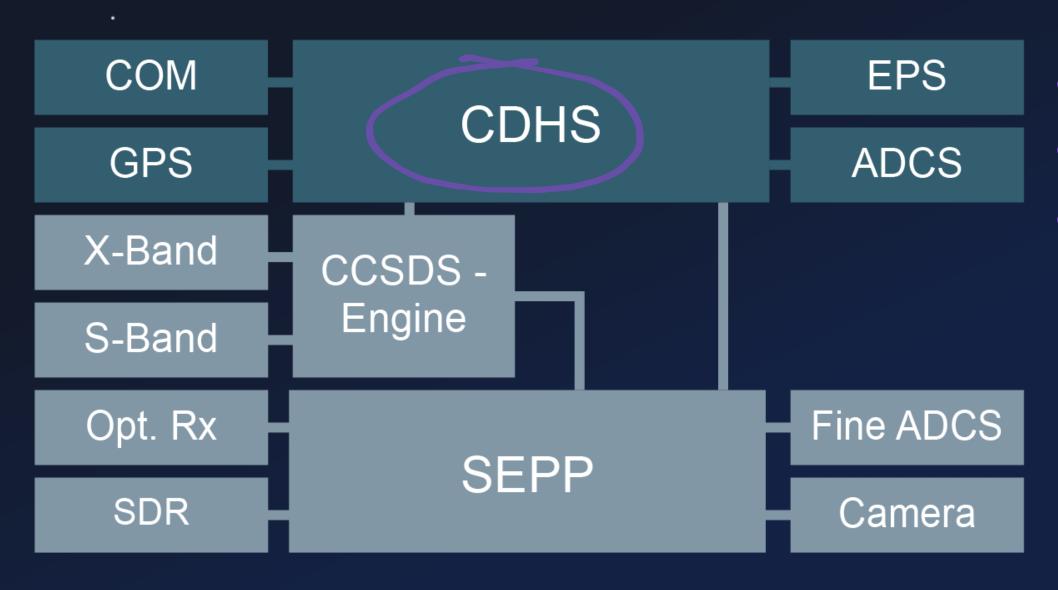
- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC



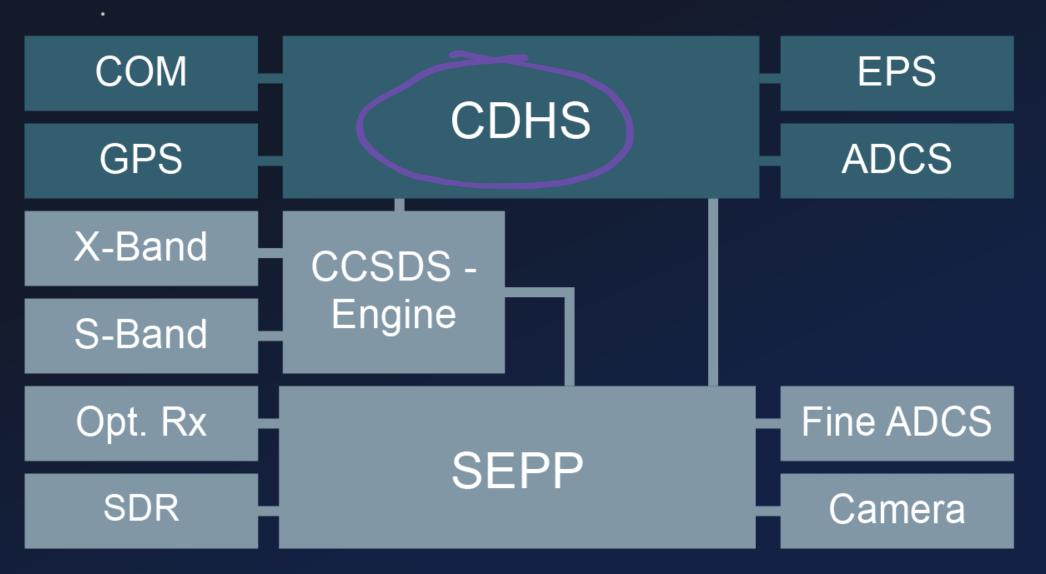
- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC
- 3. Hijack Bus Control Flow
 - No OS-Defenses
 - ASLR
 - NX Stack
 - No SW-Defenses
 - Stack Cookies



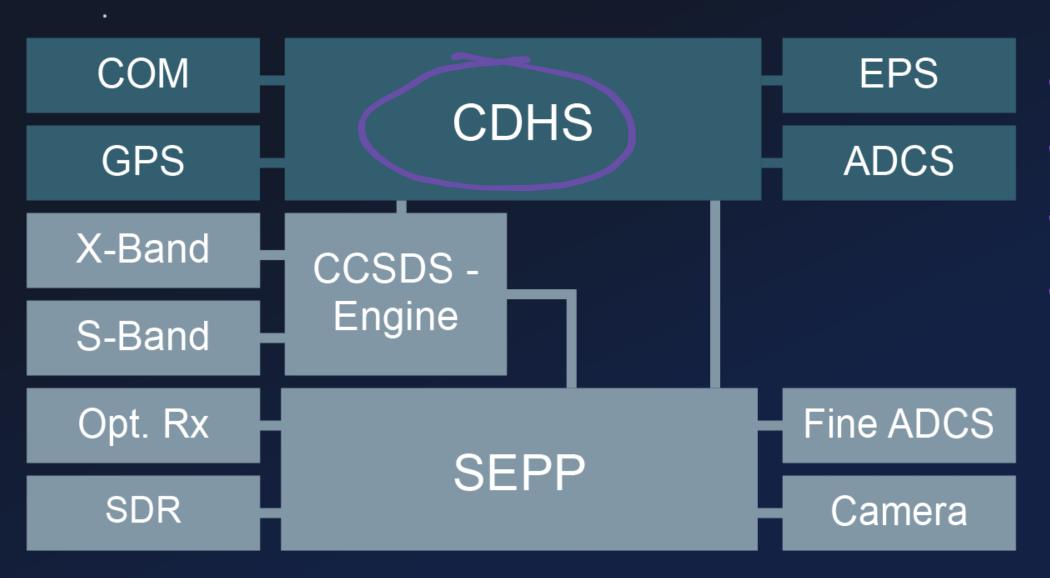
- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC
- 3. Hijack Bus Control Flow
 - No OS-Defenses
 - ASLR
 - NX Stack
 - No SW-Defenses
 - Stack Cookies



- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC
- 3. Hijack Bus Control Flow
- 4. Full Bus Privileges



- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC
- 3. Hijack Bus Control Flow
- 4. Full Bus Privileges
 - Privilege-free RTOS



- 1. Bypass COM Protection
- 2. Dangerous / Vulnerable TC
- 3. Hijack Bus Control Flow
- 4. Full Bus Privileges
 - Privilege-free RTOS

Exploitation



- 1 Hijack Control Flow
- 2 Patch Live Firmware
- (3) Add "Password" to TC stack
- **(4)** ...
- **(5)** \$\$\$

1 Hijack Control Flow

```
1 void task_adcs_servr() {
     do {
       packet = csp_read(conn, 10);
       if (packet) {
         packet_data = packet->data;
         switch(*packet_data) {
10
11
           case SET LOGFILE: {
             packet_data = packet->data + 0xf;
12
             log_file_name[0] = '\0';
13
             strcat(log_file_name,packet_data);
14
15
16
17
18
19
20
21
```

```
1 void task_adcs_servr() {
     do {
    1 void init_adcs(void) {
         gpio_enable_module((gpio_map_t *)GPS_USART_GPIO_MAP.18362,2);
10
         cmd adcs setup();
11
         adcs_node_set(1,0x14);
         xTaskGenericCreate(task_adcs, "ADCS", 0x2000, 0x0, 8, &pvStack_18, 0x0, 0x0);
12
         xTaskGenericCreate(task_adcs_server, "ASRV", 0x1000, &adcs_server_port, 9, &pvStack_18, 0x0, 0x0);
13
14
15
16
17
18
19
20
21
```

```
1 void task_adcs_servr() {
     do {
   1 void init_adcs(void) {
         gpio_enable_module((gpio_map_t *)GPS_USART_GPIO_MAP.18362,2);
10
         cmd adcs setup();
11
        adcs_node_set(1,0x14);
         xTaskGenericCreate(task_adcs, "ADCS", 0x2000, 0x0, 8, &pvStack_18, 0x0, 0x0);
12
         xTaskGenericCreate(task_adcs_server, "ASRV", 0x1000, &adcs_server_port, 9, &pvStack_18, 0x0, 0x0);
```

```
1 void task_adcs_servr() {
   1 void init_adcs(void) {
         gpio_enable_module((gpio_map_t *)GPS_USART_GPIO_MAP.18362,2);
        cmd adcs setup();
        adcs_node_set(1,0x14);
        xTaskGenericCreate(task_adcs, "ADCS", 0x2000, 0x0, 8, &pvStack_18, 0x0, 0x0);
         xTaskGenericCreate(task_adcs_server, "ASRV", 0x1000, &adcs_server_port, 9, &pvStack_18, 0x0, 0x0);
18
19
20
```

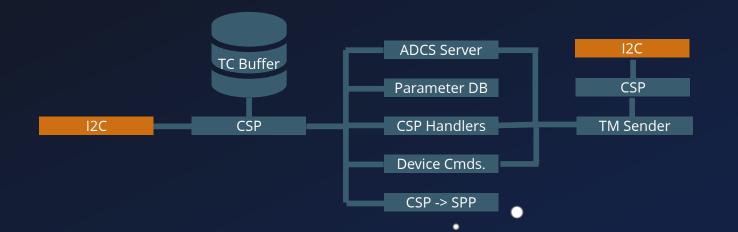
1 Hijack Control Flow

```
1 case SET_LOGFILE: {
     packet_data = packet->data + 0xf;
     log_file_name[0] = '\0';
     strcat(log_file_name,packet_data);
     adcs_logdata._20_4_ = csp_hton32( packet->data[...] | ... );
     adcs_logdata._24_4_ = csp_hton32( packet->data[...] | ... );
     adcs_logdata[28] = packet->data[10];
     adcs logdata[29] = packet->data[0xb];
10
11
     adcs_get_jdate();
12
13
     GS_ADCS_Log_Start(log_file_name, packet_data, pcVar7)
14 }
15
```

```
1 case SET LOGFILE: {
     packet data = packet->data + 0xf;
     log file name[0] = ' \setminus 0';
     strcat(log_file_name,packet_data);
     adcs_logdata._20_4_ = csp_hton32( packet->data[...] | ... );
     adcs logdata. 24 4 = csp_hton32( packet->data[...] | ... );
     adcs_logdata[28] = packet->data[10];
     adcs logdata[29] = packet->data[0xb];
     adcs_get_jdate();
                              1 void GS_ADCS_Log_Start(char *filename, void *pkt_data, uint param_3) {
                                  char sprintf_buf [60];
     GS ADCS Log Start(log f
13
14 }
                                  __n = sprintf(sprintf_buf,"%s\n%7.6f\n%3.1f\n%u%u%u%u%u\n", filename, ...);
                                  fd = fopen(filename, "wb");
                                  fwrite(&data, 1, __n, fd);
```

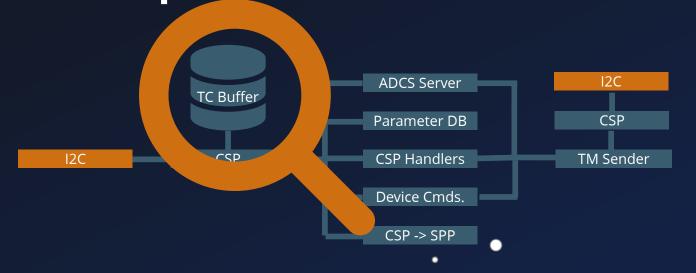
1 Hijack Control Flow

Jump Address



1 Hijack Control Flow

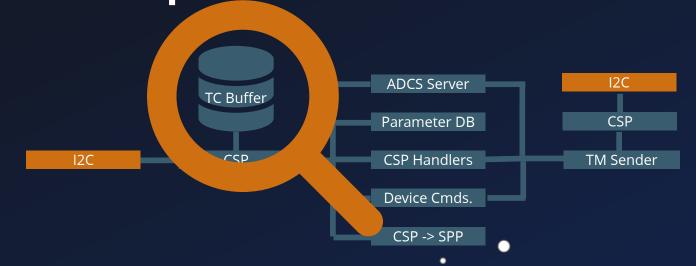
Jump Address



1 Hijack Control Flow

. . .

Jump Address

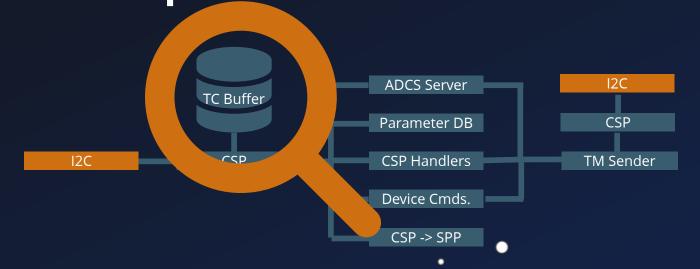


20 TC Buffers

1 Hijack Control Flow

. . .

Jump Address



20 TC Buffers

2 Patch Live Firmware

```
d140fcc7:
                      fc 1b d0 05
                                              r11,0xd005
                                      movh
                     e0 2b df fe
                                              r11,57342
   2 d140fccb:
                                      sub
                                              r12,0xd00b
   3 d140fccf:
                     fc 1c d0 0b
                                      movh
   4 d140fcd3:
                     e0 2c d2 fc
                                              r12,54012
                                      sub
                     04 52
                                              r2,r2
   5 d140fcd7:
                                      eor
                      fe c2 ff e6
                                               r2,pc,-26
   6 d140fcd9:
                                       sub
                      fc 13 d0 0c
                                              r3,0xd00c
     d140fcdd:
                                      movh
   8 d140fce1:
                     e0 23 14 88
                                      sub
                                              r3,5256
                     31 e5
     d140fce5:
                                              r5,30
                                      mov
  10
     d140fce7 <loop>:
  12 d140fce7:
                      05 34
                                      ld.ub
                                              r4, r2++
                                              r3++,r4
                     06 c4
                                      st.b
  13 d140fce9:
                                              r5,1
  14 d140fceb:
                     20 15
                                      sub
                                              r5,0
. 15 d140fced:
                     58 05
                                      cp.w
                     cf c1
                                              d140fce6 <main+0x1f>
  16 d140fcef:
                                      brne
                     5d 1b
                                      icall
  17 d140fcf1:
                                              r11
```

2 Patch Live Firmware

```
d140fcc7:
                     fc 1b d0 05
                                              r11,0xd005
                                     movh
                     e0 2b df fe
                                              r11,57342
   2 d140fccb:
                                      sub
                                              r12,0xd00b
   3 d140fccf:
                     fc 1c d0 0b
                                     movh
                     e0 2c d2 fc
     d140fcd3:
                                              r12,54012
                                      sub
                     04 52
                                              r2,r2
   5 d140fcd7:
                                      eor
                     fe c2 ff e6
                                              r2,pc,-26
   6 d140fcd9:
                                       sub
                     fc 13 d0 0c
                                              r3,0xd00c
     d140fcdd:
                                     movh
   8 d140fce1:
                     e0 23 14 88
                                      sub
                                              r3,5256
                     31 e5
     d140fce5:
                                              r5,30
                                     mov
     d140fce7 <loop>:
  12 d140fce7:
                     05 34
                                      ld.ub
  13 d140fce9:
                     06 c4
                                      st.b
  14 d140fceb:
                     20 15
                                      sub
. 15 d140fced:
                     58 05
                                     cp.w
  16 d140fcef:
                     cf c1
                                              d140fce6 <main+0x1f>
                                     brne
                     5d 1b
                                      icall
  17 d140fcf1:
                                              r11
```

2 Patch Live Firmware

```
1 d140fcc7:
                     fc 1b d0 05
                                              r11,0xd005
                                     movh
                     e0 2b df fe
   2 d140fccb:
                                              r11,57342
                                      sub
                                              r12,0xd00b
   3 d140fccf:
                     fc 1c d0 0b
                                     movh
   4 d140fcd3:
                     e0 2c d2 fc
                                              r12,54012
                                      sub
                     04 52
  5 d140fcd7:
                                     eor
                     fe c2 ff e6
                                              r2,pc,-26
  6 d140fcd9:
                                      sub
  7 d140fcdd:
                     fc 13 d0 0c
                                              r3,0xd00c
                                     movh
  8 d140fce1:
                     e0 23 14 88
                                      sub
                                              r3,5256
  9 d140fce5:
                     31 e5
                                      mov
     d140fce7 <loop>:
  12 d140fce7:
                     05 34
                                      ld.ub
                                              r4, r2++
                                              r3++,r4
  13 d140fce9:
                     06 c4
                                      st.b
                                              r5,1
  14 d140fceb:
                     20 15
                                      sub
                                              r5,0
. 15 d140fced:
                     58 05
                                      cp.w
                     cf c1
                                              d140fce6 <main+0x1f>
  16 d140fcef:
                                      brne
                     5d 1b
                                      icall
  17 d140fcf1:
                                              r11
```









```
1 i2c_rx_csp_packet = (csp_packet_t *)frame;
2 *(uint *)frame->data = *(uint *)frame->data ^ 0xdeadbeef;
3 csp_qfifo_write(i2c_rx_csp_packet, &csp_if_i2c, pxTaskWoken);
```





```
1 i2c_rx_csp_packet = (csp_packet_t *)frame;
2 *(uint *)frame->data = *(uint *)frame->data ^ 0xdeadbeef;
3 csp_qfifo_write(i2c_rx_csp_packet, &csp_if_i2c, pxTaskWoken);
```





```
1 i2c_rx_csp_packet = (csp_packet_t *)frame;
2 *(uint *)frame->data = *(uint *)frame->data ^ 0xdeadbeef;
3 csp_qfifo_write(i2c_rx_csp_packet, &csp_if_i2c, pxTaskWoken);
```

Demo Setup

Emulation Overview

TC Handlers

Sensors

OBSW

AVR32

QEMU

Simulation

Agent

Emulation Overview

TC Handlers

OBSW

AVR32

QEMU

UHF

Simulation Sensors Agent

Telecommand

TCP

Telemtry



Emulation Overview

UHF Telecommand **TC Handlers** Simulation TCP **Telemtry** Sensors **OBSW** Sensor Values AVR32 Agent TCP Flight Manuvers **QEMU**

AVR32-QEMU

404 - AVR32 Not Found

AVR32

QEMU

AVR32-QEMU

404 - AVR32 Not Found

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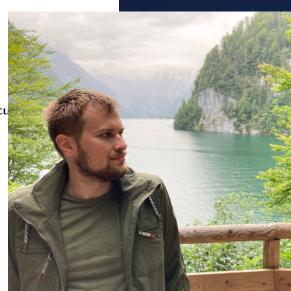
RUHR-UNIVERSITÄT BOCHUM

Hacking the Stars: A Fuzzing Based Security Assessment of CubeSat Firmware

Florian Göhler

Master's Thesis – December 22, 2022. Chair for System Security.

1st Supervisor: Prof. Dr. Thorsten Holz 2nd Supervisor: M.Sc. Johannes Willbold





AVR32

QEMU

AVR32-QEMU

404 - AVR32 Not Found

QEMU

AVR32





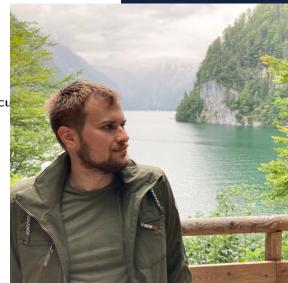
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- Florian Göhler
- AVR32 in QEMU from Scratch
- Incl. I2C, SPI, PDCA, etc.
- Blog:
 - How to add a new architecture to QEMU - Part 1-4



Simulation Agent

- TCP Server in QEMU
 - Writes packets to I2C bus
 - Same as on OPS-Sat
 - Provides Sensors with Values

Simulation Agent

Simulation Agent

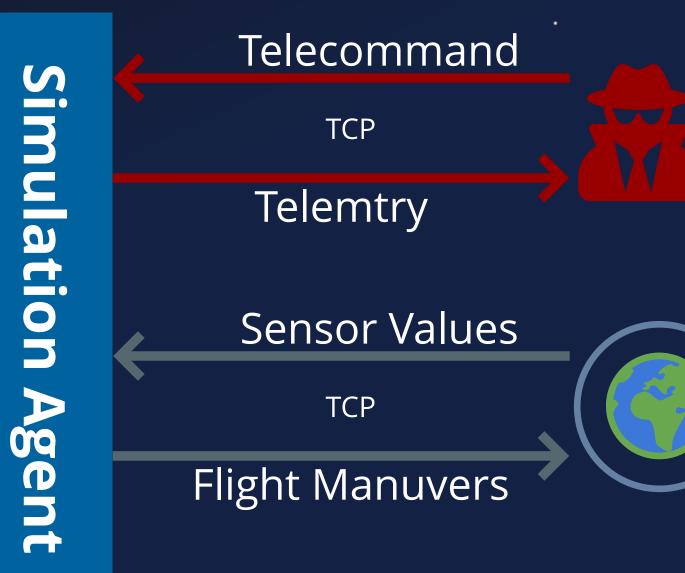
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 - Writes packets to I2C bus
 - Same as on OPS-Sat
 - Provides Sensors with Values

Simulation Agent

Telecommand TCP
Telemtry

Simulation Agent

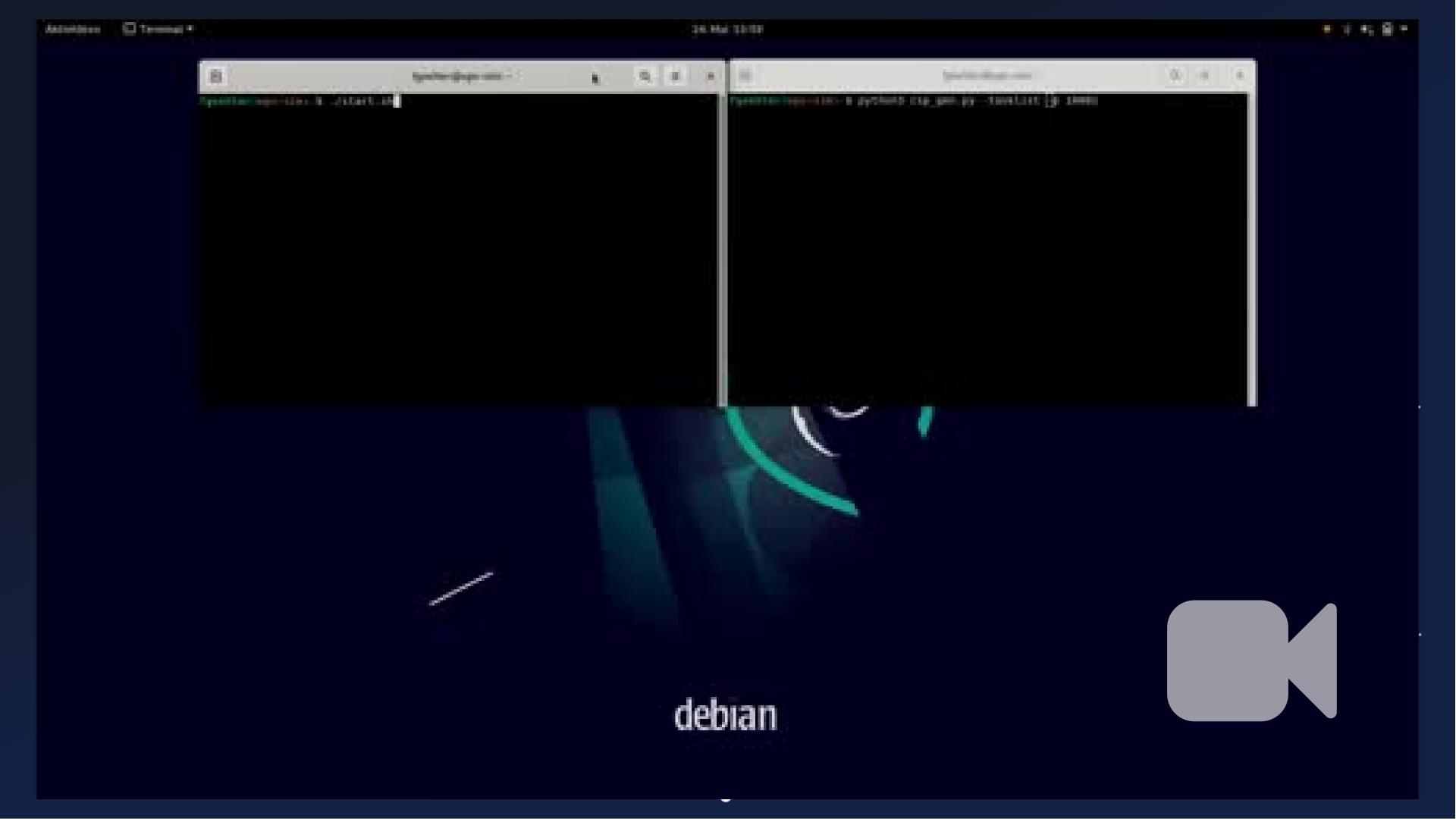
- TCP Server in QEMU
 - Writes packets to I2C bus
 - Same as on OPS-Sat
 - Provides Sensors with Values



Live Demo



```
1 $> ./access-satellite.
2 [*] Uploading TC ...
3 [*] Deploying payload ...
4 [*] Payload written to flash ...
5 [*] Rebooting ...
6 [*] $$$
```





Cosmic Radiation
Degraded Memory



Cosmic Radiation
Degraded Memory



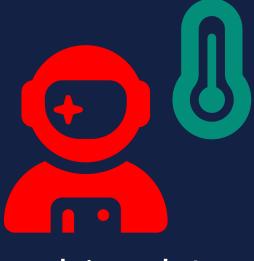
Very Limited Attack
Time Windows



Cosmic Radiation
Degraded Memory



Very Limited Attack
Time Windows



Combined Attacks
Software + Sensors

Lesson Learnt



Lessons Learnt



Firmware Attacks on Satellites are a thing



ViaSat Incident != Satellite Firmware Attack



Common Sat Protocols lack Security



Security by Obscurity

Lessons Learnt



Complex TC/TM pipelines



Missing State-of-the-Art Defenses



Buffer Overflow => Remote Code Exeuction



Full Satellite Takeover



Thanks!



- Firmware Attacks on Satellite
- Satellite Exploitation Objectives
- Satellite TC + TM Pipelines
- Missing OS & SW-Defenses
- Full Satellite Takeover





Also visit my Talks @ TyphoonCon'23, Seoul, South Korea Black Hat USA '23, Las Vegas, USA

Johannes Willbold - johannes.willbold@rub.de

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